Estimating High Dimensional Monotone Index Models by Iterative Convex Optimization[1]

Shakeeb Khan, Xiaoying Lan, Elie Tamer

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Abstract

In this paper we propose new approaches to estimating large dimensional monotone index models. This class of models has been popular in the applied and theoretical econometrics literatures as they include discrete choice, nonparametric transformation, and duration models. The main advantage of our approach is computational: in comparison, rank estimation procedures such as proposed in Han (1987) and Cavanagh and Sherman (1998) optimize a nonsmooth, non convex objective function, and finding a global maximum gets increasingly difficult with a large number of regressors. This makes such procedures particularly unsuitable for "big data" models. For our semiparametric model of increasing dimension, we propose new algorithm based estimators involving the method of sieves and establish asymptotic its properties. The algorithm uses an iterative procedure where the key step exploits its strictly convex objective function. Our main results here generalize those in, e.g. Dominitz and Sherman (2005) and Toulis and Airoldi (2017), who consider algorithmic based estimators for models of fixed dimension. We extend our method to estimate multivariate versions of these large dimensional models.

Key Words Monotone Index models, Convex Optimization, Sieve Projection Pursuit.

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1. Introduction

Monotone index models have received a great deal of attention in both the theoretical and applied econometrics literature, as many economic variables of interest are of a limited or qualitative nature. A leading special case in this class is the binary choice model which is usually represented by some variation of the following equation:

$$y_i = I[x_i'\beta_0 - \epsilon_i \geq 0] \tag{1.1}$$

where $I[\cdot]$ is the usual indicator function, y_i is the observed response variable, taking the values 0 or 1 and x_i is an observed vector of covariates which effect the behavior of y_i. Both the disturbance term ϵ_i, and the vector β_0 are unobserved, the latter often being the parameter estimated from a random sample of (y_i, x_i') $i = 1, 2, ...n$.

The disturbance term ϵ_i is restricted in ways that ensure identification of β_0. Parametric restrictions specify the distribution of ϵ_i up to a finite number of parameters and assume it is distributed independently of the covariates x_i. Under such a restriction, β_0 can be estimated (up to scale) using maximum likelihood or nonlinear least squares. However, except in special cases, these estimators are inconsistent if the distribution of ϵ_i is misspecified or conditionally heteroskedastic. Semiparametric, or "distribution free" restrictions have also been imposed in the literature, resulting in a variety of estimation procedures for β_0. The first was the "maximum score" estimator proposed in Manski (1975). Identification of β_0 was based on a conditional median restriction, and based on that Manski (1975), Manski (1984) established the estimator's consistency. Kim and Pollard (1990) established its rate of convergence and limiting distribution, which were $n^{-1/3}$ and non-Gaussian, respectively.

A main drawback of the estimator is its computational difficulty. This arises from the objective function in Manski (1975) being nonsmooth and nonconvex. This makes finding a global optimum a formidable task. Furthermore the problem becomes more difficult the

larger the dimension of x_i.

Alternative semiparametric restrictions used in the literature were based independence/index restrictions. Estimation procedures under this restriction include those proposed by Han (1987), Ichimura (1993), Klein and Spady (1993b). These also have the robustness advantage over parametric approaches, but like maximum score are difficult to compute due to nonconvexity of their respective objective functions, and once again the difficulty increases with the dimension of x_i. Recent work which is motivated by computational concerns is Ahn et al. (2018). However, their two step procedure involves a fully nonparametric estimator in the first stage, so is also not suitable for models with a large number of regressors.

Consequently, a related drawback of all these procedures is that they are designed to estimate parameters in models of a small and *fixed* dimension. A relatively recent and thriving literature in econometrics and machine learning is recognizing the many advantages of allowing for large dimensional models. Such models have a particularly well empirical motivation in binary or discrete choice models. For example, in the decision whether or not to purchase a particular good, explanatory variables would include prices of of other goods which are substitutes or compliments, which could be a large set.

This is a special case of models that consider the situation when the dimension of x_i is large, and this is now often modeled with its dimension increasing with the sample size. Due primarily to its empirical relevance there has been a burgeoning literature on estimation and inference in certain econometric and statistics models with a large number of regressors or a large number of moment conditions. Examples include work in Belloni et al. (2018), Belloni et al. (2014b), Caner (2014), Cattaneo et al. (2018a), Cattaneo et al. (2018b), Chernozhukov et al. (2017), Van de Geer et al. (2014), Han and Phillips (2006), Mammen (1989), Mammen (1993), Newey and Windmeijer (2009), Portnoy (1984), Portnoy (1985).

Particularly related to the work in our paper of estimating large dimensional binary choice

or monotone index models are the recent contributions in Sur and Candès (2019), Fan et al. (2020), and Dominitz and Sherman (2005). Sur and Candès (2019) considers inference in a large dimensional logit model, relying on the logistic distribution of the disturbance term. As is the case with all parametric approaches, estimates and inference results are not robust to such a rigid distributional specification.

In contrast, the approach in Fan et al. (2020) is semiparametric, and robust to distributional misspecification. They estimate parameters by optimizing at the objective function introduced in Han (1987), but with the number parameters increasing with the sample size. But unfortunately, such and related estimation procedures cannot be implemented in large dimensional models. This is still the case even with recent developments in algorithms and search methods for optimizing non smooth and/or non convex objective functions. See for example important recent work based on mixed integer programming (MIP) as in, e.g. Fan et al. (2020) and Shin and Todorov (2021).

Also related is the work in Dominitz and Sherman (2005), who consider an algorithmic based estimator for parameters in a class of monotonic index models. Like in our paper the motivation of their approach over existing methods is computational. But they focus on the fixed dimension case, and impose a shape restriction on the disturbance term which restricts the class of models compared to the existing semiparametric literature.

Therefore, in light of the drawbacks in the existing literature, this paper proposes a new estimation procedure to address this omission in this literature. Specifically we aim to construct a computationally feasible estimator for a semiparametric binary choice and monotone index models with *increasing* dimension and establish its asymptotic properties. As we will discuss in detail in the next section, our algorithm uses an iterative estimator based on a stochastic gradient descent method(SGD), and we show how to use the method of sieves (Chen (2007)) to approximate the distribution in each stage of the iteration.[2]

[2]Alternative nonparametric methods could also be used. One example is kernel regression on the index. This

The rest of the paper is organized in follows. In the next section we further discuss the models and parameters we wish to estimate and provide a brief literature review, highlighting important related work in the econometrics, computational and computer science literatures. In doing so we will compare the relative advantages and disadvantages from both theoretical and computational viewpoints. Section 3 then introduces our algorithmic based estimators. Section 4 then explores the asymptotic properties of this procedure, and provides detailed regularity conditions on the sieve space and basis functions, as well as those on the dimension space of the regressors. Section 5 further explores the finite sample properties of the estimator via a simulation study. Section 6 concludes by summarizing and future work, such as discussing other models for which similar algorithm based estimators can be applied to.

2. Model and Related Literature

. Generally speaking, the class of models we will consider estimating are often referred to as monotonic transformation models. One such variant was introduced in Han (1987). We express this model as the equation:

$$y_i = T(x_i'\beta_0, \epsilon_i) \tag{2.1}$$

Where y_i is an observed scalar dependent variable, x_i is an observed vector of covariates of fixed dimension p, and ϵ_i is an unobserved scalar disturbance term. $T(\cdot, \cdot)$ is an unknown transformation function assumed to be monotonic in each of its arguments. β_0 is an unknown p dimensional vector of regression coefficients, often the parameter of interest to identify and estimate from a random sample of (y_i, x_i). The popularity of class of models is that that it nests many special cases that arise in the literature. This includes binary choice models discussed in the previous section but also , censored regression models and duration

is in one sense appears similar to profile methods used in Ichimura (1993) and Klein and Spady (1993a). But in fact since our algorithm preserves convexity throughout it converges to a global optimum in contrast to theirs, which are very difficult to implement.

models with unknown baseline hazard functions. Identification of β_0 is usually based on the assumption that ϵ_i has an unknown distribution that is is independent of x_i. To estimate β_0, Han (1987) proposed the maximum rank correlation estimator. This involved optimizing the objective function:

$$G_n(\beta) = \frac{1}{n(n-1)} \sum_{i \neq j} I[y_i > y_j] I[x_i'\beta > x_j'\beta] \tag{2.2}$$

He showed the optimizer, subject to a scale normalization was consistent and Sherman (1993) established root-n consistency and asymptotic normality, under standard regularity conditions. Variants of the model and the estimator include work in Abrevaya (1999), Abrevaya (2000), Khan and Tamer (2007), Abrevaya et al. (2010), and more recently Khan et al. (2019) and Fan et al. (2020). While a desirable feature of the original MRC estimator was the generality of the class of modes that could be estimated, a major drawback was its implementability. The objective function is nonsmooth and non concave, making finding a global maximum virtually impossible when the dimension of x_i is sufficiently large. Recent advances in optimization routines such as mixed integer programing, used in, e.g. Fan et al. (2020) and Shin and Todorov (2021) are very valuable, they do not completely solve the problem as it still the case that optimization is np "hard", where n is the sample size and p is the dimension of x_i- see, e.g. Shin and Todorov (2021) for a detailed discussion on this. Other estimation procedures for this model that are not rank based include Cosslett (1983), Ichimura (1993), Ahn et al. (2018). As is the case with the MRC estimator they are not well suited for x_i having a moderately large dimension.

Cosslett (1983) proposes an algorithmic estimator based on MLE and includes include two steps. First he approximates the distribution of the error using basic distribution functions, second he estimates β via MLE and repeats the process until convergence. However, the estimators involves finding the maximum of a non-concave function. This is computationally hard because while one can use grid search to find the maximum, with more than just a few regressors it's almost impossible to implement those methods in practice. As mentioned

previously, more modern methods such as MIP (Shin and Todorov (2021)) alleviate but do not completely solve this problem. Ichimura (1993) also involves a non convexity objective function in the iterative NLLS procedure. Ahn et al. (2018) involves two steps each of which is closed form. However, it also cannot be used in large dimensional models due to the fully nonparametric procedure in the first stage.

In this paper to address this omission in the literature, we propose a new iterative estimation procedure that is based on the stochastic gradient descent method(SGD). Furthermore we establish its asymptotic properties, specifically its convergence rate and limiting distribution. One requirement of existing SGD algorithms is that the error distribution is known so we instead use a sieve method to approximate the distribution. As we will explain, first we use their algorithm to estimate β as if the error is logit distributed, second we use a sieve method, for example Series Logit Estimator(SLE) to get the estimation of the distribution of error.[3] Finally we use their algorithm to estimate β again using the estimated distribution and repeat until convergence. As we explain in detail below, we use the gradient method to get the maximum of each iteration, since our SLE is based on logit MLE that is globally convex in the parameters.

Algorithmic based approaches to estimate β in parametric models can be found in the computer science literature. Kalai and Sastry (2009) used monotonic regression. While their method is simple and fast in programming, they do not prove convergence. Agarwal et al. (2013) propose an estimator based on Kalai and Sastry (2009). They proved consistency but the estimator required the underlying distribution function be known.

Our iterative estimator is distinct from, but relates to Agarwal et al. (2013) and SGD, which (unlike ours) requires the knowledge of the error distribution. In their setting the SGD estimator is easy to compute because the algorithm of updating β is linear since the

[3]The choice of sieve estimator is crucial as not all methods ensure the distribution function estimator is monotonic. Monotonicity is crucial for the convexity of our objective function within the algorithm. Chen et al. (2011) show how Bernstein polynomials can be used to ensure monotonicity.

objective function is convex. It is one type of a Newton Raphson procedure and an example of the stochastic approximation method of Robbins and Monro (1951). In related work to that, Toulis and Airoldi (2017) propose implicit SGD estimator and derived its the limiting distribution.

What makes our iterative procedure distinct from all of these is it is not based on the assumption of a known error distribution[4]. Instead, our iterative method uses the method of sieve to estimate the unknown distribution. The method of sieves, proposed in, e.g. Grenander (1981) uses a sequence of finite-dimensional spaces, which is called the sieve space, to approximate an unknown infinite-dimensional space. The complexity of sieve space should increase with the number of observations and the sieves should be dense in the unknown space.

In our algorithm, we will use Series Logit Estimator(SLE), which is also used in Hirano et al. (2003) when they estimate the propensity score function in a treatment effect model. It is a special case of sieve MLE proposed by Geman and Hwang (1982), and they proved the consistency of sieve MLE with i.i.d data. For dependent and heterogeneous data, White (1991) provide a more detailed analysis. Hirano et al. (2003) use logistic model with power series. They only require some smoothness properties of the unknown distribution. Our estimator is similar to their two-step sieve estimator, but is iterative. It starts with modeling the unknown function nonparametrically and then estimates the parametric part with GMM or MLE. Under some regularity conditions, the parametric part of their two-step sieve estimator can get $\sqrt{n}-$asymptotic normality, see Chen (2007), Chen et al. (2003) for more discussion. As for the nonparametric part of sieve estimator, like Chen (2007) pointed out rates of convergence and limiting distribution theory for smooth functionals can be established.

Our estimator can extend to high dimensional cases. By high dimension we mean as the

[4]Distribution free algorithmic approaches distinct from what we propose in this paper and based on different assumptions include work by Dominitz and Sherman (2005), Gamarnik and Gaudio (2020), Lanteri et al. (2020).

sample size increases to infinity, the number of regressors can also increase to infinity. Fan et al. (2020) propose general rank estimators in high dimensions. They apply the estimator to Han's MRC and obtain consistency if $p_n/n \to 0$ is satisfied, where p_n is the number of covariates and is growing with the number of observations n. Under a the more restrictive condition that ${p_n}^2/n \to 0$, they attain asymptotic normality of the estimator. However, for implementation they use the algorithm by Wang (2007), which still suffers from the computational problems when the dimension is large, like many simplex search based algorithms, such as in Nelder and Mead (1965).

Sur and Candès (2019) consider logistic regression in high dimension. They find an area in the parameter space where MLE exists and they also explore what they call the 'average' behavior of the MLE, i.e, the true parameters are centered around a multiple of true parameter and the asymptotic variance of the MLE are also centered. As our estimator involves logit MLE inside the iteration we can apply some useful results from Sur and Candès (2019).

3. Estimation Procedure

In this section we introduce our algorithmic based estimator, establish its asymptotic properties and state the assumptions the theory is based on. For ease of illustration, we will focus on the binary choice model, but the algorithm based estimator and its asymptotic properties we discuss below easily carry over to the general monotone index model.

$$y_i = \mathbb{1}\{x_i^T \beta_0 > \epsilon_i\} \quad i = 1, 2, ...n \tag{3.1}$$

x_i is a p dimensional regressors whose transpose denoted by x_i^T, β_0 is a vector of length of p, $\mathbb{1}$ is an indicator function and ϵ is an unobserved random variable. The distribution of ϵ must satisfy some assumptions to make the estimator consistent. Specifically, we assume that it

is J-Lipschitz condition, i.e, $0 \leq g(b) - g(a) \leq J * (b - a)$ for all $a \leq b$, where $g : \mathbb{R} \to \mathbb{R}$ is the CDF of error. Also here we x_i are some continuous random variables. Suppose we have n observations, each observation x_i is a $p * 1$ estimator.

First, we introduce the explicit stochastic gradient descent estimator(SGD), the estimator is a special example of stochastic approximation Robbins and Monro (1951), The following is the SGD algorithm, where we denote iterations by the letter k, $k = 1, 2, ...K(n)$, recalling n denotes the sample size.

Algorithm 1 SGD estimator $g(\cdot)$ known

1: Starting with initial guess $\hat{\beta}_0$, and starting with $k = 1$, set $\hat{\Sigma}_k = C_k$, where C_k is a $p * p$ matrix.
2: Set $\hat{D}_k = (g(x_k^T \hat{\beta}_{k-1}) - y_k) * x_k^T$
3: Update $\hat{\beta}_k = \hat{\beta}_{k-1} - \gamma_k \hat{\Sigma}_k \hat{D}_k$, where γ_k is a "learning parameter", whose properties we discuss below.
4: Go back to Step 1 and set $k = k + 1$.
5: Repeat until you get $\hat{\beta}_K$.

We alter the SGD algorithm to find a minimum value for a convex loss function.

$g(.)$ is a non-decreasing function, then according to Lemma 1, there exists a function $G : \mathbb{R} \to \mathbb{R}$ such that $G' = g$ and G is a convex function.

$$\zeta(\beta; (x, y)) = G(x^T \beta) - y x^T \beta \tag{3.2}$$

The loss function is similar to that proposed by Agarwal et al. (2013). Notice that the loss function is convex in β since G is convex. Now the k_{th} SGD updating for $\hat{\beta}$ becomes:

$$\hat{\beta}_k = \hat{\beta}_{k-1} - \gamma_k C_k \nabla \zeta(\beta_{k-1}; (x_k, y_k)) \tag{3.3}$$

So replacing Step 3 in the above algorithm this way, our SGD estimator at the K^{th} iteration as $\hat{\beta}_K$.

But this algorithm is for the case with known error distribution. In our model since it is unknown, we use the method of sieves to get a feasible semiparametric estimator. The

following is the k_{th} sieve SGD **group** updating for β, with $k = 1, 2, ...K$.

$$\tilde{\beta}_k = \tilde{\beta}_{k-1} - \gamma_k C_k \frac{1}{n} \sum_{i=1}^{n} \nabla \tilde{\zeta}_{k-1}(\beta_{k-1}; (x_i, y_i)) \tag{3.4}$$

where $\tilde{\zeta}_{k-1}(\tilde{\beta}_{k-1}; (x_i, y_i))$ is the estimation for $\zeta(\tilde{\beta}_{k-1}; (x_i, y_i))$ using logistic series estimation.

The following details each step of this algorithm :

Algorithm 2 SieveSGD group estimator

1: Denote initial estimate of β_0 and $g(.)$ as $\tilde{\beta}_0$ and $\tilde{g}_0(.)$, and recall ^{T} denote transpose of a vector; calculate $\nabla \tilde{\zeta}_0(\tilde{\beta}_0; (x_i, y_i)) = (\tilde{g}_0(x_i^T \tilde{\beta}_0) - y_i)x_i$ for each i.
2: In first iteration, use group SGD updating in (4.5) to update $\tilde{\beta}_0$ to $\tilde{\beta}_1$
3: Calculate $z_{1i} = \tilde{\beta}_1 * x_i$ for each $i = 1, 2, ...n$
4: Using the full sample of n observations, calculate logistic regression of y_i on index $\tilde{\pi}_0^1 + z_{1i}\tilde{\pi}_1^1 + z_{1i}^2\tilde{\pi}_2^1 + ... + z_{1i}^q\tilde{\pi}_q^1$ to get estimation of error distribution $g(.)$(here q relates to order of sieve approximation)
5: Calculate $\nabla \tilde{\zeta}_1(\tilde{\beta}_1; (x_i, y_i)) = (L(\tilde{\pi}_0^1 + z_{1i}\tilde{\pi}_1^1 + z_{1i}^2\tilde{\pi}_2^1 + ... + z_{1i}^q\tilde{\pi}_q^1) - y_i)x_i$ for each i, where $L(.)$ denotes the CDF of logistic distribution.
6: Go back to 2 to get next iteration and repeat. So in general, in k_{th} iteration, use group SGD updating (4.5) to calculate $\tilde{\beta}_k$.
7: Calculate $z_{ki} = \tilde{\beta}_k * x_i$ for each i, and calculate logistic regression of y_i on index $\tilde{\pi}_0^k + z_{ki}\tilde{\pi}_1^k + z_{ki}^2\tilde{\pi}_2^k + ... + z_{ki}^q\tilde{\pi}_q^k$ to get estimation of error distribution $g(.)$, calculate $\nabla \tilde{\zeta}_k(\tilde{\beta}_k; (x_i, y_i)) = (L(\tilde{\pi}_0^k + z_{ki}\tilde{\pi}_1^k + z_{ki}^2\tilde{\pi}_2^k + ... + z_{ki}^q\tilde{\pi}_q^k) - y_i)x_i$ for each i.
8: Set $k = k + 1$ and repeat step 5 and 6 until you get to K and $\tilde{\beta}_K$.

We denote the SSGD estimator as $\tilde{\beta}_K$.

Finally we introduce a third algorithmic based estimator, also using the method of sieves. Basically this just averages all the K estimates computed in the previous algorithm.

Algorithm 3 SieveSGD average estimator

1: Initially guess β_0 and $g(.)$ as $\tilde{\beta}_0$ and $\tilde{g}_0(.)$, calculate $\nabla\tilde{\zeta}_0(\tilde{\beta}_0;(x_i,y_i)) = (\tilde{g}_0(x_i^T\tilde{\beta}_0) - y_i)x_i$ for each $i = 1, 2, ...n$.
2: In first iteration, use group SGD updating 4.5 to update $\tilde{\beta}_0$ to $\tilde{\beta}_1$
3: Calculate $z_{1i} = \tilde{\beta}_1 * x_i$ for each $i = 1, 2, ..n$
4: Calculate logistic regression of y_i on index $\tilde{\pi}_0^1 + z_{1i}\tilde{\pi}_1^1 + z_{1i}^2\tilde{\pi}_2^1 + ... + z_{1i}^q\tilde{\pi}_q^1$ to get estimation of error distribution $g(.)$(here q is the tuning parameter), calculate $\nabla\tilde{\zeta}_1(\tilde{\beta}_1;(x_i,y_i)) = (L(\tilde{\pi}_0^1 + z_{1i}\tilde{\pi}_1^1 + z_{1i}^2\tilde{\pi}_2^1 + ... + z_{1i}^q\tilde{\pi}_q^1) - y_i)x_i$ for each i.($L(.)$ is CDF of logistic distribution)
5: Go back to 2 to update $\tilde{\beta}_1$ to $\tilde{\beta}_2$ and repeat. In k_{th} iteration, use group SGD updating 4.5 calculate $\tilde{\beta}_k$.
6: Calculate $z_{ki} = \tilde{\beta}_k * x_i$ for each i, calculate logistic regression of y_i on index $\tilde{\pi}_0^k + z_{ki}\tilde{\pi}_1^k + z_{ki}^2\tilde{\pi}_2^k + ... + z_{ki}^q\tilde{\pi}_q^k$ to get updated estimation of error distribution $g(.)$, calculate $\nabla\tilde{\zeta}_k(\tilde{\beta}_k;(x_i,y_i)) = (L(\tilde{\pi}_0^k + z_{ki}\tilde{\pi}_1^k + z_{ki}^2\tilde{\pi}_2^k + ... + z_{ki}^q\tilde{\pi}_q^k) - y_i)x_i$ for each i.
7: Repeat step 5 and 6 until you get $\tilde{\beta}_K$.
8: Lastly, calculate the average of the K estimates, $\tilde{\beta}_k, k = 1, 2, ...K$.
$\bar{\beta}_K = \frac{1}{K-t}\sum_{k=1}^{k=K-t}\tilde{\beta}_k$

We denote this averaged estimator, ASSGD, as $\bar{\beta}_K$.

To establish the validity of our algorithmic based estimators we use the assumptions that are similar to Toulis and Airoldi (2017).

Assumption 3.1. *$\{\gamma_k\} = \gamma_1 k^{-\gamma}$, where $\gamma_1 > 1$ is the learning parameter, $\gamma \in (0.5, 1]$.*

Assumption 3.2. *function $g(.)$ satisfies J-Lipschitz conditions, i.e, $0 \leq g(b) - g(a) \leq J * (b - a)$ and $g(.)$ is non-decreasing and differentiable almost surely.*

Assumption 3.3. *The matrix $\hat{I}_i(\beta) \equiv x_i x_i^T$ has nonvanishing trace, that is , there exists constant $b > 0$ such that trace($\hat{I}_i(\beta)$) $\geq b$ almost surely, for all β. The matrix $I(\beta_0) = E(\hat{I}_i(\beta_0))$, has minimum eigenvalue $\underline{\lambda}_f > 0$ and maximum eigenvalue $\overline{\lambda}^f < \infty$. (These are standard conditions- see, e.g. Lehmann and Casella (2006), Theorem 5.1,page 463).*

Assumption 3.4. *C_k is a fixed positive-definite matrix, such that $C_k = C + O(\gamma_n)$, where $||C|| = 1$, $C \succ 0$ and symmetric, and C commutes with $I(\beta)$. Every C_k has a greatest eigenvalue $\overline{\lambda}_c$ and smallest eigenvalue $\underline{\lambda}_c$.*

Our first theoretical result is for the SGD algorithm, which is for the parametric model as it is based on knowing the error distribution.

Theorem 1. *Under assumptions 3.1-3.4, assume $K = n$, use SGD algorithm 1 we get*

$$\mathbb{E}||\hat{\beta}_K - \beta_0||^2 \leq \frac{8\overline{\lambda}_c^2\sigma_x^2(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1}}n^{-1} + exp(-log(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})\phi(n))[||\hat{\beta}_0 - \beta_0|| + (1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})^{n_0}A]$$

with n sufficiently large, where $A = 4\overline{\lambda}_c^2\sum_i \gamma_i^2 < \infty$ and $\phi(n) = n^{1-\gamma}$ if $\gamma \in (0.5, 1]$ and $\phi(n) = \log n$ if $\gamma = 1$. n_0 is some constant.

Remark 1. *Thus the above theorem establishes that estimator based on the first algorithm is consistent and can converge at the parametric rate. While interesting as it can apply to any parametric model, and not just logit or probit to yield a computationally tractable estimator for a wide class of models, it is limited in scope when compared to distribution free estimators discussed earlier in the paper.*

To establish asymptotic properties of our SSGD algorithm based estimator for semiparametric models, we impose the following additional conditions. They are primarily for the sieve component in our algorithm and similar to those in Hirano et al. (2003)

Assumption 3.5. *the support $\mathbf{X}$ of X is a compact subset of $\mathbb{R}^p$.*

Assumption 3.6. *the cdf $g(.)$ is s times continuously differentiable, with $s \geq 4$.*

Assumption 3.7. *the cdf $g(.)$ is bounded away from zero and one on $\mathbf{X}$.*

Assumption 3.8. *the density of X is bounded away from zero on $\mathbf{X}$.*

Assumption 3.9. *$q \to \infty$ as $n \to \infty$ and $q^3/n \to 0$.*

With these assumptions we have the following result for our algorithmic based estimator for the semiparametric binary choice and monotone index models:

Theorem 2. *Under assumptions 3.1-3.4 and 3.6-3.10, assume* $\gamma_0 = 0$. *By setting* $n^{\frac{1}{2\gamma}} \leq K(n) \leq n^{\frac{1}{\gamma}}$,*using sieve SGD group algorithm 2 we get*

$$\mathbb{E}||\tilde{\beta}_{K(n)} - \beta_0||^2 \leq \frac{2(C_1\sqrt{C_2} + 4\overline{\lambda}_c^2\sigma_x^2)(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2}}(K(n))^{-\gamma}$$
$$+ exp(-log(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})\phi(K(n)))[||\beta_0 - \beta_0|| + (1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})^{n_0}A]$$

with n *sufficiently large, where* $A = (C_1\sqrt{C_2} + 4\overline{\lambda}_c^2\sigma_x^2)\sum_i \gamma_i^2 < \infty$,$\phi(K(n)) = K(n)^{1-\gamma}$ *if* $\gamma < 1$ *and* $\phi(K(n)) = log(K(n))$ *if* $\gamma = 1$. n_0 *is some constant.*

Remark 2. *Thus we can conclude that our algorithmic based estimator for the regression coefficients in the semiparametric models are consistent and can indeed converge at the parametric rate. This is a main advantage of our approach compared to the existing literature, as our algorithm is designed to be implementable with many regressors, in contrast to rank based estimators and closed form estimators which require nonparametric estimation in the first stage. The result shows that this does not come at a cost of a slower rate of convergence.*

The next theorem establishes limiting distribution for the algorithmic estimator for models of fixed dimension.

Theorem 3. *Under assumptions 3.1-3.4 and 3.6-3.10, assume* $\gamma_0 = 0$. *By setting* $K(n) = n$ *and* $\gamma \in (0.5, 1)$,*using sieve SGD average algorithm 3 we get*

$$\sqrt{n}(\bar{\beta}_K - \beta_0) \to N(0, \Sigma_2^{-1}\Sigma_1\Sigma_2^{-1})$$

where $\Sigma_1 = \mathbb{E}g(x_k^T\beta_0)(1-g(x_k^T\beta_0))x_kx_k^T$ *and* $\Sigma_2 = \mathbb{E}g'(x_k^T\beta_0)x_kx_k^T - f(x_k^T\beta_0)$, *where* $f(x_k^T\beta_0)) = \lim_{q\to\infty} x_kR^q(x_k^T\beta_0)^T\mathbb{E}R^{q\prime}(x_i^T\beta^*)g'(x_i^T\beta_0)x_i^T$ *and* $R^q(x_k^T\beta_0)$ *is orthogonal polynomial function of* $x_k^T\beta_0$, *and* $R^{q\prime}(x_k^T\beta_0)$ *denotes its derivative.*

While the previous result is desirable it is limited in the sense that it is based on models of fixed dimension. This is in contrast to some of the recent literature designed for big data sets which are modeled as the dimension increasing with the sample size. To attain a result for

these models, we impose the following additional assumptions on p, the number of regressors, which now depend on n.:

Assumption 3.10. *$var(x^T\beta_0)$ is bounded.*

Assumption 3.11. *$p \to \infty$ as $n \to \infty$ and $p/n \to 0$ where ρ is any positive number.*

Assumption 3.12. *$p \to \infty$ as $n \to \infty$ and $p^2/n \to 0$ where ρ is any positive number.*

With these additional conditions our next result establishes rates of convergence for the algorithmic estimator.

Theorem 4. *Under assumption 3.1-3.4 and 3.6-3.12, using sieve SGD group algorithm 2 and $\gamma_0 = 0$ and by setting $n^{\frac{1}{2\gamma}} \leq K(n) \leq n^{\frac{1}{\gamma}}$ with $pK(n)^{-\gamma} \to 0$,we get*

$$\mathbb{E}||\tilde{\beta}_{K(n)} - \beta_0||^2 \leq \frac{2(C_3\sqrt{C_4}C_5 + 4\overline{\lambda}_c^2\sigma_x^2)(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2}}pK(n)^{-\gamma}$$
$$+ exp(-log(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})\phi(K(n)))[||\tilde{\beta}_0 - \beta_0|| + (1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})^{n_0}A]$$

with n sufficiently large, where $A = (C_3\sqrt{C}_4C_5 + 4\overline{\lambda}_c^2\sigma_x^2)\sum_i \gamma_i^2 < \infty$ and $\phi(K(n)) = (K(n))^{1-\gamma}$if $1 - \gamma > 0$ and $\phi(K(n)) = log(K(n))$ if $1 - \gamma = 0$. $\gamma \in (0.5, 1]$. n_0 is some constant.

Next, we state conditions for the limiting distribution theory of sieve based algorithm estimator

Theorem 5. *Under assumption 3.1-3.4 and 3.6-3.13, by setting $K(n) = n$ and choosing $\gamma \in (0.5, 1)$ and $\frac{p^2}{n^{2\gamma-1}} \to 0 \to 0$,using sieve SGD average algorithm 3, assuming $\gamma_0 = 0$ and x_k are independent across each regressor, for any $\varsigma \in \mathbb{R}^p$ with $||\varsigma|| = 1$ we get $||\bar{\beta}_K - \beta_0|| = o_p(\sqrt{\frac{p}{n}})$, and*

$$\sqrt{n}\frac{\varsigma'(\bar{\beta}_K - \beta_0)}{(\varsigma'\Sigma_2^{-1}\Sigma_1\Sigma_2^{-1}\varsigma)^{\frac{1}{2}}} \to N(0, 1)$$

where $\Sigma_1 = \mathbb{E}g(x_k^T\beta_0)(1-g(x_k^T\beta_0))x_k x_k^T$ *and* $\Sigma_2 = \mathbb{E}g'(x_k^T\beta_0)x_k x_k^T - f(x_k^T\beta_0)$*, where* $f(x_k^T\beta_0)) = \lim_{q\to\infty} x_k R^q(x_k^T\beta_0)^T \mathbb{E}R^{q\prime}(x_i^T\beta_0)g'(x_i^T\beta_0)x_i^T$ *and* $R^q(x_k^T\beta_0)$ *is orthogonal polynomial function of* $x_k^T\beta_0$*, and* $R^{q\prime}(x_k^T\beta_0)$ *denotes its derivative.*

4. Extensions

One of the advantages of our proposed procedures is it can be used for more complicated models involving a binary equation with many regressors, in which case rank based procedures would be difficult to implement. Examples of these models include ones studied in Manski (1987), Abrevaya et al. (2010), Khan and Tamer (2007), Khan et al. (2019), Khan et al. (2020), for binary choice panel data models, triangular binary systems, duration models, multinomial choice models, and partially identified transformation models, respectively. In this section we propose a new algorithmic based estimator for a the multinomial choice model in Khan et al. (2019), a binary choice model with fixed effects a binary choice model with sample selection.

4.1. Censored Duration Models

Duration models have seen widespread use in empirical work in various areas of economics. This is because many time-to-event variables are of interest to researchers conducting empirical studies in labor economics, development economics, public finance and finance. For example, the time-to-event of interest may be the length of an unemployment spell, the time between purchases of a particular good, time intervals between child births, and insurance claim durations, to name a few.

Since the seminal work in Cox (1972), Cox (1975), the most widely used models in duration analysis are the proportional hazards model, and its extension, the mixed proportional

hazards model, introduced in Lancaster (1979). These models can be represented as monotonic transformation models, where an unknown, monotonic transformation of the dependent variable is a linear function of observed covariates plus an unobserved error term, subject to restrictions that maintain the (mixed) proportional hazards assumption.

The monotonic transformation model in its most basic form is usually expressed as

$$T(y_i) = x_i'\beta_0 + \epsilon_i \quad i = 1, 2, ...n \tag{4.1}$$

where $(y_i, x_i')'$ is a $(p+1)$ dimensional observed random vector, with y_i denoting the dependent variable, usually a time to event, and x_i denoting a vector of observed covariates. The random variable ϵ_i is unobserved and independent of x_i with an unknown distribution. The function $T(\cdot)$ is assumed to be monotonic, but otherwise unspecified. The p-dimensional vector β_0 is unknown, and is often the object of interest to be estimated from a random sample of n observations.

Duration data is often subject to right censoring for a variety of reasons that are usually a consequence of the empirical researcher's observation or data collection plan.

When the data is subject to censoring the variable y_i is no longer always observed. Instead one observes the pair (v_i, d_i) where v_i is a scalar random variable, and d_i is a binary random variable. We can express the *right censored* transformation model as

$$T(v_i) = \min(x_i'\beta_0 + \epsilon_i, c_i) \tag{4.2}$$

$$d_i = I[x_i'\beta_0 + \epsilon_i \leq c_i] \tag{4.3}$$

where $I[\cdot]$ denotes the indicator function, and c_i denotes the random censoring variable. We note the censoring variable need not always be observed, as would occur in a *competing risks* type setting (see, e.g. Heckman and Honoré(1990)).

Here wish to allow for the presence of *covariate dependent* censoring, i.e., in the case where c_i can be arbitrarily correlated with x_i. This would be in line with the form of censoring

allowed for in the Partial Maximum Likelihood Estimator (PMLE) introduced in Citecox2. Since the censoring variable need not be restricted to be a function of the index, this model no longer fits intro the framework of single, monotone index models.

Nonetheless, Khan and Tamer (2007) sowed that the regression coefficients β_0 could still be identified and estimated because properly transformed variables could indeed satisfy a monotone index condition. After such a transformation they proposed what they referred to as a partial rank estimator. Like the rank estimators referred to at the beginning of this paper, it involved optimizing a non smooth, yonconvex objective function, And so was to suitable for large dimensional models. This motivates our algorithmic based approach.

To illustrate how to construct it for this model, we first transform the observed variables, v_i, x_i, d_i as done in Khan and Tamer (2007):

$$\begin{aligned} y_{0i} &= v_i \\ y_{1i} &= d_i v_i + (1 - d_i) \cdot (+\infty) \end{aligned} \tag{4.4}$$

They then showed that for a pair of distinct observations, i, j that the probability $P(y_{1i} \geq y_{0j} | x_i, x_j)$ is monotonic in the index $(x_j - x_i)'\beta_0)$ This motivated a constructive identification result and a rank based estimation procedure. A drawback of this procedure was computational, because like the original MRC the objective function was non smooth and non concave. This motivates an algorithmic procedure similar to before, but with the following adjustments for this model, and that is based on splitting the sample into pairs (1,n),(2,n-1), etc.

Let $y_{ssi} = I[y_{1i} \geq y_{0(n-i+1)}] \quad i = 1, 2, ...n/2.$

Let $x_{ssi} = (x_i - x_{n-i+1})$.

Here the k_{th} sieve SGD **group** updating for β, with $k = 1, 2, ...K$.

$$\tilde{\beta}_k = \tilde{\beta}_{k-1} - \gamma_k C_k \frac{2}{n} \sum_{i=1}^{n/2} \nabla \tilde{\zeta}_{k-1}(\beta_{k-1}; (x_{ssi}, y_{ssi})) \tag{4.5}$$

where $\nabla \tilde{\zeta}_{k-1}(\tilde{\beta}_{k-1}; (x_{ssi}, y_{ssi}))$, defined in detail below is the estimation for $\nabla \zeta(\tilde{\beta}_{k-1}; (x_{ssi}, y_{ssi}))$ using logistic series estimation described below.

1: Denote initial estimate of β_0 and error distribution $g(.)$ as $\tilde{\beta}_0$ and $\tilde{g}_0(.)$, use standard logit for $\tilde{g}_0(.)$, and recall ^{T} denote transpose of a vector; calculate $\nabla \tilde{\zeta}_0(\tilde{\beta}_0; (x_{ssi}, y_{ssi})) = (\tilde{g}_0(x_{ssi}^T \tilde{\beta}_0) - y_{ssi}) x_{ssi}$ for each $i = 1, 2, ...n/2$.
2: In first iteration, use group SGD updating in (4.5) to update $\tilde{\beta}_0$ to $\tilde{\beta}_1$
3: Calculate $z_{1ssi} = \tilde{\beta}_1 * x_{ssi}$ for each $i = 1, 2, ...n/2$
4: Using the sample of $n/2$ observations, calculate logistic regression of y_{ssi} on index $\tilde{\pi}_0^1 + z_{1ssi}\tilde{\pi}_1^1 + z_{1ssi}^2\tilde{\pi}_2^1 + ... + z_{1ssi}^q\tilde{\pi}_q^1$ to get estimation of error distribution $g(.)$(here q relates to order of sieve approximation)
5: Calculate $\nabla \tilde{\zeta}_1(\tilde{\beta}_1; (x_{ssi}, y_{ssi})) = (L(\tilde{\pi}_0^1 + z_{1ssi}\tilde{\pi}_1^1 + z_{1ssi}^2\tilde{\pi}_2^1 + ... + z_{1si}^q\tilde{\pi}_q^1) - y_{ssi}) x_{ssi}$ for each i, where $L(.)$ denotes the CDF of logistic distribution.
6: Go back to 2 to get next iteration and repeat. So in general, in k_{th} iteration, use group SGD updating (4.5) to calculate $\tilde{\beta}_k$.
7: Calculate $z_{ki} = \tilde{\beta}_k * x_{ssi}$ for each i, and calculate logistic regression of y_{ssi} on index $\tilde{\pi}_0^k + z_{ki}\tilde{\pi}_1^k + z_{ki}^2\tilde{\pi}_2^k + ... + z_{ki}^q\tilde{\pi}_q^k$ to get estimation of error distribution $g(.)$, calculate $\nabla \tilde{\zeta}_k(\tilde{\beta}_k; (x_{ssi}, y_{ssi})) = (L(\tilde{\pi}_0^k + z_{ki}\tilde{\pi}_1^k + z_{ki}^2\tilde{\pi}_2^k + ... + z_{ki}^q\tilde{\pi}_q^k) - y_{ssi}) x_{ssi}$ for each i.
8: Set $k = k + 1$ and repeat step 5 and 6 until you get to K and $\tilde{\beta}_K$.

We denote the SSGD estimator as $\tilde{\beta}_K$.

4.2. Multinomial Choice

We consider the standard multinomial response model where the dependent variable takes one of $J + 1$ mutually exclusive and exhaustive alternatives numbered from 0 to J. Specifically, for individual i, alternative j is assumed to have an unobservable indirect utility y_{ij}^*. The alternative with the highest indirect utility is assumed chosen. Thus the observed choice y_{ij} can be defined as

$$y_{ij} = \mathbf{1}[y_{ij}^* > y_{ik}^*, \forall k \neq j]$$

with the convention that $y_{ij} = 0$ indicates that the choice of alternative j is not made by individual i. As is standard in the literature, an assumption of joint continuity of the indirect utilities rules out ties (with probability one). In addition, we maintain the familiar linear form for indirect utilities[5]

$$\begin{aligned} y_{i0}^* &= 0, \\ y_{ij}^* &= x_{ij}'\beta_0 - \epsilon_{ij}, \ j = 1, ..., J, \end{aligned} \tag{4.6}$$

where β_0 is a p-dimensional vector of unknown preference parameters of interest whose first component is normalized to have absolute value 1 (scale normalization). Note that for alternative $j = 0$, the standard (location) normalization $y_{i0}^* = 0$ is imposed. The vector $\epsilon_i \equiv (\epsilon_{i1}, ..., \epsilon_{iJ})'$ of unobserved error terms, attained by stacking all the scalar idiosyncratic errors ϵ_{ij}, is assumed to be jointly continuously distributed and independent of the $p \times J$-dimensional vector of regressors $x_i \equiv (x_{i1}', ..., x_{iJ}')'$[6]. We stress that expression (4.6) is rather general. By properly re-organizing x_{ij}'s and β_0, (4.6) can accommodate both alternative-specific and individual-specific covariates[7]

Consider a multinomial response model with 3 alternatives ($J = 2$) for now where the indirect utilities for alternatives 0, 1, and 2 are

$$\begin{aligned} y_{i0}^* &= 0, \\ y_{ij}^* &= x_{ij}'\beta_0 - \epsilon_{ij}, \ j = 1, 2. \end{aligned}$$

This simple model is sufficient to illustrate our approach, which is straightforward to be applied to data with more alternatives.

[5]Our method can be applied to more general models with indirect utilities $y_{ij}^* = u_j(x_{ij}'\beta_0, -\epsilon_{ij})$, $j = 1, 2$, where $u_j(\cdot, \cdot)$'s are unknown (to econometrician) $\mathbb{R}^2 \mapsto \mathbb{R}$ functions strictly increasing in each of their arguments. It will be clear that our rank procedure does not rely on the additive separability of the regressors and error terms.

[6]We impose the independence restriction here to simplify exposition. As will become clear below, our matching-based approach allows ϵ_i to be correlated with individual-specific regressors.

[7]See Cameron and Trivedi (2005) p. 498 for a detailed discussion.

Given the indirect utilities, the observed dependent variables y_{ij} is of the form

$$y_{ij} = \mathbf{1}[y^*_{ij} > y^*_{ik}, \forall k \neq j], \ j = 0, 1, 2,$$

Important work for semiparametric estimation of the cross sectional model include include Lee (1995), who proposes a profile likelihood approach, extending the results in Klein and Spady (1993a) for the binary response model. Ahn, Ichimura, Powell, and Ruud (2018) propose a two-step estimator that requires nonparametric methods but show the second step is of closed-form. Shi, Shum, and Song (2018) also propose a two-step estimator in panel setups exploiting a cyclic monotonicity condition, which also requires a high dimensional nonparametric first stage, but whose second stage is not closed-form as Ahn, Ichimura, Powell, and Ruud (2018) is.

Khan et al. (2019) optimize the objective function

$$G_{1n}(b) = \frac{1}{n(n-1)} \sum_{i \neq m} \mathbf{1}[x_{i2} = x_{m2}](y_{i1} - y_{m1}) \cdot sgn((x_{i1} - x_{m1})'b), \tag{4.7}$$

with respect to b. This too is nonsmooth non concave and difficult to implement.

Our algorithmic estimator of β_0 using all i^{th}, m^{th} observation pairs is constructed with the following algorithm. It will involve kernel weights as in Ahn and Powell (1993)

$$\hat{\omega}_{im} = k_h((x_{i2} - x_{m2}))$$

where $k(\cdot)$ is a kernel function and h is a bandwidth sequence and $k_h(\cdot) = \frac{1}{h}k(\frac{\cdot}{h})$. Our algorithm involves the following steps:

1. Start with initial guess $\tilde{\beta}_0, \tilde{g}_0$. The second is first guess of the conditional distribution of ϵ_{i1} so use say logit.

2. With these initial guesses calculate the $p \times 1$ vector

$$\nabla\tilde{\zeta}_0(\tilde{\beta}_0, x_{i1}, y_{i1}, \hat{\omega}_{im}) \equiv (\tilde{g}_0(x_i'\tilde{\beta}_0) - y_{i1})x_{i1}\hat{\omega}_{im}$$

for $i = 1, 2, ...n$.

3. Update $\tilde{\beta}$ as

$$\tilde{\beta}_1 = \tilde{\beta}_0 - \gamma_1 C_k \frac{1}{n^2} \sum_{i,j} \nabla \tilde{\zeta}_0(\tilde{\beta}_0, x_{i1}, y_{i1}, \hat{\omega}_{ij})$$

where γ_1 is a "tempering" parameter, C_p is a $p \times p$ matrix (could be identity matrix).

4. With the updated β, $\tilde{\beta}_1$, update $\tilde{g}_0$ to $\tilde{g}_1$ using sieves. Basically updating from logit to flexible logit. Using all observations do logit, of y_{i1} on polynomial $z_{1i}, z_{1i}^2, z_{1i}^q$, where here $z_{1i} = x_{i1}'\tilde{\beta}_1$. Denote the estimated intercept and regression coefficients by $\tilde{\pi}_0, \tilde{\pi}_1, ...\tilde{\pi}_q$. Our update $\tilde{g}$, from $\tilde{g}_0$ to $\tilde{g}_1$ is

$$\tilde{g}_1(z_{1i}) = \Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q)$$

where $\Lambda(\cdot)$ denotes the logit cdf.

5. calculate the $p \times 1$ vector

$$\nabla \tilde{\zeta}_1(\tilde{\beta}_1, x_{i1}, y_{i1}, \hat{\omega}_{im}) \equiv (\Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q) - y_i)x_i t_i \hat{\omega}_{ij}$$

6. Go back to 3.

4.3. Panel Data Binary Choice Models

Here we consider estimation of a binary choice model with fixed effects. Andersen (1970) considered the problem of inference on fixed effects linear models from binary response panel data. He showed that inference is possible if the disturbances for each panel member are known to be white noise with the logistic distribution and if the observed explanatory variables vary over time. Nothing need be known about the distribution of the fixed effects and he proved that a conditional maximum likelihood estimator consistently estimates the model parameters up to scale.

Manski (1987) showed that identification of the regression coefficients remains possible if the disturbances for each panel member are known only to be time-stationary with unbounded support and if the observed explanatory variables vary enough over time and have large support.

Specifically, he considered the model:

$$y_{it} = I[\alpha_i + x'_{it}\beta_0 + \epsilon_{it} > 0] \tag{4.8}$$

where $i = 1, 2, ...n,\ t = 1, 2$. The binary variable y_{it} and the p-dimensional regressor vector x_{it} are each observed and the parameter of interest is the p dimensional vector β_0. The unobservables are α_i, and ϵ_{it}, the former not varying with t and often referred to as the "fixed effect" or the individual specific effect. Manski (1987) imposes no restrictions on the conditional distribution of α_i conditional on $x_i \equiv x_{i1}, x_{i2}$. His identification result is based on the condition that

$$E[y_{i2} - y_{i1}|x_{i1}, x_{i2}, y_{i1} \neq y_{i2}]$$

is monotonic in $(x_{i2} - x_{i1})'\beta_0$.

His proposed an estimator of β_0 up to a scale normalization that optimized the following objective function

$$\frac{1}{n}\sum_{i=1}^{n} I[y_{i2} \neq y_{i1}]|(y_{i2} - y_{i1}) - I[(x_{i2} - x_{i1})'\beta > 0]| \tag{4.9}$$

As was the case with the rank estimators discussed earlier on in this paper , this estimator is difficult to compute due to the non smoothness and non convexity of the objective function. Attaining a global optimum becomes even more difficult the larger the value of p, making this estimator unsuitable for large dimensional models.

This motivates our algorithmic procedure we introduce here:

1. Start with initial guess $\tilde{\beta}_0, \tilde{g}_0$. The second is first guess of the conditional probability of $y_{i2} = 1, y_{i1} = 0$ conditioning on $y_{i1} \neq y_{i2}$.

2. With these initial guesses calculate the $p \times 1$ vector

$$\nabla\tilde{\zeta}_0(\tilde{\beta}_0, \Delta x_i, \Delta y_i) \equiv (\tilde{g}_0(\Delta x_i'\tilde{\beta}_0) - \Delta y_i)\Delta x_i\omega_i$$

   for $i = 1, 2, ...n$. Where $\Delta y_i \equiv (y_{i2} - y_{i1})$, $\Delta x_i \equiv (x_{i2} - x_{i1}), \omega_i \equiv I[y_{i1} \neq y_{i2}]$

3. Update $\tilde{\beta}$ as

$$\tilde{\beta}_1 = \tilde{\beta}_0 - \gamma_1 C_k \frac{1}{n^*} \sum_{i=1}^{n} \nabla\tilde{\zeta}_0(\tilde{\beta}_0, \Delta x_i, \Delta y_i)$$

   where γ_1 is a "tempering" parameter, C_k is a $p \times p$ matrix (could be identity matrix), $n_0 \equiv \sum_{i=1}^{n} I[y_{i1} \neq y_{i2}]$.

4. With the updated β, $\tilde{\beta}_1$, update $\tilde{g}_0$ to $\tilde{g}_1$ using sieves, basically again updating from a logit to flexible logit. Using all observations, do logit of Δy_i on polynomial $z_{1i}, z_{1i}^2, z_{1i}^q$, where $z_{1i} = \Delta x_i'\tilde{\beta}_1$. Denote the estimated regression coefficients by $\tilde{\pi}_0, \tilde{\pi}_1, ...\tilde{\pi}_q$. Our updated $\tilde{g}$, from $\tilde{g}_0$ to $\tilde{g}_1$ is

$$\tilde{g}_1(z_{1i}) = \Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q)$$

   where $\Lambda(\cdot)$ denotes the logit cdf.

5. calculate the $p \times 1$ vector

$$\nabla\tilde{\zeta}_1(\tilde{\beta}_0, \Delta x_i, \Delta y_i) \equiv (\Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q) - \Delta y_i)\Delta x_i$$

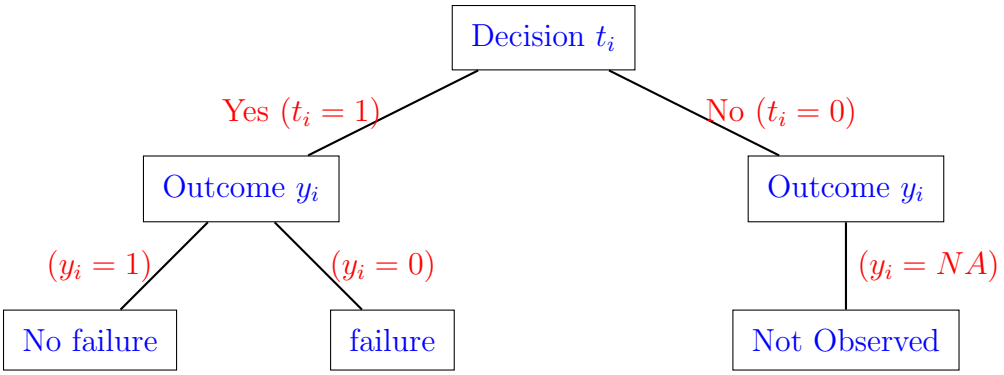
6. Go back to 3.

4.4. Selective Labeling Models

These models arise in the many domains where the observed binary outcomes are themselves a consequence of the existing choices of of one of the agents in the model. These models are gaining increasing interest in the computer science and machine learning literatures where they refer the potentially endogenous sample selection as the *selective labels problem.* Empirical settings for such models arise in fields as diverse as criminal justice, health care, and insurance. For important recent work in this area, see for example Lakkaraju et al. (2017). The authors there focus on judicial bail decisions, and where one observes the outcome of whether a defendant filed to return for their court appearance only if the judge in the case decides to release the defendant on bail. Letting t_i denote the binary decision to grant bail, and y_i denote the binary outcome of the defendant returning for court appearance, they consider a model of the form

$$y_i = \begin{cases} 0 \text{ or } 1, & \text{if } t_i = 1 \\ \text{not observed (NA)}, & \text{otherwise} \end{cases} \tag{4.10}$$

This process and the ensuing model can be best explained with the diagram below. The top node indicates the decision made by the agent (judge in our criminology example) which corresponds to a *yes* ($t_i = 1$) or *no* ($t_i = 0$) on individual i. The other observed dependent variable, corresponding to the two nodes beneath the top one, is denoted by y_i, where $y_i \in \{0, 1, NA\}$ and denotes the resulting outcome (return to court in our example). The selective labels problem occurs because the observation of outcome y_i is constrained by the decision t_i made by the judge:



Of course controlling for selection bias has a rich history in the econometrics literature, but usually for models where the outcome variable after selection is continuous. Seminal work in the parametric literature is in Heckman (1974) and for a semiparametric approach see Ahn and Powell (1993).

With the availability of regressors for each of the equations in the binary outcome our econometric model is of the form:

$$t_i = I[w_i'\delta_0 + \eta_i > 0] \tag{4.11}$$

$$y_i = t_i \cdot I[x_i'\beta_0 + \epsilon_i > 0] \tag{4.12}$$

Wish to first estimate δ_0, β_0 based on a random sample of (t_i, w_i, y_i, x_i).

Our proposed way is to first estimate $k-$ dimensional vector δ_0 first and with that, use a matching as in Ahn and Powell (1993) to estimate β_0. We will not use rank in either step because the dimension of w_i, x_i are large. To illustrate will assume w.l.o.g. that each are $k \times 1$ vectors.

Algorithm for estimating δ_0, which is identical to algorithm discussed in previous section :

1. Start with initial guess $\tilde{\delta}_0, \tilde{g}_0$. The second is first guess of distribution of η_i, so use say logit.

2. With these initial guesses calculate the $k \times 1$ vector

$$\nabla\tilde{\zeta}_0(\tilde{\delta}_0, w_i, d_i) \equiv (\tilde{g}_0(w_i'\tilde{\delta}_0) - t_i)w_i$$

for $i = 1, 2, ...n$.

3. Update $\tilde{\delta}$ as

$$\tilde{\delta}_1 = \tilde{\delta}_0 - \gamma_1 C_k \frac{1}{n}\sum_{i=1}^{n} \nabla\tilde{\zeta}_0(\tilde{\delta}_0, w_i, t_i)$$

where γ_1 is a "tempering" parameter, C_k is a $k \times k$ matrix (could be identity matrix).

4. With the updated δ, $\tilde{\delta}_1$, update $\tilde{g}_0$ to $\tilde{g}_1$ using sieves. Basically updating from logit to flexible logit. Using all observations, do logit of d_i on polynomial $z_{1i}, z_{1i}^2, z_{1i}^q$, where $z_{1i} = w_i'\tilde{\delta}_1$. Denote the estimated intercept and regression coefficients by $\tilde{\pi}_0, \tilde{\pi}_1, ...\tilde{\pi}_q$. Our updated $\tilde{g}$, from $\tilde{g}_0$ to $\tilde{g}_1$ is

$$\tilde{g}_1(z_{1i}) = \Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q)$$

where $\Lambda(\cdot)$ denotes the logit cdf.

5. calculate the $k \times 1$ vector

$$\nabla\tilde{\zeta}_1(\tilde{\delta}_0, w_i, t_i) \equiv (\Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q) - t_i)w_i$$

6. Go back to 3.

Now to estimate β_0, we will do something similar, but control for selection bias. Our estimator of β_0 using all i^{th}, j^{th} observation pairs is constructed with the following algorithm. It will involve kernel weights as in Ahn and Powell (1993)

$$\hat{\omega}_{ij} = k_h((w_i - w_j)'\hat{\delta})$$

where $\hat{\delta}$ is our first stage algorithmic estimator described above. $k(\cdot)$ is a kernel function and h is a bandwidth sequence and $k_h(\cdot) = \frac{1}{h}k(\frac{\cdot}{h})$. Our second step algorithm involves the following steps:

1. Start with initial guess $\tilde{\beta}_0, \tilde{g}_0$. The second is first guess of the conditional distribution of ϵ_i, conditioning on $\eta_i > -w_i'\delta_0$, so use say logit.

2. With these initial guesses calculate the $k \times 1$ vector

$$\nabla\tilde{\zeta}_0(\tilde{\beta}_0, x_i, t_i, y_i, \hat{\omega}_{ij}) \equiv (\tilde{g}_0(x_i'\tilde{\beta}_0) - y_i)x_i t_i \hat{\omega}_{ij}$$

   for $i = 1, 2, ...n$.

3. Update $\tilde{\beta}$ as

$$\tilde{\beta}_1 = \tilde{\beta}_0 - \gamma_1 C_k \frac{1}{n^2} \sum_{i,j} \nabla\tilde{\zeta}_0(\tilde{\beta}_0, x_i, t_i, y_i, \hat{\omega}_{ij})$$

   where γ_1 is a "tempering" parameter, C_k is a $k \times k$ matrix (could be identity matrix).

4. With the updated β, $\tilde{\beta}_1$, update $\tilde{g}_0$ to $\tilde{g}_1$ using sieves. Basically updating from logit to flexible logit. Using all observations for which $t_i = 1$, do logit, of y_i on polynomial $z_{1i}, z_{1i}^2, z_{1i}^q$, where here $z_{1i} = x_i'\tilde{\beta}_1$. Denote the estimated intercept and regression coefficients by $\tilde{\pi}_0, \tilde{\pi}_1, ...\tilde{\pi}_q$. Our update $\tilde{g}$, from $\tilde{g}_0$ to $\tilde{g}_1$ is

$$\tilde{g}_1(z_{1i}) = \Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q)$$

   where $\Lambda(\cdot)$ denotes the logit cdf.

5. calculate the $k \times 1$ vector

$$\nabla\tilde{\zeta}_1(\tilde{\beta}_1, x_i, t_i, y_i, \hat{\omega}_{ij}) \equiv (\Lambda(\tilde{\pi}_0 + z_{1i}\tilde{\pi}_1 + z_{1i}^2\tilde{\pi}_2 + ...z_{1i}^q\tilde{\pi}_q) - y_i)x_i t_i \hat{\omega}_{ij}$$

6. Go back to 3.

Implementation of this algorithm involves selection of matching weights, as is often the case for estimating selection and treatment effect models- see, e.g. Ahn and Powell (1993). As in there, for consistency of our procedure we require $h_n \to 0$ as $n \to \infty$, and further restrictions to ensure root-n consistency and asymptotic normality of the second stage estimator of β_0.

5. Simulation Study

In this section we explore the relative finite sample properties of our estimation procedure by presenting the results from a series of Monte Carlo experiments. In the simulation study we focus on the binary choice model:

$$y_i = \mathbb{1}\{x_i^T \beta_0 > \epsilon\}$$

x_i and β_0 is a vector with length 9, the true value of β_0 is $\{1, 1, 2, 4, 5, -1, -2, -4, -5\}$. ϵ follows either standard normal distribution or cauchy distribution with location equivalent to 0 and scale equivalent to 1. We set $q = 2$, which means we use z, z^2 and z^3 to estimate the underlying distribution. The number of observations were 5000 or 10000. We calculate the average time of each experiment, mean bias and root mean square error with 500 experiments.

MRC estimator and MS estimator are not feasible in the binary choice model with more than 3 regressors. We compare our estimator (KLT) with Dominitz and Sherman (2005) (DS), where they use iterative least square with kernel estimation of the distribution of error, which in one sense is similar to ours. One major problem with theirs is that there are 3 tuning parameters in the process and no clear way to choose them in computing the estimator.

TABLE 1. COMPUTATION TIME(SECOND)

	KLT		DS	
Sample size	Normal error	Cauchy error	Normal error	Cauchy error
5000	349.896	201.324	758.784	746.196
10000	642.756	400.62		

We can see from Table 1 that our estimator requires much less time to compute than the estimator of Dominitz and Sherman (2005). For the sample size of 10000, the time of our estimator is around 10 min, which is reasonable and feasible for empirical studies.

Table 2 and Table 3 are the mean bias and root mean square error (RMSE) of our estimator and their estimator. The mean bias does not decrease with the number of observations may

Table 2. normal distribution comparison

	KLT				DS	
	N=5000		N=10000		N=5000	
Beta	Bias	RMSE	Bias	RMSE	Bias	RMSE
1	-0.00245	0.074159	-0.00431	0.051545	0.089473	-0.00759
2	-0.00528	0.116748	-0.00543	0.085119	0.128051	-0.00852
4	-0.00383	0.215743	-0.01637	0.156179	0.236556	-0.01471
5	-0.00334	0.264365	-0.02086	0.194141	0.291545	-0.01225
-1	0.001095	0.073209	0.003431	0.051931	0.089551	-0.00076
-2	0.00202	0.119057	0.008036	0.086456	0.128528	0.00513
-4	0.001222	0.214129	0.016845	0.158186	0.236176	0.009738
-5	0.003662	0.263349	0.018584	0.19901	0.289038	0.013762

Table 3. cauchy distribution comparison

	KLT				DS	
	N=5000		N=10000		N=5000	
Beta	Bias	RMSE	Bias	RMSE	Bias	RMSE
1	0.009164	0.141747	0.007211	0.102666	0.192022	-0.16365
2	0.011969	0.230573	0.010308	0.167794	0.379245	-0.3429
4	0.028555	0.422073	0.0264	0.289527	0.743516	-0.68575
5	0.046395	0.532154	0.028414	0.359989	0.919298	-0.84691
-1	-0.01341	0.14509	-0.00531	0.103166	0.194638	0.163287
-2	-0.00424	0.228275	-0.01507	0.161979	0.379526	0.345423
-4	-0.03135	0.419305	-0.02808	0.295145	0.735462	0.681659
-5	-0.04541	0.530584	-0.02518	0.371865	0.921918	0.853838

due to the constant complexity of sieve space. The RMSE of our estimator decrease with size. The bias and RMSE of their estimator is high and this may be because it's hard to select the many required tuning parameters with their procedure.

6. Conclusions

In this paper, we proposed a new estimation procedures for binary choice and monotonic index models with increasing dimensions. From an empirical perspective the model can be motivated by models of consumer demand with large consideration sets so prices of many compliments and substitutes are explanatory variables. Existing estimation procedures for this model cannot be implemented in practice when the number of regressors is large. In contrast, our algorithmic based procedure can be used for many regressor models as it involves convex optimization at each iteration of the procedure. We show this iterative procedure also has desirable asymptotic properties when the number of regressors increases with the sample size in ways that are standard in "big data" literature.

Our work here leaves areas for future research. This paper focused on a single equation binary choice model. It would be interesting to see how the proposed algorithmic estimator can be extended to nonbinary and/or systems of simultaneous equation models with a large number of regressors in each equation in each model. For example rank estimators were proposed for the multinomial choice model was proposed in Khan et al. (2019), but was difficult computationally when there were many regressors. We aim to see how our approach in this paper can be adapted to estimate that model and what its asymptotic properties would be. Similarly, Khan and Tamer (2007) propose a rank estimator for duration models with general forms of censoring, that was also difficult computationally for large dimensional models, We conjecture now and aim to show in future work that our approach here is adaptable for that class of models.

Finally, our results here concern high-dimensional models where the number of covariates is at most the same order as the sample size. A recent related literature concerns ultra-high-dimensional models where the number of covariates is much larger than the sample size. In those models some form of (approximate) sparsity is imposed in the model- see, e.g., Belloni et al. (2014a), Belloni et al. (2017). In that setting, inference is conducted after covariate selection, where the resulting number of selected covariates is much smaller. It would be of interest to investigate if such an approach for that type of design can be considered using our method here for large dimensional monotone index models.

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A. Appendix

Lemma 1. *Suppose $g : R \to R$ is a non-decreasing function, then there exists a convex function $G : R \to R$ such that $G' = g$.*

Proof. Define $G(x) = \int_d^x g(t)dt$, where d is a constant. Then $G(x)$ is convex since $G'(x) = g(x) \geq 0$. □

Lemma 2. *Suppose X is a $v*1$ vector of random variables $X_1, X_2...X_v$ on product probability space $(\Omega, \mathcal{F}, P)$. P is the product of measures $P_1, P_2...P_v$. The domain of at least one of random variables is $\mathbb{R}$ and the measure of it is continuous. $\mathbb{E}(X^TX)$ is positive definite matrix. $g(.)$ is a non-negative continuous function on $\mathbb{R}$. $\mathbb{E}g(X^T\beta) > 0$ for constant vector β with length v. Then $\mathbb{E}g(X^T\beta)(X^TX)$ is positive definite matrix.*

Proof. We know $\mathbb{E}(X^TX)$ and $\mathbb{E}g(X^T\beta)(X^TX)$ are semi-positive definite matrix. If $\det\mathbb{E}(X^TX) = 0$ if and only if there is linear relation between $X_1, X_2...X_v$, then there is no linear relation between $g(X^T\beta)X_1, g(X^T\beta)X_2...g(X^T\beta)X_v$ and we finish the proof.The sufficiency is obvious and we only prove the necessity. There exists a linear relation among columns of $\mathbb{E}(X^TX)$ since $\det\mathbb{E}(X^TX) = 0$. Denote $\mathbb{E}(X^TX)$ as $[A_1, A_2...A_v]$. Suppose $A_1 = a_2 * A_2 + a_3 * A_3 + ... + a_v * A_v$, where $a_1, a_2...a_v$ are constant, and at least one of them is not zero.By changing the second column into $a_2 * A_2 + a_3 * A_3 + ... + a_v * A_v$, we get a new matrix denoted as $[B_1, B_2...B_v]^2$, By changing the second rows into $a_2*B_2+a_3*B_3+...+a_v*B_v$ we get the new matrix, and the first $2 * 2$ elements are the following:

$$\begin{bmatrix} \mathbb{E}(X_1^2) & \mathbb{E}(X_1(a_2X_2 + a_3X_3 + ... + a_vX_v)) \\ \mathbb{E}(X_1(a_2X_2 + a_3X_3 + ... + a_vX_v)) & \mathbb{E}(a_2X_2 + a_3X_3 + ... + a_vX_v)^2 \end{bmatrix}$$

Then the determinant of the above matrix is 0, then by Hölder's inequality, $X_1 = a_2 * X_2 + a_3 * X_3 + ... + a_v * X_v$. □

Theorem 1. *Under assumptions 3.1-3.4, assume $K = n$ we get*

$$\mathbb{E}||\beta_K - \beta_0||^2 \leq \frac{8\overline{\lambda}_c^2\sigma_x^2(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1}}n^{-1} + exp(-log(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})\phi(n))[||\beta_0 - \beta_0|| + (1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})^{n_0}A]$$

with n sufficiently large, where $A = 4\overline{\lambda}_c^2\sum_i \gamma_i^2 < \infty$ and $\phi(n) = n^{1-\gamma}$ if $\gamma \in (0.5, 1]$ and $\phi(n) = logn$ if $\gamma = 1$. n_0 is some constant.

Proof. We start from Eq. (3) and k is the iterative times,

$$\beta_k - \beta_0 = \beta_{k-1} - \beta_0 - \gamma_k C_k \nabla\zeta(\beta_{k-1}; (x_k, y_k))$$

then,

$$\begin{aligned} ||\beta_k - \beta_0||^2 =& ||\beta_{k-1} - \beta_0||^2 \\ & - 2\gamma_k(\beta_{k-1} - \beta_0)^T C_k \nabla\zeta(\beta_{k-1}; (x_k, y_k)) \\ & + \gamma_k^2 ||C_k \nabla\zeta(\beta_{n-1}; (x_k, y_k))||^2 \end{aligned} \tag{A.1}$$

for the third term,

$$\begin{aligned} & \gamma_k^2 ||C_k \nabla\zeta(\beta_{k-1}; (x_k, y_k))||^2 \\ & \leq 4\gamma_k^2 \overline{\lambda}_c^2 \sigma_x^2 \end{aligned}$$

its expectation is bounded as

$$\begin{aligned} & \mathbb{E}(\gamma_k^2 ||C_k \nabla\zeta(\beta_{k-1}; (x_k, y_k))||^2) \\ & \leq 4\gamma_k^2 \overline{\lambda}_c^2 \sigma_x^2 \end{aligned}$$

for the second term,

$$\begin{aligned} & \mathbb{E}(-2\gamma_k(\beta_{k-1} - \beta_0)^T C_k \nabla\zeta(\beta_{k-1}; (x_k, y_k))) \\ & = -2\gamma_k \mathbb{E}((\beta_{k-1} - \beta_0)^T C_k \nabla\zeta(\beta_{k-1}; (x_l, y_k))) \\ & = -2\gamma_k \mathbb{E}((\beta_{k-1} - \beta_0)^T C_k \nabla h(\beta_{k-1}; (x_k, y_k))) \quad [where \nabla h(\beta_{k-1}; (x_k, y_k)) = \mathbb{E}(\nabla\zeta(\beta_{k-1}; (x_k, y_k)|\mathcal{F}_{k-1})] \\ & = -2\gamma_k \mathbb{E}((\beta_{k-1} - \beta_0)^T C_k (\nabla h(\beta_{k-1}; (x_k, y_k)) - \nabla h(\beta_0; (x_k, y_k))) \\ & \leq -2\gamma_k \underline{\lambda}_c \underline{\lambda}_{f1} \mathbb{E}||\beta_{k-1} - \beta_0||^2 \end{aligned}$$

Where $\underline{\lambda}_{f1}$ is the least eigenvalue of $\mathbb{E}g(x_k^T\beta_0)x_k^T x_k$. The last inequality comes from strong

convexity by Assumption 3.3 and 2. $\nabla h(\beta_0;(x_k,y_k))=0$ is implied by Eq.3.1

$$\begin{aligned} & g(x_k^T\beta_0)-\mathbb{E}(y_k|x_k)=0 \\ \implies & g(x_k^T\beta_0)x_k-\mathbb{E}(y_k|x_k)x_k=0 \\ \implies & \mathbb{E}(\nabla\zeta(\beta_0;(x_k,y_k))=0 \\ \implies & \nabla h(\beta_0;(x_k,y_k))=0 \end{aligned}$$

Then we can rewrite Eq. A.1 as

$$\begin{aligned} \mathbb{E}||\beta_k-\beta_0||^2 \leq & (1-2\gamma_k\underline{\lambda}_c\underline{\lambda}_{f1})\mathbb{E}||\beta_{k-1}-\beta_0||^2+4\gamma_k^2\overline{\lambda}_c^2\sigma_x^2 \\ & \frac{1}{(1+2\gamma_k\underline{\lambda}_c\underline{\lambda}_{f1})}\mathbb{E}||\beta_{k-1}-\beta_0||^2+4\gamma_k^2\overline{\lambda}_c^2\sigma_x^2 \end{aligned}$$

By corollary 2.1 in Toulis and Airoldi (2017) with $a_k=4\gamma_k^2\overline{\lambda}_c^2\sigma_x^2$ and $b_k=2\gamma_k\underline{\lambda}_c\underline{\lambda}_{f1}$,and $K=n$ we get

$$\mathbb{E}||\beta_K-\beta_0||^2\leq\frac{8\overline{\lambda}_c^2\sigma_x^2(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1}}n^{-1}+exp(-log(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})\phi(n))[||\beta_0-\beta_0||+(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f1})^{n_0}A]$$

with n sufficiently large, where $A=4\overline{\lambda}_c^2\sum_i\gamma_i^2<\infty$ and $\phi(n)=n^{1-\gamma}$ if $\gamma\in(0.5,1]$ and $\phi(n)=logn$ if $\gamma=1$. n_0 is some constant. □

Theorem 2. *Under assumptions 3.1-3.4 and 3.6-3.10, assume $\gamma_0=0$.By setting $n^{\frac{1}{2\gamma}}\leq K(n)\leq n^{\frac{1}{\gamma}}$,using sieve SGD group algorithm 2 we get*

$$\begin{aligned} \mathbb{E}||\tilde{\beta}_{K(n)}-\beta_0||^2\leq & \frac{2(C_1\sqrt{C_2}+4\overline{\lambda}_c^2\sigma_x^2)(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2}}(K(n))^{-\gamma} \\ & +exp(-log(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})\phi(K(n)))[||\beta_0-\beta_0||+(1+2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})^{n_0}A] \end{aligned}$$

with n sufficiently large, where $A=(C_1\sqrt{C_2}+4\overline{\lambda}_c^2\sigma_x^2)\sum_i\gamma_i^2<\infty$,$\phi(K(n))=K(n)^{1-\gamma}$ if $\gamma<1$ and $\phi(K(n))=log(K(n))$ if $\gamma=1$. n_0 is some constant.

Proof. the following are notations and definitions from Hirano et al. (2003) with some changes; we use matrix norm $||A||=\sqrt{tr(A'A)}$. Define

$$L_N(\pi)=\frac{1}{n}\sum_{i=1}^{n}(y_i lnL(R_q^{\hat{\beta}}(x_i)'\pi)+(1-y_i)lnL(1-R_q^{\hat{\beta}}(x_i)'\pi))$$

$R_q^{\hat{\beta}}(x_i) \equiv R^q(x_i^T\hat{\beta})$, $R_q^{\hat{\beta}}(x) \equiv R^q(x^T\hat{\beta})$, $R_q^{\beta_0}(x) \equiv R^q(x^T\beta_0)$,$R^q(.)$ is the basis functions in Hirano et al. (2003) with order q. $\mathbb{E}R_q^{\hat{\beta}}(x_i) = 0$ for non-constant term and $\mathbb{E}R_q^{\hat{\beta}}(x_i)'R_q^{\hat{\beta}}(x_i) = 1$. $\iota(q) = sup_{x\in X}||R_q^{\hat{\beta}}(x_i)||$, where $\iota(q) \leq Cq$ for some constant C. $L(.)$ is logistic distribution. $g^*(x) \equiv g(x^T\beta_0)$. $L_N(\pi)$ is the MLE of y_i on $x_i^T\hat{\beta}$. Define

$$\hat{\pi}_q = \underset{\pi}{argmax} L_N(\pi)$$

then, we have

$$||\beta_k - \beta_0||^2 = ||\beta_{k-1} - \beta_0||^2 - 2\gamma_k \frac{1}{n}\sum_{i=1}^{n}(\beta_{k-1} - \beta_0)^T C_k \nabla\hat{\zeta}(\beta_{k-1}; (x_i, y_i)) + \gamma_k^2 \frac{1}{n}\sum_{i=1}^{n} ||C_k \nabla\hat{\zeta}(\beta_{k-1}; (x_i, y_i))||^2$$

where $\nabla\hat{\zeta}(\beta_{k-1}; (x_i, y_i) = (L(R_q^{\beta_{k-1}}(x_i)'\hat{\pi}_q) - y_i)x_i$.

for the second term, by maximize $L_N(\pi)$, we get

$$\frac{1}{n}\sum_{i=1}^{n} L(R_q^{\beta_{k-1}}(x_i)'\hat{\pi}_q) - y_i)R_q^{\beta_{k-1}}(x_i) = 0. \tag{A.2}$$

then,

$$\mathbb{E}(L(R_q^{\beta_{k-1}}(x_k)'\hat{\pi}_q) - g(x_k^T\beta_0))R_q^{\beta_{k-1}}(x_k)|\beta_{k-1}, \hat{\pi}_q) = O(\sqrt{1/n}). \tag{A.3}$$

We can approximate $L(R_q^{\beta_{k-1}}(x_k)'\hat{\pi}_q)$ and $g(x_k^T\beta_0)$ with $R_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q$ and $R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*$, according to Lorentz (1986), assuming the second term is increasing[8], then equation becomes

$$\mathbb{E}((R_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q - R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*)R_q^{\beta_{k-1}}(x_k)) = O(\sqrt{1/n}) + O(q^{-s}). \tag{A.4}$$

then we can get $\tilde{\pi}_q^w$

$$\tilde{\pi}_q = \mathbb{E}(R_q^{\beta_{k-1}}(x_k)R_q^{\beta_0}(x_k)')\tilde{\pi}_q^* + O(\sqrt{1/n}) + O(q^{-s}). \tag{A.5}$$

[8]we can relax this to allow some portion of the function is not increasing, but it will not change the result here.

then,

$$
\begin{aligned}
&\mathbb{E}(2\gamma_k \frac{1}{n}\sum_{i=1}^{n}(\beta_{k-1}-\beta_0)^T C_k \nabla\hat{\zeta}(\beta_{k-1};(x_i,y_i)))\\
=&2\gamma_k \underline{\lambda}_c \mathbb{E}\frac{1}{n}\sum_{i=1}^{n}(L(R_q^{\beta_{k-1}}(x_i)'\hat{\pi}_q)-y_i)(x_i^T\beta_{k-1}-x_i^T\beta_0)\\
\geq&2\gamma_k \underline{\lambda}_c \mathbb{E}_{\beta_{k-1}}\mathbb{E}((L(R_q^{\beta_{k-1}}(x_k)'\hat{\pi}_q)-g(x_k^T\beta_0))(x_i^T\beta_{k-1}-x_k^T\beta_0)|\beta_{k-1})\\
&-(O(\iota(q)q^{-s}\frac{1}{\sqrt{n}})+O(\frac{\iota(q)^2}{n})+O(\frac{1}{\sqrt{n}}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}}\\
&-O(\frac{1}{\sqrt{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2\\
\geq&2\gamma_k \underline{\lambda}_c \mathbb{E}_{\beta_{k-1}}\mathbb{E}((R_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q-R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*)(x_i^T\beta_{k-1}-x_k^T\beta_0)|\beta_{k-1})\\
&-\gamma_k(O(q^{-s})+O(\frac{\iota(q)^2}{n})+O(\frac{1}{\sqrt{n}}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}}-O(\frac{1}{\sqrt{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2\\
\geq&2\gamma_k \underline{\lambda}_c \mathbb{E}_{\beta_{k-1}}\mathbb{E}((\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*-R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*)(x_i^T\beta_{k-1}-x_k^T\beta_0)|\beta_{k-1})\\
&-\gamma_k(O(\sqrt{1/n})+O(q^{2-s})+O(\frac{\iota(q)^2}{n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}}-O(\iota(q)^2\sqrt{\frac{q}{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2\\
\geq&2\gamma_k \underline{\lambda}_c \mathbb{E}_{\beta_{k-1}}\mathbb{E}((\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*-R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*))(\tilde{g}^{-1}(\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*)-x_k^T\beta_0)|\beta_{k-1})\\
&-\gamma_k(O(\sqrt{1/n})+O(q^{2-s})+O(\frac{\iota(q)^2}{n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}}-O(\iota(q)^2\sqrt{\frac{q}{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2
\end{aligned}
$$

where $\tilde{R}_q^{\beta_{k-1}}(x_k)' \equiv R_q^{\beta_{k-1}}(x_k)'\mathbb{E}(R_q^{\beta_{k-1}}(x_k)R_q^{\beta_0}(x_k)')$ and $\tilde{g}(x_k^T\beta_0) \equiv R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*$.

The first inequality is coming from

$$
\begin{aligned}
&\mathbb{E}\frac{1}{n}\sum_{i=1}^{n}(L(R_q^{\beta_{k-1}}(x_i)'\hat{\pi}_q)-y_i)(x_i^T\beta_{k-1}-x_i^T\beta_0)\\
=&\mathbb{E}\frac{1}{n}\sum_{i=1}^{n}(L(R_q^{\beta*}(x_i)'\hat{\pi}_q^*)-g(x_k^T\beta_0))(x_i^T\beta_{k-1}-x_i^T\beta_0)\\
&+\mathbb{E}\frac{1}{n}\sum_{i=1}^{n}(L(R_q^{\beta_{k-1}}(x_i)'\hat{\pi}_q)-L(R_q^{\beta*}(x_i)'\hat{\pi}_q^*))(x_i^T\beta_{k-1}-x_i^T\beta_0)\\
&-\mathbb{E}\frac{1}{n}\sum_{i=1}^{n}(y_i-g(x_k^T\beta_0))(x_i^T\beta_{k-1}-x_i^T\beta_0)\\
=&\mathbb{E}_{\beta_{k-1}}\mathbb{E}((L(R_q^{\beta_0}(x_k)'\hat{\pi}_q^*)-g(x_k^T\beta_0))(x_i^T\beta_{k-1}-x_k^T\beta_0)|\beta_{k-1})+(O(\iota(q)q^{-s}\frac{1}{\sqrt{n}})+O(\frac{\iota(q)^2}{n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0\\
&+O(\frac{1}{\sqrt{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2+\mathbb{E}_{\beta_{k-1}}\mathbb{E}((L(R_q^{\beta_{k-1}}(x_i)'\hat{\pi}_q)-L(R_q^{\beta_0}(x_k)'\hat{\pi}_q^*))(x_i^T\beta_{k-1}-x_k^T\beta_0)|\beta_{k-1})\\
&+O(\frac{1}{\sqrt{n}})(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}}\\
=&\mathbb{E}_{\beta_{k-1}}\mathbb{E}((L(R_q^{\beta_{k-1}}(x_k)'\hat{\pi}_q)-g(x_k^T\beta_0))(x_i^T\beta_{k-1}-x_k^T\beta_0)|\beta_{k-1})\\
&+(O(\iota(q)q^{-s}\frac{1}{\sqrt{n}})+O(\frac{\iota(q)^2}{n})+O(\frac{1}{\sqrt{n}}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}}\\
&+O(\frac{1}{\sqrt{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2
\end{aligned}
$$

where $\hat{\pi}_q^*$ is the value of $\hat{\pi}_q$ when $\beta_{k-1}=\beta_0$ in equation A.2. The proof is similar to the bound on (5) in the addendum of Hirano et al. (2003).

then,

$$\mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' O(\frac{1}{\sqrt{n}})|\beta_{k-1}) = \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(L(R_q^{\beta_{k-1}}(x_k)'\hat{\pi}_q) - g(x_k^T\beta_0))R_q^{\beta_{k-1}}(x_k)|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})$$

$$= \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)'(\tilde{\pi}_q - \tilde{\pi}_q^*)|\beta_{k-1}) + \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k) O(q^{-s})|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})$$

$$+ \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k)(R_q^{\beta_{k-1}}(x_k) - R_q^{\beta_0}(x_k)\tilde{\pi}_q^*)|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})$$

$$= \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(y_i - g(x_i^T\beta_0)))|\beta_{k-1})$$

$$+ \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(g(x_i^T\beta_0) - R_q^{\beta_0}(x_i)\tilde{\pi}_q^*))|\beta_{k-1})$$

$$+ \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}$$

$$* (\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)((R_q^{\beta_0}(x_i) - R_q^{\beta_{k-1}}(x_i)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k))\tilde{\pi}_q^*))|\beta_{k-1})$$

$$+ \{\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}$$

$$* (\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(R_q^{\beta_{k-1}}(x_i)'(\mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k) - R_q^{\beta_{k-1}}(x_i)')\tilde{\pi}_q^*))|\beta_{k-1})$$

$$+ \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k)(R_q^{\beta_{k-1}}(x_k) - R_q^{\beta_0}(x_k)\tilde{\pi}_q^*)))|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})\}$$

$$+ \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i) O(q^{-s}))|\beta_{k-1})$$

$$+ \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k) O(q^{-s})|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})$$

By requiring $s \geq 4.5$ and we consider $q = n^d$, $d < 1/5$ and $d > \frac{1}{2(s-2)}$the bound become

$$O(\frac{1}{\sqrt{n}}) + O(\iota(q)^2 \frac{1}{\sqrt{n}})||\beta_{k-1} - \beta_0||$$

see Appendix B for more information.

$O(\sqrt{1/n})$ is invariant to k if $\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2$ is convergent for k and n sufficient large. We will address this issue later.

The last inequality comes from approximate continuous function $\tilde{g}^{-1}(\tilde{R}_q^{\beta_{k-1}}(x_k))$ by A.4. $f(x_k^T\beta^{k-1}) \equiv \mathbb{E}((\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^* - R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*))(\tilde{g}^{-1}(\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*) - x_k^T\beta_0)|\beta_{k-1})$. Denote $x_k^T\beta_{k-1}$

as z, we can rewrite $\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^* - R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*$ as $\mathbb{E}(R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*|z) - R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*$, so $f(.) \geq 0$ with equality if and only if $\beta_{k-1} = \beta_0$. $f'(x_k^T\beta_0) = 0$ and $f''(x_k^T\beta_0) = \mathbb{E}(\tilde{g}^{-1})'(\tilde{R}_q^{\beta_0}(x_k))(\frac{\partial \tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*}{\partial(x_k^T\beta_{k-1})}|_{\beta^{k-1}=\beta_0})^2$ 0 since $\tilde{g}(.)$ is increasing.

$$\frac{\partial \tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*}{\partial(x_k^T\beta_{k-1})}|_{\beta^{k-1}=\beta_0} = \frac{\partial R_q^{\beta_0}(x_k)'}{\partial(x_k^T\beta_0)}\tilde{\pi}_q + R_q^{\beta_0}(x_k)\mathbb{E}(\frac{\partial R_q^{\beta_0}(x_k)}{\partial(x_k^T\beta_0)}R_q^{\beta_0}(x_k))\tilde{\pi}_q$$

We know that $\mathbb{E}R_q^{\beta_0}(x_k)\mathbb{E}(\frac{\partial R_q^{\beta_0}(x_k)}{\partial(x_k^T\beta_0)}R_q^{\beta_0}(x_k))\tilde{\pi}_q = 0$ and $R_q^{\beta_0}(x_k)\mathbb{E}(\frac{\partial R_q^{\beta_0}(x_k)}{\partial(x_k^T\beta_0)}R_q^{\beta_0}(x_k))\tilde{\pi}_q$ is continuons in $x_k^T\beta_0$ and $(\tilde{g}^{-1})'(\tilde{R}_q^{\beta_0}(x_k)) = 1/(g'(x_k^T\beta_0) + O(q^{-s}))$, so $f''(x_k^T\beta_0) > 0$. then, by 2 we have

$$\begin{aligned}
&\mathbb{E}(2\gamma_k\frac{1}{n}\sum_{i=1}^{n}(\beta_{k-1}-\beta_0)^T C_k\nabla\hat{\zeta}(\beta_{k-1};(x_i,g(x_i^T\beta_0)))))\\
\geq&2\gamma_k\underline{\lambda}_c\underline{\lambda}_{f2}\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2\\
&-\gamma_k(\sqrt{1/n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}} - \gamma_k O(\iota(q)^2\frac{1}{\sqrt{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2
\end{aligned}$$

where λ_{f2} is the smallest eigenvalue of $\mathbb{E}(\tilde{g}^{-1})'(\tilde{R}_q^{\beta_0}(x_k))(\frac{\partial \tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*}{\partial(x_k^T\beta_{k-1})}|_{\beta^{k-1}=\beta_0})^2 x_k^T x_k$.

for the third term,

$$\begin{aligned}
&\gamma_k^2\frac{1}{n}\sum_{i=1}^{n}\mathbb{E}||C_k\nabla\hat{\zeta}(\beta_{k-1};(x_i,g(x_i^T\beta_0)))||^2\\
\leq&4\gamma_k^2\overline{\lambda}_c^2\sigma_x^2
\end{aligned}$$

Then,

$$\begin{aligned}
\mathbb{E}||\beta_k-\beta_0||^2 \leq& (1-2\gamma_k\underline{\lambda}_c\underline{\lambda}_f + \gamma_k O(\iota(q)^2\frac{1}{\sqrt{n}})\mathbb{E}||\beta_{k-1}-\beta_0||^2\\
&+\gamma_k(O(\sqrt{1/n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1}-\beta_0||^2)^{\frac{1}{2}} + 4\gamma_k^2\overline{\lambda}_c^2\sigma_x^2
\end{aligned}$$

then, if n is sufficiently large, $n \geq n_1$,

$$\begin{aligned}\mathbb{E}||\beta_k - \beta_0||^2 \leq & (1 - 2\gamma_k \underline{\lambda}_c \underline{\lambda}_{f2}) \mathbb{E}||\beta_{k-1} - \beta_0||^2 \\ & + \gamma_k (O(\sqrt{1/n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2)^{\frac{1}{2}} + 4\gamma_k^2 \overline{\lambda}_c^2 \sigma_x^2 \\ \leq & \frac{1}{1 + 2\gamma_k \underline{\lambda}_c \underline{\lambda}_{f2}} \mathbb{E}||\beta_{k-1} - \beta_0||^2 \\ & + \gamma_k (O(\sqrt{1/n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2)^{\frac{1}{2}} + 4\gamma_k^2 \overline{\lambda}_c^2 \sigma_x^2\end{aligned}$$

Here we can treat $(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2)^{\frac{1}{2}} \leq \mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2 + 1$. Then we can see from the bound for $\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2$ of each iteration that $\mathbb{E}_{\beta_{K(n)-1}}||\beta_{K(n)-1} - \beta_0||^2$ is convergent for $K(n) = n^{\frac{1}{\gamma}}$ and n sufficient large even if $O(\sqrt{1/n})$ is variant to k. So we can choose the supremum of $O(\sqrt{1/n})$ among each iteration. then, assume $\gamma_0 = 0$, there exists a constant C_1 such that $O(\sqrt{1/n}) \leq C_1 n^{\frac{1}{2}}$

$$\mathbb{E}||\beta_k - \beta_0||^2 \leq \frac{1}{1 + 2\gamma_k \underline{\lambda}_c \underline{\lambda}_{f2}} \mathbb{E}||\beta_{k-1} - \beta_0||^2 + \gamma_k C_1 n^{\frac{1}{2}} (\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2)^{\frac{1}{2}} + 4\gamma_k^2 \overline{\lambda}_c^2 \sigma_x^2$$

Since $\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2$ converges, by guess $\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2 \leq C_2 k^{-\gamma}$ we can solve the inequality easily, we are done if the guessing is right in the aggregate inequality. By setting $K(n) = n^{\frac{1}{\gamma}}$ and corollary 2.1 in Toulis and Airoldi (2017) with $a_k = (C_1\sqrt{C_2} + 4\overline{\lambda}_c^2 \sigma_x^2)\gamma_k^2$ and $b_k = 2\gamma_k \underline{\lambda}_c \underline{\lambda}_{f2}$, By setting $n^{\frac{1}{2\gamma}} \leq K(n) \leq n^{\frac{1}{\gamma}}$,using sieve SGD group algorithm 2 we get

$$\begin{aligned}\mathbb{E}||\tilde{\beta}_{K(n)} - \beta_0||^2 \leq & \frac{2(C_1\sqrt{C_2} + 4\overline{\lambda}_c^2 \sigma_x^2)(1 + 2\gamma_1 \underline{\lambda}_c \underline{\lambda}_{f2})}{2\gamma_1 \underline{\lambda}_c \underline{\lambda}_{f2}} (K(n))^{-\gamma} \\ & + exp(-log(1 + 2\gamma_1 \underline{\lambda}_c \underline{\lambda}_{f2})\phi(K(n)))[||\tilde{\beta}_0 - \beta_0|| + (1 + 2\gamma_1 \underline{\lambda}_c \underline{\lambda}_{f2})^{n_0} A]\end{aligned}$$

with n sufficiently large, where $A = (C_1\sqrt{C_2} + 4\overline{\lambda}_c^2 \sigma_x^2) \sum_i \gamma_i^2 < \infty$,$\phi(K(n)) = K(n)^{1-\gamma}$ if $\gamma < 1$ and $\phi(K(n)) = log(K(n))$ if $\gamma = 1$. n_0 is some constant. We can choose C large enough so that $\frac{2(C_1\sqrt{C_2} + 4\overline{\lambda}_c^2 \sigma_x^2)(1 + 2\gamma_1 \underline{\lambda}_c \underline{\lambda}_{f2})}{2\gamma_1 \underline{\lambda}_c \underline{\lambda}_{f2}} + ||\tilde{\beta}_0 - \beta_0|| + (1 + 2\gamma_1 \underline{\lambda}_c \underline{\lambda}_{f2})^{n_0} A \leq C_2$, then $\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2 \leq C_2 k^{-\gamma}$. □

Theorem 3. *Under assumptions 3.1-3.4 and 3.6-3.10, assume $\gamma_0 = 0$. By setting $K(n) = n$ and $\gamma \in (0.5, 1)$,using sieve SGD average algorithm 3 we get*

$$\sqrt{n}(\bar{\beta}_K - \beta_0) \to N(0, \Sigma_2^{-1}\Sigma_1\Sigma_2^{-1})$$

where $\Sigma_1 = \mathbb{E}g(x_k^T\beta_0)(1 - g(x_k^T\beta_0))((\mathbb{E}x_kx_k^T)^{-\frac{1}{2}}x_k + x_k^T\beta_0 l_{\beta_0})((\mathbb{E}x_kx_k^T)^{-\frac{1}{2}}x_k + x_k^T\beta_0 l_{\beta_0})^T$ *and* $\Sigma_2 = \mathbb{E}g'(x_k^T\beta_0)(I + l_{\beta_0}(\beta_0)')(\mathbb{E}x_kx_k^T)^{-\frac{1}{2}}x_kx_k^T$. $l_{\beta_0} = [1/l_1, 1/l_2, ...1/l_p]$, *and* l_i *is the* i*th element of* $(\mathbb{E}x_kx_k^T)^{\frac{1}{2}}\beta_0$.

Proof. W.L.O.G, we set $\mathbb{E}x_kx_k^T = I_p$ and then we calculate the variance without this assumption by using $(\mathbb{E}x_kx_k^T)^{-\frac{1}{2}}x_k$ and $(\mathbb{E}x_kx_k^T)^{\frac{1}{2}}(\bar{\beta}_K - \beta_0)$ to replace x_k and $(\bar{\beta}_K - \beta_0)$ respectively.

First, we write equation 4.5 as $\frac{1}{n}\sum_{i=1}^n \nabla\tilde{\zeta}_{k-1}(\tilde{\beta}_{k-1}; (x_i, y_i)) = \frac{1}{\gamma_k}(\tilde{\beta}_{k-1} - \tilde{\beta}_k)$. By Theorem 2, Taylor expansion on $\frac{1}{n}\sum_{i=1}^n \nabla\tilde{\zeta}_{k-1}(\tilde{\beta}_{k-1}; (x_i, y_i))$ we get $\frac{1}{n}\sum_{i=1}^n \nabla\tilde{\zeta}_{k-1}(\tilde{\beta}_{k-1}; (x_i, y_i)) = \frac{1}{n}\sum_{i=1}^n \nabla\tilde{\zeta}_{k-1}(\beta_0; (x_i, y_i)) + \frac{1}{n}\sum_{i=1}^n \frac{\partial\nabla\tilde{\zeta}_{k-1}(\beta_0;(x_i,y_i))}{\partial\beta}(\tilde{\beta}_{k-1} - \beta_0)$. We know that $\frac{1}{n}\sum_{i=1}^n \nabla\tilde{\zeta}_{k-1}(\beta_0; (x_i, y_i)) - \frac{1}{n}\sum_{i=1}^n \nabla\zeta(\beta_0; (x_i, y_i)) - \frac{1}{n}\sum_i x_i^T\beta_0 l_{\beta_0}(y_i - g(x_i^T\beta_0))$ is negeligible from the similar argument in theorem 2, then if we prove $\frac{1}{n}\sum_{k=1}^n \frac{1}{\gamma_k}(\tilde{\beta}_{k-1} - \tilde{\beta}_k)$ is negligible $o(1/\sqrt{n})$ and

$$\frac{1}{n}\sum_{i=1}^n \frac{\partial\nabla\tilde{\zeta}_{k-1}(\beta_0; (x_i, y_i))}{\partial\beta} \xrightarrow{p} (\frac{1}{n}\sum_{i=1}^n \frac{\partial\nabla\zeta(\beta_0; (x_i, y_i))}{\partial\beta} + \lim_{q\to\infty} \mathbb{E}x_kR_q^{\beta_0}(x_k)'\mathbb{E}(R_q^{\beta_0}(x_k)g'(x_k^T\beta_0)x_k^T))$$

is negligible $o(1/\sqrt{n})$. then $\frac{1}{n}\sum_{k=1}^n(\tilde{\beta}_k - \beta_0)$ behaves like

$$\begin{aligned}(\frac{1}{n}\sum_{i=1}^n \frac{\partial\nabla\zeta(\beta_0; (x_i, y_i))}{\partial\beta} + \lim_{q\to\infty} \mathbb{E}x_kR_q^{\beta_0}(x_k)'\mathbb{E}(R_q^{\beta_0}(x_k)g'(x_k^T\beta_0)x_k^T))^{-1} \\ *(\frac{1}{n}\sum_{i=1}^n \nabla\zeta(\beta_0; (x_i, y_i)) + \frac{1}{n}\sum_i x_i^T\beta_0 l_{\beta_0}(y_i - g(x_i^T\beta_0))) \\ \to N(0, \Sigma_{22}^{-1}\Sigma_{11}(\Sigma_{22}^{-1})^T)\end{aligned}$$

where $\Sigma_{11} = \mathbb{E}g(x_k^T\beta_0)(1 - g(x_k^T\beta_0))(x_k + x_k^T\beta_0 l_{\beta_0}^t)(x_k + x_k^T\beta_0 l_{\beta_0}^t)^T$ and $\Sigma_{22} = \mathbb{E}g'(x_k^T\beta_0)(I +$

$l^t_{\beta_0}(\beta_0)')x_k x_k^T$ and $l^t_{\beta_0} = [1/\beta_0^{(1)}, 1/\beta_0^{(2)}, , , 1/\beta_0^{(p)}]'$.

$$\begin{aligned}\frac{1}{n}\sum_{k=1}^{n}\frac{1}{\gamma_k}(\tilde{\beta}_{k-1}-\tilde{\beta}_k) &\le \frac{1}{n}(-\frac{1}{\gamma_n}(\tilde{\beta}_n-\beta_0)+\sum_{k=1}^{n-1}|(\frac{1}{\gamma_k}-\frac{1}{\gamma_{k-1}})(\tilde{\beta}_k-\beta_0)|+\frac{1}{\gamma_1}(\tilde{\beta}_0-\beta_0))\\ &\le \frac{1}{n}(-\frac{1}{\gamma_n}(\tilde{\beta}_n-\beta_0)+C\sum_{k=1}^{n-1}\frac{1}{\sqrt{k}}+\frac{1}{\gamma_1}(\tilde{\beta}_0-\beta_0))\\ &= o(1/\sqrt{n})\end{aligned}$$

This means $\frac{1}{n}\sum_{k=1}^{n}\frac{1}{\gamma_k}(\tilde{\beta}_{k-1}-\tilde{\beta}_k)$ is negligible.

For Σ_1

$$\begin{aligned}&\lim_{n\to\infty}(\frac{1}{n}\sum_{i=1}^{n}\nabla\zeta(\beta_0;(x_i,y_i))+\frac{1}{n}\sum_i x_i^T\beta_0 l_{\beta_0}(y_i-g(x_i^T\beta_0)))\\ =&\mathbb{E}g(x_k^T\beta_0)(1-g(x_k^T\beta_0))(x_k+x_k^T\beta_0 l_{\beta_0})(x_k+x_k^T\beta_0 l_{\beta_0})^T\end{aligned}$$

For the second term in Σ_2, if we use the similar argument in theorem 2, we know that the second term is negligible.

$$\lim_{q\to\infty}\mathbb{E}x_k R_q^{\beta_0}(x_k)'\mathbb{E}(R_q^{\beta_0}(x_k)g'(x_k^T\beta_0)x_k^T)=\mathbb{E}g'(x_k^T\beta_0)x_k^T\beta_0 l_{\beta_0}x_k^T=\mathbb{E}g'(x_k^T\beta_0)l_{\beta_0}(\beta_0)'x_k x_k^T$$

since $(\mathbb{E}x_k R_q^{\beta_0}(x_k)')R_q^{\beta_0}(x_k)=x_k^T\beta_0 l_{\beta_0}$ by getting fitted value of x_k regressing on $R_q^{\beta_0}(x_k)$.

At last we drop the independent assumption $\mathbb{E}x_k x_k^T = I_p$.Then $N(0,\Sigma_{22}^{-1}\Sigma_{11}(\Sigma_{22}^{-1})^T)$ becomes $N(0,\Sigma_2^{-1}\Sigma_1(\Sigma_2^{-1})^T)$. where $\Sigma_1=\mathbb{E}g(x_k^T\beta_0)(1-g(x_k^T\beta_0))((\mathbb{E}x_k x_k^T)^{-\frac{1}{2}}x_k+x_k^T\beta_0 l_{\beta_0})((\mathbb{E}x_k x_k^T)^{-\frac{1}{2}}x_k+x_k^T\beta_0 l_{\beta_0})^T$ and $\Sigma_2=\mathbb{E}g'(x_k^T\beta_0)(I+l_{\beta_0}(\beta_0)')(\mathbb{E}x_k x_k^T)^{-\frac{1}{2}}x_k x_k^T$. $l_{\beta_0}=[1/l_1,1/l_2,...1/l_p]$, and l_i is the ith element of $(\mathbb{E}x_k x_k^T)^{\frac{1}{2}}\beta_0$.

□

Theorem 4. *Under assumption 3.1-3.4 and 3.6-3.12, using sieve SGD group algorithm 2 and* $\gamma_0 = 0$ *and by setting* $n^{\frac{1}{2\gamma}} \leq K(n) \leq n^{\frac{1}{\gamma}}$ *with* $pK(n)^{-\gamma} \to 0$*,we get*

$$\mathbb{E}||\tilde{\beta}_{K(n)} - \beta_0||^2 \leq \frac{2(C_3\sqrt{C_4}C_5 + 4\overline{\lambda}_c^2\sigma_x^2)(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2}}pK(n)^{-\gamma}$$
$$+ exp(-log(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})\phi(K(n)))[||\beta_0 - \beta_0|| + (1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})^{n_0}A]$$

with n *sufficiently large, where* $A = (C_3\sqrt{C}_4C_5 + 4\overline{\lambda}_c^2 p\sigma_x^2)\sum_i \gamma_i^2 = O(p)$ *and* $\phi(K(n)) = (K(n))^{1-\gamma}$ *if* $1 - \gamma > 0$ *and* $\phi(K(n)) = log(K(n))$ *if* $1 - \gamma = 0$. $\gamma \in (0.5, 1]$. n_0 *is some constant.*

Proof. with assumption 3.11, we only have two changes here. The first one is

$$\mathbb{E}(2\gamma_k\frac{1}{n}\sum_{i=1}^{n}(\beta_{k-1} - \beta_0)^T C_k\nabla\hat{\zeta}(\beta_{k-1}; (x_i, y_i)))$$
$$=2\gamma_k\underline{\lambda}_c\mathbb{E}\frac{1}{n}\sum_{i=1}^{n}(L(R_q^{\beta_{k-1}}(x_i)'\hat{\pi}_q) - y_i)(x_i^T\beta_{k-1} - x_i^T\beta_0)$$
$$\geq 2\gamma_k\underline{\lambda}_c\mathbb{E}_{\beta_{k-1}}\mathbb{E}((\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^* - R_q^{\beta_0}(x_k)'\tilde{\pi}_q^*))(\tilde{g}^{-1}(\tilde{R}_q^{\beta_{k-1}}(x_k)'\tilde{\pi}_q^*) - x_k^T\beta_0)|\beta_{k-1})$$
$$- \gamma_k(O(\sqrt{p/n}) + O(\sqrt{p}q^{2-s}) + O(\frac{\sqrt{p}\iota(q)^2}{n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2)^{\frac{1}{2}} - O(\iota(q)^2\sqrt{\frac{q}{n}})\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2$$

The second one is

$$\gamma_k^2\frac{1}{n}\sum_{i=1}^{n}\mathbb{E}||C_k\nabla\hat{\zeta}(\beta_{k-1}; (x_i, g(x_i^T\beta_0)))||^2$$
$$\leq 4p\gamma_k^2\overline{\lambda}_c^2\sigma_x^2$$

then, if n is sufficiently large, $n \geq n_1$,

$$\mathbb{E}||\beta_k - \beta_0||^2 \leq (1 - 2\gamma_k\underline{\lambda}_c\underline{\lambda}_{f2})\mathbb{E}||\beta_{k-1} - \beta_0||^2$$
$$+ \gamma_k(O(\sqrt{p/n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2)^{\frac{1}{2}} + 4p\gamma_k^2\overline{\lambda}_c^2\sigma_x^2$$
$$\leq \frac{1}{1 + 2\gamma_k\underline{\lambda}_c\underline{\lambda}_{f2}}\mathbb{E}||\beta_{k-1} - \beta_0||^2$$
$$+ \gamma_k(O(\sqrt{p/n}))(\mathbb{E}_{\beta_{k-1}}||\beta_{k-1} - \beta_0||^2)^{\frac{1}{2}} + 4p\gamma_k^2\overline{\lambda}_c^2\sigma_x^2$$

By corollary 2.1 in Toulis and Airoldi (2017) and setting $n^{\frac{1}{2\gamma}} \leq K(n) \leq n^{\frac{1}{\gamma}}$, we get

$$\mathbb{E}||\beta_{K(n)} - \beta_0||^2 \leq \frac{2(C_3\sqrt{C_4}C_5 + 4\overline{\lambda}_c^2\sigma_x^2)(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})}{2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2}} pK(n)^{-\gamma}$$
$$+ exp(-log(1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})\phi(K(n)))[||\tilde{\beta}_0 - \beta_0|| + (1 + 2\gamma_1\underline{\lambda}_c\underline{\lambda}_{f2})^{n_0}A]$$

with n sufficiently large, where $A = (C_3\sqrt{C_4}C_5 + 4\overline{\lambda}_c^2 p\sigma_x^2)\sum_i \gamma_i^2 = O(p)$ and $\phi(K(n)) = (K(n))^{1-\gamma}$if $1 - \gamma > 0$ and $\phi(K(n)) = log(K(n))$ if $1 - \gamma = 0$. $\gamma \in (0.5, 1]$. n_0 is some constant. □

Theorem 5. *Under assumption 3.1-3.4 and 3.6-3.13, by setting $K(n) = n$ and choosing $\gamma \in (0.5, 1)$ and $\frac{p^2}{n^{2\gamma-1}} \to 0 \to 0$,using sieve SGD average algorithm 3, assuming $\gamma_0 = 0$ and x_k are independent across each regressor, for any $\varsigma \in \mathbb{R}^p$ with $||\varsigma|| = 1$ we get $||\bar{\beta}_K - \beta_0|| = o_p(\sqrt{\frac{p}{n}})$, and*

$$\sqrt{n}\frac{\varsigma'(\bar{\beta}_K - \beta_0)}{(\varsigma'\Sigma_2^{-1}\Sigma_1\Sigma_2^{-1}\varsigma)^{\frac{1}{2}}} \to N(0,1)$$

where $\Sigma_1 = \mathbb{E}g(x_k^T\beta_0)(1 - g(x_k^T\beta_0))((\mathbb{E}x_kx_k^T)^{-\frac{1}{2}}x_k + x_k^T\beta_0 l_{\beta_0})((\mathbb{E}x_kx_k^T)^{-\frac{1}{2}}x_k + x_k^T\beta_0 l_{\beta_0})^T$ and $\Sigma_2 = \mathbb{E}g'(x_k^T\beta_0)(I + l_{\beta_0}(\beta_0)')(\mathbb{E}x_kx_k^T)^{-\frac{1}{2}}x_kx_k^T$. $l_{\beta_0} = [1/l_1, 1/l_2, ...1/l_p]$, and l_i is the ith element of $(\mathbb{E}x_kx_k^T)^{\frac{1}{2}}\beta_0$.

Proof. There are two differences compared to the proof when p is fixed. The first it the following:

$$\begin{aligned}
\frac{1}{n}\sum_{k=1}^{n}\frac{1}{\gamma_k}\varsigma'(\tilde{\beta}_{k-1} - \tilde{\beta}_k) &\leq \frac{1}{n}(-\frac{1}{\gamma_n}\varsigma'(\tilde{\beta}_n - \beta_0) + \sum_{k=1}^{n-1}|(\frac{1}{\gamma_k} - \frac{1}{\gamma_{k-1}})\varsigma'(\tilde{\beta}_k - \beta_0)| + \frac{1}{\gamma_1}\varsigma'(\tilde{\beta}_0 - \beta_0)) \\
&< \frac{1}{n}(-\frac{1}{\gamma_n}(\tilde{\beta}_n - \beta_0) + \sum_{k=1}^{n-1}|(\frac{1}{\gamma_k} - \frac{1}{\gamma_{k-1}}||\varsigma'||||\tilde{\beta}_k - \beta_0|| + \frac{1}{\gamma_1}\varsigma'(\tilde{\beta}_0 - \beta_0)) \\
&< \frac{1}{n}(-\frac{1}{\gamma_n}(\tilde{\beta}_n - \beta_0) + \sum_{k=1}^{n-1}|(k - (k-1))|C\sqrt{\frac{p}{k}} + \frac{1}{\gamma_1}\varsigma'(\tilde{\beta}_0 - \beta_0)) \\
&= o(\sqrt{\frac{p}{n}})
\end{aligned}$$

this means $\frac{1}{n}\sum_{k=1}^{n}\frac{1}{\gamma_k}(\tilde{\beta}_{k-1} - \tilde{\beta}_k)$ is negligible.The second difference is the following:

The second-order term of Taylor expansion of $\nabla\tilde{\zeta}_{k-1}(\beta_0; (x_i, y_i))$ is $\frac{\partial^2\nabla\tilde{\zeta}_{k-1}(\tilde{\beta}_k^*; (x_i,y_i))}{\partial\beta^2}$, where $\tilde{\beta}_k^* = \psi\tilde{\beta}_k + (1-\psi)\beta_0$ and $\psi \in [0,1]$. $\frac{\partial^2\nabla\tilde{\zeta}_{k-1}(\tilde{\beta}_k^*; (x_i,y_i))}{\partial\beta^2}$ is bounded since $\tilde{\beta}_K = \beta_0 + o(1)$ and Σ_{22} has bounded derivatives. Then the second-order term of Taylor expansion of $\frac{1}{n^2}\sum_{k=1}^{n}\sum_{i=1}^{n}\varsigma'\nabla\tilde{\zeta}_{k-1}(\beta_0; (x_i, y_i))$ is bounded by $C\frac{1}{n}\sum_{k=1}^{n}||\mathbb{E}\varsigma' x_k||\frac{p}{k^\gamma} \leq C\frac{1}{n}\sum_{k=1}^{n}\frac{p^{\frac{3}{2}}}{k^\gamma}$, which is $o(\sqrt{\frac{p}{n}})$ if $\frac{p^2}{n^{2\gamma-1}} \to 0$.

then $\frac{1}{n}\sum_{k=1}^{n}(\tilde{\beta}_k - \beta_0)$ behaves like

$$(\frac{1}{n}\sum_{i=1}^{n}\frac{\partial\nabla\zeta(\beta_0;(x_i,y_i))}{\partial\beta} + \lim_{q\to\infty}\mathbb{E}x_k R_q^{\beta_0}(x_k)'\mathbb{E}(R_q^{\beta_0}(x_k)g'(x_k^T\beta_0)x_k^T))^{-1}$$
$$*(\frac{1}{n}\sum_{i=1}^{n}\nabla\zeta(\beta_0;(x_i,y_i)) + \frac{1}{n}\sum_i x_i^T\beta_0 l_{\beta_0}(y_i - g(x_i^T\beta_0)))$$

then for any $\varsigma \in \mathbb{R}^p$ we get $||\beta_K - \beta_0|| = o_p(\sqrt{\frac{p}{n}})$, and

$$\sqrt{n}\frac{\varsigma'(\beta_K - \beta_0)}{(\varsigma'\Sigma_2^{-1}\Sigma_1\Sigma_2^{-1}\varsigma)^{\frac{1}{2}}} \to N(0,1)$$

where $\Sigma_1 = \mathbb{E}g(x_k^T\beta_0)(1-g(x_k^T\beta_0))((\mathbb{E}x_k x_k^T)^{-\frac{1}{2}}x_k + x_k^T\beta_0 l_{\beta_0})((\mathbb{E}x_k x_k^T)^{-\frac{1}{2}}x_k + x_k^T\beta_0 l_{\beta_0})^T$ and $\Sigma_2 = \mathbb{E}g'(x_k^T\beta_0)(I + l_{\beta_0}(\beta_0)')(\mathbb{E}x_k x_k^T)^{-\frac{1}{2}}x_k x_k^T$. $l_{\beta_0} = [1/l_1, 1/l_2, ...1/l_p]$, and l_i is the ith element of $(\mathbb{E}x_k x_k^T)^{\frac{1}{2}}\beta_0$.

□

B. Appendix B

$$\mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' O(\frac{1}{\sqrt{n}})|\beta_{k-1}) = \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(L(R_q^{\beta_{k-1}}(x_k)'\hat{\pi}_q) - g(x_k^T\beta_0))R_q^{\beta_{k-1}}(x_k)|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})$$

$$= \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)'(\tilde{\pi}_q - \tilde{\pi}_q)|\beta_{k-1}) + \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k) O(q^{-s})|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})$$

$$+ \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k)(R_q^{\beta_{k-1}}(x_k) - R_q^{\beta_0}(x_k)\tilde{\pi}_q)|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})$$

$$= \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(y_i - g(x_i^T\beta_0)))|\beta_{k-1}) \tag{B.1}$$

$$+ \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(g(x_i^T\beta_0) - R_q^{\beta_0}(x_i)\tilde{\pi}_q))|\beta_{k-1}) \tag{B.2}$$

$$+ \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}$$

$$* (\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)((R_q^{\beta_0}(x_i) - R_q^{\beta_{k-1}}(x_i)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k))\tilde{\pi}_q))|\beta_{k-1}) \tag{B.3}$$

$$+ \{\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}$$

$$* (\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(R_q^{\beta_{k-1}}(x_i)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k) - R_q^{\beta_{k-1}}(x_i)')\tilde{\pi}_q))|\beta_{k-1})$$

$$+ \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)'(\mathbb{E}(R_q^{\beta_{k-1}}(x_k)(R_q^{\beta_{k-1}}(x_k) - R_q^{\beta_0}(x_k))\tilde{\pi}_q)|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})\} \tag{B.4}$$

$$+ \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i) O(q^{-s}))|\beta_{k-1}) \tag{B.5}$$

$$+ \mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)' \mathbb{E}(R_q^{\beta_{k-1}}(x_k) O(q^{-s})|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1}) \tag{B.6}$$

For B.1

$$
\begin{aligned}
&\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(y_i - g(x_i^T\beta_0)))|\beta_{k-1}) \\
&\leq \mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(y_i - g(x_i^T\beta_0)))|\beta_{k-1}) + O(\iota(q)^3 q^{-s}\frac{\sqrt{q}}{\sqrt{n}}) \\
&\leq \frac{1}{n}\sum_i x_i^T\beta_{k-1} l_{\beta_{k-1}}(y_i - g(x_i^T\beta_0)) + O(\iota(q)^3 q^{-s}\frac{\sqrt{q}}{\sqrt{n}}) \\
&\leq O(\frac{1}{\sqrt{n}}) + O(\iota(q)^3 q^{-s}\frac{\sqrt{q}}{\sqrt{n}})
\end{aligned}
$$

where we use $||\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1} - I_q|| = O_p(\iota(q)\sqrt{\frac{q}{n}})$ by Newey (1997). The next-to-last equation needs independence assumption of x_i across each regressor. Even without the independence assumption we still can get the last equation.

For B.2

$$
\begin{aligned}
&\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(g(x_i^T\beta_0) - R_q^{\beta_0}(x_i)\tilde{\pi}_q))|\beta_{k-1}) \\
=&O(\iota(q)^2 q^{-s})(1 + O(\iota(q)\sqrt{\frac{q}{n}}))
\end{aligned}
$$

For B.3

$$
\begin{aligned}
&\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1} \\
&* (\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)((R_q^{\beta_0}(x_i) - R_q^{\beta_{k-1}}(x_i)'\mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k))\tilde{\pi}_q))|\beta_{k-1}) \\
=&O(\iota(q)^2\frac{1}{\sqrt{n}})(1 + O(\iota(q)\sqrt{\frac{q}{n}}))||\beta_{k-1} - \beta_0||
\end{aligned}
$$

Here $\mathbb{E}R_q^{\beta_{k-1}}(x_i)((R_q^{\beta_0}(x_i) - R_q^{\beta_{k-1}}(x_i)'\mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k))\tilde{\pi}_q) = 0$ because by regressing $R_q^{\beta_0}(x_i))'\tilde{\pi}_q$ on $R_q^{\beta_0}(x_i)$ we get the residual $((R_q^{\beta_0}(x_i) - R_q^{\beta_{k-1}}(x_i)'\mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k))\tilde{\pi}_q)$, which is orthogonal to $R_q^{\beta_{k-1}}(x_i)$.

For B.4

$$\begin{aligned}
&\{\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1} \\
&*(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)(R_q^{\beta_{k-1}}(x_i)'(\mathbb{E}(R_q^{\beta_{k-1}}(x_k)' R_q^{\beta_0}(x_k) - R_q^{\beta_{k-1}}(x_i)'))\tilde{\pi}_q))|\beta_{k-1}) \\
&+\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)'\mathbb{E}(R_q^{\beta_{k-1}}(x_k)(R_q^{\beta_{k-1}}(x_k) - R_q^{\beta_0}(x_k)\tilde{\pi}_q)|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1})\}|\beta_{k-1}) \\
=&0
\end{aligned}$$

For B.5

$$\begin{aligned}
&\mathbb{E}((x_k^T R_q^{\beta_{k-1}}(x_k)')(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)' R_q^{\beta_{k-1}}(x_i))^{-1}(\frac{1}{n}\sum_i R_q^{\beta_{k-1}}(x_i)O(q^{-s}))|\beta_{k-1}) \\
=&O(\iota(q)^2 q^{-s})(1 + O(\iota(q)\sqrt{\frac{q}{n}}))
\end{aligned}$$

For B.6

$$\begin{aligned}
&\mathbb{E}(x_k^T R_q^{\beta_{k-1}}(x_k)'\mathbb{E}(R_q^{\beta_{k-1}}(x_k)O(q^{-s})|\beta_{k-1}, \hat{\pi}_q)|\beta_{k-1}) \\
=&O(\iota(q)^2 q^{-s})
\end{aligned}$$

Adding the bound together, we get

$$\begin{aligned}
&O(\frac{1}{\sqrt{n}}) + O(\iota(q)^3 q^{-s}\frac{\sqrt{q}}{\sqrt{n}}) + O(\iota(q)^2 q^{-s})(1 + O(\iota(q)\sqrt{\frac{q}{n}})) \\
&+O(\iota(q)^2\frac{1}{\sqrt{n}})(1 + O(\iota(q)\sqrt{\frac{q}{n}}))||\beta_{k-1} - \beta_0|| + 0 \\
&+O(\iota(q)^2 q^{-s})(1 + O(\iota(q)\sqrt{\frac{q}{n}})) + O(\iota(q)^2 q^{-s}) \\
\leq&O(\iota(q)^2 q^{-s}) + O(\frac{1}{\sqrt{n}}) + O(\iota(q)^2\frac{\sqrt{q}}{n}) + O(\iota(q)^2\frac{1}{\sqrt{n}})||\beta_{k-1} - \beta_0||
\end{aligned}$$

By requiring $s \geq 4.5$ and we consider $q = n^d$ and $d < 1/5$ the bound become

$$O(\frac{1}{\sqrt{n}}) + O(\iota(q)^2\frac{1}{\sqrt{n}})||\beta_{k-1} - \beta_0||$$