Nonlinear Panel Data Models Based on Sieve Estimation

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In this talk, we have a brief review some useful results about sieve estimation for non- and semi-parametric panel data models. We then show how the sieve method is used in two nonlinear panel data models. The first is a semi-parametric single-index panel data model where the time series regressors are stationary and cross-sectional dependence is allowed. The second model is a partially linear panel data model where the regressors are linearly integrated.

By using a Hermite polynomial approximation method to each of the unknown link functions involved, closed-form estimators for the index parameter vector and unknown functions are proposed. Under a general spatial mixing dependence structure, which naturally takes into account both serial correlation and cross-sectional dependence, asymptotically normal estimators are established for the case where both N and T diverge to infinity jointly. The estimation theory is finally evaluated by simulated and real data examples.

The talk is based on the 2 working papers, appended here.
Partially Linear Panel Data Models with Cross-Sectional Dependence and Nonstationarity

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Partially Linear Panel Data Models with Cross–Sectional Dependence and Nonstationarity

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Abstract

In this paper, we consider a partially linear panel data model with cross–sectional
dependence and non–stationarity. Meanwhile, we allow fixed effects to be correlated
with the regressors to capture unobservable heterogeneity. Under a general spatial
error dependence structure, we then establish some consistent closed–form estimates
for both the unknown parameters and the unknown function for the case where \( N \)
and \( T \) go jointly to infinity. Rates of convergence and asymptotic normality results
are established for the proposed estimators. Both the finite–sample performance
and the empirical applications show that the proposed estimation method works
well when the cross–sectional dependence exists in the data set.

Keywords: Asymptotic theory; closed–form estimate; orthogonal series method; partially linear
panel data model.

JEL classification: C13, C14, C23, C51

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1 Introduction

Nonlinear and nonstationary time series models have received considerable attention during the last thirty years. Nonlinearity and nonstationarity are dominant characteristics of many economic and financial data sets, for example, exchange rates and inflation rates. Many datasets, such as aggregate disposable income and consumption, are found to be integrated processes. With the development of asymptotic theory in recent years, researchers are able to construct econometric models using original data rather than a differenced version, while in the past one might need to use a differenced version to satisfy stationarity requirements. In a recent publication, Gao and Phillips (2013) consider a partially linear time series data model of the form:

\[ Y_t = AX_t + g(V_t) + e_t, \]
\[ X_t = H(V_t) + U_t, \quad t = 1, \ldots, T, \]

which extend existing partially linear models given in Härdle et al. (2000) and allow the integrated time series \( V_t = V_{t-1} + \epsilon_t \) to be the driving force of the data set. Moreover, a semiparametric estimation method is provided in Gao and Phillips (2013) to recover the parameter \( A \) of interest and unknown function \( g(\cdot) \) based on a kernel estimation technique. As a result, the relationship of some vital integrated economic and financial variables, like the impact of interest rates on private consumption, may be depicted directly in modelling. While the literature on nonstationary time series grows, very few nonlinear and nonstationary panel data models have been provided to accommodate nonstationarity.

Recent studies by Robinson (2012) and Chen et al. (2012b) involve the time trend to capture nonstationarity and extend the time series model in Gao and Phillips (2013) to the panel data setting:

\[ y_{it} = x_{it}'\beta_0 + g(t/T) + \omega_i + e_{it}, \]
\[ x_{it} = \phi(t/T) + \lambda_i + v_{it}, \]

for \( i = 1, \ldots, N \) and \( t = 1, \ldots, T \), where the relations \( \sum_{i=1}^{N} \omega_i = 0 \) and \( \sum_{i=1}^{N} \lambda_i = 0 \) are stipulated for the purpose of identification. Recently, Bai et al. (2009) and Kapetanios et al. (2011) extend the linear panel data models considered by Bai (2009) and Pesaran (2006) by allowing the factors (also often known as macro shocks in some basic economic concepts) to follow nonstationary time series processes. Meanwhile, Bai and Carrion-I-Silvestre (2009) study the problem of unit root testing in the presence of multiple structural changes and common dynamic factors, and Bai and Ng (2010) extend their earlier work in Bai and Ng (2004) to
investigate the panel data unit root test with cross-sectional dependence.

Following the literature, it is necessary to establish some relevant asymptotic theory for panel data models when unit root processes are involved in the system. In this paper, one of our aims is to provide some new asymptotic theory for panel data models with the presence of integrated processes when \( N \) and \( T \) diverge jointly. These results can easily be employed to further studies on the panel data models. Due to the use of Hermite orthogonal functions, some results are also very useful to sieve-estimate-based studies. Moreover, taking into account the correlation among individuals has become an important topic when modelling panel data sets. One popular method is using a factor structure to mimic the strong correlation between individuals. Since Pesaran (2006) and Bai (2009), many extensions have been made. Another popular approach is measuring the correlation between individuals by geographical locations with a spatial error structure on the cross-section dimension. Many papers have adopted this approach, see, for example Pesaran and Tosetti (2011), Chen et al. (2012b) and Chen et al. (2012a). In this paper, the latter one is employed.

Based on the literature given above, we consider a partially linear panel data model with integrated time series. Specifically, the model is formulated as follows:

\[
y_{it} = x_{it}'\beta_0 + g(u_{it}) + \omega_i + e_{it}, \\
x_{it} = \phi(u_{it}) + \lambda_i + v_{it}, \\
u_{it} = u_{i,t-1} + \eta_{it}, \quad i = 1, \ldots, N \text{ and } t = 1, \ldots, T, 
\]

(1.1)

where \( x_{it} \) and \( u_{it} \) are observable explanatory variables, \( u_{it} \) follows an integrated process on time dimension, \( g(w) \) is an unknown function in \( L^2(\mathbb{R}) \), \( \phi(w) = (\phi_1(w), \ldots, \phi_d(w))' \) is a vector of unknown integrable functions. Note that, under the current set-up, \( \phi_j(w) \) for \( j = 1, \ldots, d \) and \( g(w) \) will not be constants and all the constant terms are absorbed in fixed effects \( \omega_i \) and \( \lambda_i \). Since we shall use the within transformation later on, all the fixed effects simply disappear from the system. Thereby, we do not require extra conditions on identifiability, which is similar to (3.2.5) on page 32 of Hsiao (2003). Accordingly, the fixed effects can capture unobservable heterogeneity and be correlated with the regressors. More detailed discussions and examples can be seen in Hsiao (2003). Note also that model (1.1) extends some time series models discussed in Härdle et al. (2000) to the panel data case.

One interesting finding is that for model (1.1), the within transformation does not affect the asymptotic theory to be established. This is different from those for panel data models with stationarity on the time dimension. A short explanation is that, for a stationary panel data set \( \mu_{it} \), \( \frac{1}{T} \sum_{t=1}^{T} g(\mu_{it}) = E[g(\mu_{it})] + O_P \left( \frac{1}{\sqrt{T}} \right) \) under regular restrictions. However, for an integrated panel data regressor \( u_{it} \), we have \( \frac{1}{T} \sum_{t=1}^{T} g(u_{it}) = O_P \left( \frac{1}{\sqrt{T}} \right) \) due to the integrability.
of $g(\cdot)$. As a result, within transformation helps to remove the fixed effects without any cost. The detailed discussion will be seen in the rest of this paper.

Another crucial finding is that the joint divergence of $(N, T) \to (\infty, \infty)$ makes the asymptotic theory drastically different from that of the integrated time series case. As stated in Lemma B.5 below, when $(N, T) \to (\infty, \infty)$ jointly

$$L_{NT} - E[L_{NT}] \to_p 0, \quad \text{where } L_{NT} = \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} g(u_{it}).$$

(1.2)

However, if $\mu$ is a unit root process, we have $l_T = \frac{1}{\rho T} \sum_{t=1}^{T} g(\mu_t) \to D L_B(1, 0) \int g(x)dx$ given some conditions on $g(x)$, where $\rho > 0$ is a constant, $B$ stands for a standard Brownian motion generated by $\mu_t$ and $L_B(1, 0)$ is the local process of $B$ that measures the sojourning time of $B$ at zero over the period $[0, 1]$. To obtain the limit of $L_{NT}$, one naive thought would be that for each $i$,

$$\frac{1}{\sqrt{T}} \sum_{t=1}^{T} g(u_{it}) \to D \rho \cdot L_{B_i}(1, 0) \int g(x)dx,$$

(1.3)

as $T \to \infty$, where $B_i$ is a standard Brownian motion generated by $u_{it}$, then by the law of large numbers, $L_{NT} \to D \rho E[L_B(1, 0)] \int g(x)dx$. Although $E[L_B(1, 0)]$ does exist, this derivation contradicts the joint divergence of $N$ and $T$, because (1.3) might not be true for $i = N$ when $(N, T) \to (\infty, \infty)$ jointly. On the other hand, the establishment of (1.2) does not need an expansion of probability space, while usually researchers have to do so in order to obtain a convergence in probability in the nonstationary context. See, for example, Park and Phillips (2001). This is extremely convenient for the establishment of our asymptotic theory.

In summary, we make the following contributions in this paper.

1. We extend the partially linear models given in Gao and Phillips (2013) and Chen et al. (2012b) and allow for the presence of nonstationarity processes on the time dimension.

2. The difference in asymptotic theory with the presence of nonstationarity for time series as $T \to \infty$ and for panel data as $(N, T) \to (\infty, \infty)$ jointly is phenomenal.

3. The sieve estimation method employed produces some simple closed-form estimators and the results in some new asymptotic properties for the estimators.

4. The results obtained under panel data setting are stronger than those achieved in the integrated time series setting due to the new limit of the type (1.2) that avoids the expansion of the original probability space in order to obtain a limit in probability.

The structure of this paper is as follows. Section 2 proposes the sieve–based estimation method and introduces the necessary assumptions for the establishment of an asymptotic theory.
in Section 3. Section 4 discusses some related extensions and limitations of our model. Section 5 evaluates the finite-sample performance by Monte Carlo simulation and a case study on Balassa–Samuelson model. Section 6 concludes. The proofs of the main results are given in Appendices A and B, while some proofs of the secondary results are provided in Appendix C of a supplementary document of this paper.

Throughout the paper, 1_d = (1, \cdots, 1)' is a d \times 1 vector; M_P = I_n - P(P'P)^{-1}P' denotes the projection matrix generated by full column matrix P_n\times m; \| \cdot \| denotes Euclidean norm; \rightarrow_P and \rightarrow_D stand for converging in probability and in distribution, respectively; \lambda_{\min}(A) and \lambda_{\max}(A) denote minimum and maximum eigenvalues of a n \times n matrix A, respectively; \lfloor a \rfloor \leq a means the largest integer part of a; \int g(w)dw represents \int_{-\infty}^{\infty} g(w)dw and similar notation applies to multiple integration.

2 Estimation method and assumptions

Let \{H_i(w), i = 0, 1, 2, \ldots\} be the Hermite polynomial system orthogonal with respect to \exp(-w^2), which is complete in the Hilbert space L^2(\mathbb{R}, \exp(-w^2)). The orthogonality of the system reads \int H_i(w)H_j(w)\exp(-w^2)dw = \sqrt{\pi}2^i!\delta_{ij}, where \delta_{ij} is the Kronecker delta. Correspondingly, the so–called Hermite functions are defined by \mathcal{H}_i(w) = \frac{1}{\sqrt{\pi}\sqrt{2}^i}H_i(w)\exp(-w^2/2) for i \geq 0, which is an orthonormal basis in the Hilbert space L^2(\mathbb{R}). Thus, the unknown function g(w) \in L^2(\mathbb{R}) can be expanded into the following orthogonal series:

\[
g(w) = \sum_{j=0}^{\infty} c_j \mathcal{H}_j(w) = Z_k(w)'C + \gamma_k(w), \quad c_j = \int g(w)\mathcal{H}_j(w)dw, \quad (2.1)
\]

where Z_k(w) = (\mathcal{H}_0(w), \ldots, \mathcal{H}_{k-1}(w))', C = (c_0, \ldots, c_{k-1})' and \gamma_k(w) = \sum_{j=k}^{\infty} c_j \mathcal{H}_j(w).

Additionally, in order to remove fixed effects from the system, we take the within transformation and write the model as

\[
y_{it} - \bar{y}_i = (x_{it} - \bar{x}_i)'\beta_0 + (Z_k(u_{it}) - \bar{Z}_{k,i})'C + \gamma_k(u_{it}) - \bar{\gamma}_{k,i} + e_{it} - \bar{e}_i,
\]

where \bar{y}_i = \frac{1}{T} \sum_{t=1}^{T} y_{it}, \bar{x}_i = \frac{1}{T} \sum_{t=1}^{T} x_{it}, \bar{Z}_{k,i} = \frac{1}{T} \sum_{t=1}^{T} Z_k(u_{it}), \bar{\gamma}_{k,i} = \frac{1}{T} \sum_{t=1}^{T} \gamma_k(u_{it}) and \bar{e}_i = \frac{1}{T} \sum_{t=1}^{T} e_{it}. For simplicity, let \hat{y}_i = y_{it} - \bar{y}_i and \hat{x}_i, \hat{Z}_{k,i}, \hat{\gamma}_{k,i}, \hat{e}_i be defined in the same fashion for 1 \leq i \leq N and 1 \leq t \leq T. Then we rewrite (1.1) in matrix notation as

\[
Y = X\beta_0 + ZC + \gamma + E, \quad (2.2)
\]
where

\[ Y_{NT \times 1} = (\hat{y}_{11}, \ldots, \hat{y}_{IT}, \ldots, \hat{y}_{N1}, \ldots, \hat{y}_{NT})', \]

\[ X_{NT \times d} = (\hat{x}_{11}, \ldots, \hat{x}_{IT}, \ldots, \hat{x}_{N1}, \ldots, \hat{x}_{NT})', \]

\[ Z_{NT \times k} = (\hat{\gamma}_k(u_{11}), \ldots, \hat{\gamma}_k(u_{IT}), \ldots, \hat{\gamma}_k(u_{N1}), \ldots, \hat{\gamma}_k(u_{NT}))', \]

\[ \gamma_{NT \times 1} = (\hat{\gamma}_k(u_{11}), \ldots, \hat{\gamma}_k(u_{IT}), \ldots, \hat{\gamma}_k(u_{N1}), \ldots, \hat{\gamma}_k(u_{NT}))', \]

\[ \xi_{NT \times 1} = (\hat{\epsilon}_{11}, \ldots, \hat{\epsilon}_{IT}, \ldots, \hat{\epsilon}_{N1}, \ldots, \hat{\epsilon}_{NT})'. \]

To simplify the proof and facilitate the discussion, we project out \( Z \) and \( X \beta_0 \) respectively and focus on the next two equations in turn in the following sections:

\[ M_2 Y = M_2 X \beta_0 + M_2 \gamma + M_2 \xi \quad \text{and} \quad M_X Y = M_X Z C + M_X \gamma + M_X \xi, \]

where \( M_2 = I_{NT} - Z (Z' Z)^{-1} Z' \) and \( M_X = I_{NT} - X (X' X)^{-1} X' \), giving the within OLS estimators of \( \beta_0 \) and \( C \):

\[ \hat{\beta} = (X' M_2 X)^{-1} X' M_2 Y \quad \text{and} \quad \hat{C} = (Z' M_X Z)^{-1} Z' M_X Y. \quad (2.3) \]

The following assumptions are necessary for the theoretical development and their detailed discussion and some examples are provided in Appendix A.

**Assumption 1**

1. Let \( \{\varepsilon_{ij}, i \in \mathbb{Z}^+, j \in \mathbb{Z}\} \) be a sequence of independent and identically distributed (i.i.d.) random variables across \( i \) and \( j \). Moreover, \( E[\varepsilon_{11}] = 0, E[\varepsilon_{11}^2] = 1 \) and \( E[|\varepsilon_{11}|^p] < \infty \) for some \( p > 4 \). In addition, \( \varepsilon_{11} \) has distribution absolutely continuous with respect to Lebesgue measure and characteristic function \( c(r) \) satisfying \( \int |rc(r)|dr < \infty \).

2. For \( 1 \leq i \leq N \) and \( 1 \leq t \leq T \), let \( u_{it} = u_{i,t-1} + \eta_{it} \) with \( u_{i0} = O_P(1) \), where \( \eta_{it} \) is a linear process of the form: \( \eta_{it} = \sum_{j=0}^{\infty} \rho_j \varepsilon_{i,t-j} \), where \( \{\rho_j\} \) is a scalar sequence, \( \rho_0 = 1 \), \( \sum_{j=0}^{\infty} j |\rho_j| < \infty \) and \( \rho := \sum_{j=0}^{\infty} \rho_j \neq 0 \).

3. (a) Let \( v_t = (v_{1t}, \ldots, v_{Nt})' \) be strictly stationary and \( \alpha \)-mixing. Also, \( E[v_{it}] = 0 \) and \( E[v_{it} v_{jt}'] = \Sigma_v \) for all \( 1 \leq i \leq N \) and \( 1 \leq t \leq T \), where \( \Sigma_v \) is a positive definite matrix. Let \( \alpha_{ij}(|t - s|) \) denote the \( \alpha \)-mixing coefficient between \( v_{it} \) and \( v_{js} \), such that for some \( \delta > 0 \), \( \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{s=1}^{T} \sum_{t=1}^{T} (\alpha_{ij}(|t - s|))^{\delta/(4+\delta)} = O(NT) \), and for the same \( \delta \), \( E[|v_{it}|^{4+\delta}] < \infty \) uniformly in \( i \) and \( t \).

(b) Let \( e_t = (e_{1t}, \ldots, e_{Nt})' \) be a martingale difference sequence. More precisely, with
filtration $F_{N,t} = \sigma(e_{1}, \ldots, e_{t}; v_{1}, \ldots, v_{t+1})$, suppose that $E[e_{t}|F_{N,t-1}] = 0$ almost surely (a.s.) and $E[e_{t}e'_{t}|F_{N,t-1}] = (\sigma_{e}(i,j))_{NN} =: \Sigma_{e}$ a.s., where $\Sigma_{e}$ is a constant matrix independent of $t$, $\sum_{i=1}^{N} \sum_{j=1}^{N} |\sigma_{e}(i,j)| = O(N)$ and $\sigma_{e}(i,i) = \sigma_{e}^{2}$. Meanwhile, $\sup_{1 \leq i \leq N} \frac{1}{N} \sum_{t=1}^{T} E[e_{it}^{4}|F_{N,t-1}] < \infty$. Let $\Sigma_{v,e} = \lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^{N} \sum_{j=1}^{N} E[v_{it}v'_{jt}]\sigma_{e}(i,j)$ and $\Sigma_{v,e}$ is positive definite.

(c) i. $\sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_{1}=1}^{T} \sum_{t_{2}=1}^{T} \sum_{t_{3}=1}^{T} \sum_{t_{4}=1}^{T} E[v_{it_{1}} \otimes v_{it_{2}} \otimes v_{jt_{3}} \otimes v_{jt_{4}}] = O(NT^{2})$.

ii. $\sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_{1}=1}^{T} \sum_{t_{2}=1}^{T} \sum_{t_{3}=1}^{T} \sum_{t_{4}=1}^{T} E[v'_{it_{1}} e_{it_{2}} v_{jt_{3}} e_{jt_{4}}] = O(NT^{2})$.

4. $\{\varepsilon_{ij}, i \in \mathbb{Z}^{+}, j \in \mathbb{Z}\}$ is independent of $\{(v_{it_{1}}, e_{it_{1}}), 1 \leq i_{1} \leq N, 1 \leq t_{1} \leq T\}$.

Assumption 2

1. There exists an integer $m > 1$, such that $x^{m-s}g^{(s)}(w) \in L^{2}(\mathbb{R})$ for $s = 0, 1, \ldots, m$.

Moreover, for $j = 1, \ldots, d$, $\phi_{j}(w) \in L(\mathbb{R}) \cap L^{2}(\mathbb{R})$.

2. Let $k = \lfloor aT^{\vartheta} \rfloor$ with a constant $a > 0$ and $0 < \vartheta < \frac{1}{4}$. Also, $k/N \to 0$ as $(N, T) \to (\infty, \infty)$.

3 Asymptotic theory

We start from investigating $\hat{\beta}$. It follows from (2.3) that

$$\hat{\beta} - \beta_{0} = (X' M_{2} X)^{-1} X' M_{2} \mathcal{E} + (X' M_{2} X)^{-1} X' M_{2} \gamma. \quad (3.1)$$

Observe that

$$\frac{1}{NT} X' M_{2} X = \frac{1}{NT} X' X - \frac{1}{NT} X' \mathcal{Z} \left( \frac{1}{N \sqrt{T}} \mathcal{Z}' \mathcal{Z} \right)^{-1} \frac{1}{NT} \mathcal{Z} X, \quad (3.2)$$

$$\frac{1}{NT} X' M_{2} \mathcal{E} = \frac{1}{NT} X' \mathcal{E} - \frac{1}{NT} X' \mathcal{Z} \left( \frac{1}{N \sqrt{T}} \mathcal{Z}' \mathcal{Z} \right)^{-1} \frac{1}{NT} \mathcal{Z}' \mathcal{E}, \quad (3.3)$$

$$\frac{1}{NT} X' M_{2} \gamma = \frac{1}{NT} X' \gamma - \frac{1}{NT} X' \mathcal{Z} \left( \frac{1}{N \sqrt{T}} \mathcal{Z}' \mathcal{Z} \right)^{-1} \frac{1}{NT} \mathcal{Z}' \gamma. \quad (3.4)$$

The consistency of $\hat{\beta} - \beta_{0}$ follows from Lemmas B.4-B.5 listed in Appendix B immediately and the normality can be achieved by further investigation on (3.2)-(3.4). We now state the first theorem of this paper.

Theorem 3.1. Under Assumptions 1 and 2, as $(N, T) \to (\infty, \infty)$ jointly, $\hat{\beta}$ is consistent. If, in addition, $N/k^{m-1} \to 0$, then $\sqrt{NT} (\hat{\beta} - \beta_{0}) \to_{D} N(0, \Sigma_{\varepsilon}^{-1} \Sigma_{v,e} \Sigma_{\varepsilon}^{-1})$, where $\Sigma_{v,e}$ is defined in Assumption 1.3.b.

Note that $\Sigma_{v,e}$ is the same as that in Theorem 1 of Chen et al. (2012b) and the discussion on the existence of $\Sigma_{v,e}$ can be found therein. Since our model is an extension of Gao and Phillips
(2013) to the panel data case, the rate of convergence given in Theorem 3.1 matches what Gao and Phillips (2013) obtain for the time series case. On the cross-sectional dimension, the optimal rate of convergence, \(N^{-1/2}\), is also achieved. Thus, replacing the time trend in Chen et al. (2012b) with non-stationary time series processes do not affect the optimal rate of convergence of \(\hat{\beta}\). Some other studies and discussions on panel data models including non-stationary time series (but not directly related to our model) can be seen in Bai et al. (2009) and Kapetanios et al. (2011). The condition \(N/k^{m-1}\) is similar to the one given in Theorem 2 of Newey (1997), Assumption 4.ii of Su and Jin (2012) and Assumption A5 of Chen et al. (2012b). The purpose of this restriction is to remove the truncation residual for us to establish the asymptotic normality. Since nonstationary times series regressors are introduced to our model, the proof of the asymptotic theory involves some new techniques, which are different from those used in the literature.

Before giving a consistent estimator for the asymptotic covariance matrix in Theorem 3.1, we show the consistency of \(\hat{C}\) given in (2.3). Note that

\[
\hat{C} - C = (Z'M_XZ)^{-1} Z'M_X\gamma + (Z'M_XZ)^{-1} Z'M_X\varepsilon.
\]  

(3.5)

In connection with Lemmas B.4–B.5 provided in the Appendix, we have the following lemma.

**Lemma 3.1.** Under Assumptions 1 and 2, as \((N,T) \rightarrow (\infty, \infty)\) jointly

\[
\|\hat{\Sigma} - \Sigma\| = O_P\left(\frac{\sqrt{k}}{\sqrt{N}\sqrt{T}}\right) + O_P\left(k^{-\frac{m-1}{2}}\right).
\]

The proof is given in Appendix B. We now turn to consistent estimation on asymptotic covariance matrix in Theorem 3.1 in order to establish the confidence interval for \(\hat{\beta}\). By (6) of Lemma B.4 below, \(\hat{\Sigma}_e = \frac{1}{NT}X'X \rightarrow_P \Sigma_e\). Thus, we need only to focus on obtaining a consistent estimator for \(\Sigma_{v,e}\). To do so, we have to impose some stronger assumptions, e.g. \(e_{it}\) is independent across \(i\), which is in the same spirit as Corollary 3.1.ii and Theorem 3.3 of Gao and Phillips (2013) and will reduce \(\Sigma_{v,e}\) to \(\sigma_v^2\Sigma_v^{-1}\). Define the estimator of \(\sigma_v^2\) as

\[
\hat{\sigma}_v^2 = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (\hat{Y}_{it} - \hat{X}_{it}'\hat{\beta} - \hat{Z}_{it}' u_{it}) (\hat{C}')^2.
\]  

(3.6)

**Corollary 3.1.** Suppose that Assumptions 1 and 2 hold. (1) As \((N,T) \rightarrow (\infty, \infty)\) jointly, \(\hat{\sigma}_v^2 \rightarrow_P \sigma_v^2\), where \(\hat{\sigma}_v^2\) is denoted by (3.6). (2) Let \(e_{it}\) be independent across \(i\). As \((N,T) \rightarrow (\infty, \infty)\) jointly, \(\hat{\Sigma}_{v,e} \rightarrow_P \Sigma_{v,e}\), where \(\hat{\Sigma}_{v,e} = \hat{\sigma}_v^2\hat{\Sigma}_v^{-1}\) and \(\hat{\Sigma}_v = \frac{1}{NT}X'X\).

The proof of Corollary 3.1 is given in Appendix C of the supplementary document. Moreover, for \(\forall w \in \mathbb{R}\), define the estimator of \(g(w)\) as \(\hat{g}(w) = Z_k(w)'\hat{C}\). After imposing some extra
revisions, the normality of $\hat{g}(w)$ can be achieved.

**Theorem 3.2.** Under Assumptions 1 and 2,

1. $\int (\hat{g}(w) - g(w))^2 dw = O_P \left( \frac{k}{N\sqrt{T}} \right) + O_P \left( k^{-m-1} \right)$.

2. Additionally, let

\[ (1) \sum_{i_1=1}^{N} \sum_{i_2=1}^{N} \sum_{i_3=1}^{N} \sum_{i_4=1}^{N} |E [e_{i_1t}e_{i_2t}e_{i_3t}e_{i_4t} | F_{Nt-1}]| = O_P(N^2) \text{ uniformly in } t, \text{ and} \]

\[ (2) k^2/N \to 0 \text{ and } N^{1/2}T^{1/4}k^{-(m-1)/2} \to 0. \]

Then as $(N, T) \to (\infty, \infty)$ jointly, $\sqrt{N\sigma_k^{-1}(w) \sqrt{T}} (\hat{g}(w) - g(w)) \to_D N(0, 1)$, where $\sigma_k(w) = a_0^{-1}\sigma_z^2\|Z_k(w)\|^2$ and $a_0 = \sqrt{2/(\pi \rho^2)}(1 + o(1))$ with $\rho = \sum_{j=0}^{\infty} \rho_j \neq 0$.

In the first result of Theorem 3.2, we establish a rate of convergence for the integrated mean squared error. For the second result of Theorem 3.2, two stronger restrictions are needed: Condition (1) is in the same spirit of (3.3) and (3.4) in Chen et al. (2012a), wherein all the relevant discussions and examples can be found; Condition (2) on the sharper bound for $k$ is due to the development of (B.15) (see Appendix B for details). It is interesting to see that the cross–sectional dependence of the error terms does not play a role in the asymptotic variance (c.f. $\sigma_k(w) = a_0^{-1}\sigma_z^2\|Z_k(w)\|^2$). A short explanation is that in the derivation of the variance for the term on RHS of equation (B.15), $E[Z_k(w)'Z_k(u_{it})Z_k(u_{jt})'Z_k(w)]]$ will attenuate at rate $t^{-1}$ for $i \neq j$.

Moreover, notice that $\|Z_k(w)\|^2 = O(k)$ uniformly by Lemma B.1. Thus, the rate of convergence for the normality is essentially $\sqrt{k^{-1}N\sqrt{T}}$, which is equivalent to the rate obtained by using kernel estimation method $\sqrt{hN\sqrt{T}}$, where $h$ is the bandwidth parameter. The condition $N^{1/2}T^{1/4}k^{-(m-1)/2}$ is in line with the same spirit of $N/k^{m-1}$ provided in Theorem 3.1. The higher–order smoothness required here is due to the development of (B.15).

Notice based on the convergence that $\frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} \mathcal{H}_0^2(x_{it}) \to_P a_0$ in Lemma B.5 and $\hat{\sigma}_e^2 \to_P \sigma_e^2$ in Corollary 3.1, $\hat{\sigma}_k(w)$, the estimator of $\sigma_k(w)$, is easily obtained and thus the hypothesis test on $\hat{g}(w)$ for $w \in \mathbb{R}$ can be conducted from the second result of Theorem 3.2. In the next section, we provide some related discussion before presenting the finite sample studies using both simulated and real data examples.

**4 Some extensions and discussions**

In the above study, we have completely ruled out the cases where $\phi_j(w)$ for $j = 1, \ldots, d$ and $g(w)$ are non–integrable. The study on (1.1) is fundamental and can provide many basic results
for the cases where \( g(w) \) includes a non–integrable term. For example, let \( g(w) = w + g_1(w) \), where \( g_1(w) \) is an integrable function on \( \mathbb{R} \). In this case, the model becomes

\[
\begin{align*}
y_{it} &= x_{it}' \beta_0 + u_{it} + g_1(u_{it}) + \omega_i + \epsilon_{it}, \\
x_{it} &= \phi(u_{it}) + \lambda_i + v_{it}.
\end{align*}
\]

Then simple transformation shows that we can rewrite (4.1) as

\[
\begin{align*}
y_{1,it} &= x_{it}' \beta_0 + g_1(u_{it}) + \omega_i + \epsilon_{it}, \\
x_{it} &= \phi(u_{it}) + \lambda_i + v_{it},
\end{align*}
\]

where \( y_{1,it} = y_{it} - u_{it} \). Since both \( y_{it} \) and \( u_{it} \) are observable, \( y_{1,it} \) can be treated as given. In this case, model (4.1) is reduced to (1.1).

We now turn to the structure of \( x_{it} \). Consider a simple partially linear model of the form:

\[
\begin{align*}
y_{it} &= x_{it}' \beta_0 + g(u_{it}) + \omega_i + \epsilon_{it}, \\
x_{it} &= u_{it} + \lambda_i + v_{it}.
\end{align*}
\]

After taking first difference, it is easy to obtain that

\[
\begin{align*}
\Delta y_{it} &= (\Delta x_{it})' \beta_0 + g(u_{it}) - g(u_{it-1}) + \Delta \epsilon_{it} \\
&= (\Delta x_{it})' \beta_0 + (Z_k(u_{it}) - Z_k(u_{it-1}))' C + \bar{\epsilon}_{it}
\end{align*}
\]

where \( \bar{\epsilon}_{it} = \gamma_k(u_{it}) - \gamma_k(u_{it-1}) + \Delta \epsilon_{it} \). Notice that (4.4) does not include fixed effects, so it is a simpler version of (1.1). In order to obtain consistent estimators for \( \beta_0 \) and \( C \), we can carry out the similar procedure as the previous sections without using within transformation.

There are also some limitations in this study. Assumption 1.3.b has excluded the case where \( E[\epsilon_{it} v_{it}] \neq 0 \). For example, we cannot allow the error term to have a form like \( \epsilon_{it} = \psi(v_{it}) + \epsilon_{it} \). This is in the same spirit as Assumptions 2 and 4 of Pesaran (2006), Assumption D of Bai (2009) and Assumption A.4 of Chen et al. (2012b). To introduce some endogeneity between \( \epsilon_{it} \) and \( v_{it} \), new techniques similar to those developed by Dong and Gao (2014) may be needed. When \( E[\epsilon_{it} v_{it}] = 0 \), we can allow \( \epsilon_{it} = \psi(v_{it}) \cdot \epsilon_{it} \), where \( \epsilon_{it} \) is independent of \( v_{it} \). In this sense, \( v_{it} \) can partially be the driving force of \( \epsilon_{it} \) by having an impact on its variance. A detailed example is given in the Monte Carlo study below.
5 Numerical Study

This section provides the results of a simple Monte Carlo study and an empirical case study by looking into Balassa–Samuelson model. In the simulation study, the biases and root of mean squared errors (RMSEs) are reported. As we can see, biases are quite small and RMSEs decrease as both $N$ and $T$ increase. The empirical case study suggests that model (1.1) outperforms the traditional panel data model used for investigating Balassa–Samuelson model.

5.1 Monte Carlo simulation

In Monte Carlo study, the data generating process (DGP) is as follows.

$$y_{it} = x_{it}'\beta_0 + (1 + u_{it}^2) \exp(-u_{it}^2) + \omega_i + e_{it},$$

$$x_{it} = ((1 + u_{it} + u_{it}^2) \exp(-u_{it}^2)) \otimes 1_d + \lambda_i + v_{it},$$

$$e_{it} = \gamma_i f_t (1 + f_{t-1}) + v_{it}'\beta_0 \epsilon_{it},$$

where $\beta_0 = (1, 2)'$ and $d = 2$. In this DGP, the error term $e_{it}$ depends on the information from the past, $f_{t-1}$, and the information from the current time period, $v_{it}$.

For each $i$, $u_{i1} \sim \text{i.i.d. } N(0, 1)$ and $u_{it} = u_{i,t-1} + \text{i.i.d. } N(0, 1)$ for $t = 2, \ldots, T$. For the factor loadings, $(\gamma_1, \ldots, \gamma_N)' \sim N(0, \Sigma_{\gamma})$, where the $(i, j)\text{th}$ element of $\Sigma_{\gamma}$ is $0.5^{i-j}$. For the factors, $f_t \sim \text{i.i.d. } N(0, 1)$ for each $t$. The error terms $\epsilon_{it} \sim \text{i.i.d. } N(0, 1)$. For each $t$,

$$(v_{1t}, \ldots, v_{Nt})' = 0.5(v_{1,t-1}, \ldots, v_{N,t-1})' + N(0, \Sigma_{v}),$$

where the $(i, j)\text{th}$ element of $\Sigma_{v}$ is $0.3^{i-j}$. For the fixed effects, $\omega_i \sim N((1 + u_{i1} + u_{i1}^2), 1)$ and $\lambda_i \sim N(1_d, I_d)$, so $w_i$ is certainly correlated with the regressor $x_{it}$.

Based on the above, the cross-sectional dependence comes into the system through both the error terms $e_{it}$ and $v_{it}$. $e_{it}$ certainly satisfies the martingale condition and slightly violates the requirements of Assumption 1.3.b on covariances, but it does not affect the accuracy of the estimators as shown later. In order to make sure that the Assumption 2.2 is satisfied, the truncation parameter is chosen as $k = \lceil 3.3 \cdot T^{1/7} \rceil$. For each replication, we record the bias and squared error as: $\text{bias} = \hat{\beta}_j - \beta_{0j}$ and $\text{se} = (\hat{\beta}_j - \beta_{0j})^2$ for $j = 1, 2$, where $\hat{\beta}_j$ denotes the estimate of $\beta_{0j}$ and $\beta_{0j}$ is the $j\text{th}$ element of $\beta_0$. After 1000 replications, we report the mean of these biases and the root of the mean of these squared errors, which are labeled as Bias and RMSE in Table 1. It is evident that in Table 1 the biases decrease to zero very quick, and the RMSEs decrease as both $N$ and $T$ increase. Though both $N$ and $T$ start from 10, the sample size given by the product of $NT$ is sufficient to obtain accurate estimation for the parameters.
5.2 Empirical study

The Balassa–Samuelson model implies that countries with a relatively low ratio of tradables to nontradables productivity will have a depreciated real exchange rate, which can be evaluated by calculating the gap between a purchasing power parity (PPP)–based U.S. dollar exchange rate and the nominal U.S. dollar exchange rate. The PPP–based exchange rate measures how many goods the domestic currency buys within the country relative to the U.S. as numéraire country, while the nominal U.S. dollar exchange rate measures how many U.S. dollars the domestic currency buys in the foreign exchange market. Specifically, we consider equation (1) of de Boeck and Slok (2006), i.e. (5.1) provided below. A very detailed description can be found therein.

\[
\ln \left( \frac{ppp_{it}}{ne_{it}} \right) = \beta \cdot \ln pgp_{it} + \gamma_i + \varepsilon_{it}, \tag{5.1}
\]

where \( ppp_{it} \) = PPP–based U.S. dollar exchange rate at \((i, t)\), \( ne_{it} \) = nominal U.S. dollar exchange rate at \((i, t)\), \( pgp_{it} \) = PPP GDP per capita at \((i, t)\).

However, running OLS regression on the above linear model by using the data set provided below gives a \( R^2 \) smaller than 15%. A modified form of the linear model (5.1) is given by

\[
\ln ppp_{it} = \beta \cdot \ln pgp_{it} + \alpha \cdot \ln ne_{it} + \gamma_i + \varepsilon_{it}. \tag{5.2}
\]

This section proposes a partially linear model of the form:

\[
\ln ppp_{it} = \beta \cdot \ln pgp_{it} + g(ne_{it}) + \gamma_i + \varepsilon_{it}, \tag{5.3}
\]

where \( g(\cdot) \) is an unknown function. We therefore compare models (5.1)–(5.3), referred to as LM1, LM2 and PM, respectively, for brevity.

For this study, the yearly data is collected from Alan Heston, Robert Summers and Bet-

<table>
<thead>
<tr>
<th></th>
<th>( \beta_1 )</th>
<th>( \beta_2 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( T ) ( \backslash ) ( N )</td>
<td>10 0.005 0.003 0.001</td>
<td>0.017 0.002 0.004</td>
</tr>
<tr>
<td></td>
<td>40 -0.005 0.004 0.000</td>
<td>-0.010 0.002 -0.002</td>
</tr>
<tr>
<td></td>
<td>80 -0.003 0.001 -0.001</td>
<td>0.004 0.000 0.000</td>
</tr>
<tr>
<td></td>
<td>10 0.334 0.162 0.115</td>
<td>0.404 0.194 0.141</td>
</tr>
<tr>
<td></td>
<td>40 0.150 0.077 0.056</td>
<td>0.199 0.099 0.069</td>
</tr>
<tr>
<td></td>
<td>80 0.107 0.052 0.037</td>
<td>0.136 0.069 0.049</td>
</tr>
</tbody>
</table>

Table 1: Bias and RMSE
tina Aten, Penn World Table Version 7.1, Center for International Comparisons of Production, Income and Prices at the University of Pennsylvania, July 2012. We choose the time period 1950–2010 and focus on OECD countries only. Since not all OECD countries have the data recorded for the whole period, we simply remove those countries that have the missing data to ensure a balanced panel data set. Notice that most of the countries left have reasonable exchange rates during this period, which vary between 0 to 5. However, some countries’ exchange rates have dramatic changes and have a clear signal on structural break, for example the exchange rate of Iceland is always less than 1 before 1975 and increases dramatically to 122 after that. Thus, we also remove some countries, whose exchange rates act as outliers to rest of the countries. It then leaves us with 17 countries, which are Australia, Austria, Belgium, Canada, Finland, France, Ireland, Israel, Italy, Luxembourg, Mexico, Netherlands, New Zealand, Portugal, Spain, Switzerland, Turkey and United Kingdom.

Before any further investigation, we examine if the nominal U.S. dollar exchange rates of all these countries have unit roots. To do so, we carry on the Augmented Dickey–Fuller (ADF) test for the time series \(\{ne_{it}, \ldots, ne_{iT}\}\) for \(i = 1, \ldots, 17\) and report the \(p\)–values of the ADF tests below. According to the report, except for Switzerland all other 16 countries have unit root in nominal U.S. dollar exchange rates based on 5% significant level, so we remove Switzerland from the data set.

<table>
<thead>
<tr>
<th>p–value</th>
<th>Australia</th>
<th>Austria</th>
<th>Belgium</th>
<th>Canada</th>
<th>Finland</th>
<th>France</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0.61</td>
<td>0.29</td>
<td>0.29</td>
<td>0.53</td>
<td>0.70</td>
<td>0.60</td>
</tr>
<tr>
<td></td>
<td>Ireland</td>
<td>Israel</td>
<td>Italy</td>
<td>Luxembourg</td>
<td>Netherlands</td>
<td>NZ</td>
</tr>
<tr>
<td>p–value</td>
<td>0.68</td>
<td>0.97</td>
<td>0.77</td>
<td>0.29</td>
<td>0.11</td>
<td>0.68</td>
</tr>
<tr>
<td></td>
<td>Portugal</td>
<td>Spain</td>
<td>Switzerland</td>
<td>Turkey</td>
<td>UK</td>
<td></td>
</tr>
<tr>
<td>p–value</td>
<td>0.85</td>
<td>0.78</td>
<td>0.02</td>
<td>0.99</td>
<td>0.83</td>
<td></td>
</tr>
</tbody>
</table>

Table 2: P-value of Augmented Dickey-Fuller Test

For the data set used in this study, \(ppp_{it}\) mainly varies between 2.5 and 5.5; \(pgp_{it}\) roughly varies between 5 and 11; except Israel, \(ne_{it}\) fluctuates between 0 and 2. Due to the limitation of space, we use Canada as an example to illustrate how these three variables change across time.

To get \(\text{In–MSE}\), all the data collected above \((i = 1, \ldots, 16\) and \(t = 1, \ldots, 61)\) are used to run the regression in order to get \(\hat{\beta}_\text{In}\) and \(\hat{C}_\text{In}\). Then \(\text{In–MSE}\) is given by

\[
\text{In–MSE} = \frac{1}{16 \times 61} \sum_{i=1}^{16} \left( \sum_{t=1}^{61} (\tilde{Y}_{it} - \tilde{X}_{it}\hat{\beta}_\text{In} - \tilde{Z}_k(u_{it})\hat{C}_\text{In})^2 \right),
\]

where \(\tilde{Y}_{it} = Y_{it} - \frac{1}{61} \sum_{t=1}^{61} Y_{it}; \tilde{X}_{it}\) and \(\tilde{Z}_k(u_{it})\) are defined in the same fashion.
To get Out–MSE, only part of data collected above \((i = 1, \ldots, 16, t = 1, \ldots, \bar{T} \text{ and } \bar{T} = 56, \ldots, 60)\) are used to estimate \(\hat{\beta}_{\text{Out},\bar{T}}\) and \(\hat{C}_{\text{Out},\bar{T}}\) in order to forecast \(\hat{Y}_{i,\bar{T}+1}\). Then Out–MSE is obtained as

\[
\text{Out–MSE} = \frac{1}{16 \times (61 - 56)} \sum_{i=1}^{16} \sum_{T=56}^{60} (\hat{Y}_{i,T+1} - \hat{X}_{i,T+1}' \hat{\beta}_{\text{Out},\bar{T}} - \hat{Z}_k(u_{i,T+1})' \hat{C}_{\text{Out},\bar{T}})^2,
\]

where \(\hat{Y}_{i,T+1} = Y_{i,T+1} - \frac{1}{T+1} \sum_{t=1}^{T+1} Y_{it} \); \(\hat{X}_{it}\) and \(\hat{Z}_k(u_{it})\) are defined in the same fashion.

Even though we treat \(g(w)\) as an unknown function and have less information for (5.3),
Table 4 shows that the estimates from partially linear model by taking into account the non-stationarity of nominal U.S. dollar exchange rates outperform the estimates from linear models.

<table>
<thead>
<tr>
<th>PM</th>
<th>LM1</th>
<th>LM2</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\hat{\beta} = 0.075$</td>
<td>$\hat{\beta} = -0.484$</td>
<td>$\hat{\beta} = 0.106$</td>
</tr>
<tr>
<td>(0.004)</td>
<td>(0.044)</td>
<td>(0.004)</td>
</tr>
</tbody>
</table>

Table 3: Estimation results for models (5.1)–(5.3)

<table>
<thead>
<tr>
<th>PM ($k = 6$)</th>
<th>LM1</th>
<th>LM2</th>
</tr>
</thead>
<tbody>
<tr>
<td>In–MSE</td>
<td>0.01180</td>
<td>2.49943</td>
</tr>
<tr>
<td>Out–MSE</td>
<td>0.01273</td>
<td>5.50020</td>
</tr>
</tbody>
</table>

Table 4: In–MSE and Out–MSE

For the partially linear panel data model (5.3), our comparisons based on the in sample mean squared errors (In–MSE) and rolling out sample mean squared errors (Out–MSE) suggest using $k = 6$ as the truncation parameter. As a comparison, the estimates of within OLS estimates for (5.1) and (5.2) are also reported. We now use the partially linear model as an example to demonstrate how to calculate these two values.

The coefficients of the basis functions are $(7.78, -19.58, 26.81, -22.84, 11.85, -3.01)$, which imply that the estimated unknown function is

$$\hat{g}(w) = 7.78 \mathcal{H}_0(w) - 19.58 \mathcal{H}_1(w) + 26.81 \mathcal{H}_2(w) - 22.84 \mathcal{H}_3(w) + 11.85 \mathcal{H}_4(w) - 3.01 \mathcal{H}_5(w).$$

Moreover, we plot $\hat{g}(w)$ and its confidence interval in Figure 2. Since most of $n_{eit}$’s are between 0 and 2, we only report $\hat{g}(w)$ on the interval $[0, 2]$. The dash–dot line in the mid represents the estimated unknown function, $\hat{g}(w)$, and the two dashed lines represent the 95% confidence interval curves.

Due to the limit of space, we report the estimated PPP–based U.S. dollar exchange rate for Belgium only in Figure 3. The dash–dot line includes the observable values and the solid line includes the estimated values. Figure 3 indicates that including more relevant explanatory variables may be necessary for improving the performance of Balassa–Samuelson model. However, this is beyond the scope of this paper. We will leave this for future research.

6 Conclusions

In this paper, we have established the estimate for a group of partially linear panel data models with non–stationarity and cross–sectional dependence. Spatial error structure analysis
technique has been used to measure the correlation among individuals. An asymptotic theory has been established for the estimators. Particularly, we do not impose any assumptions on the fixed effects, so they can be used to deal with the models with unobservable heterogeneity. More importantly, new findings include the significant difference in asymptotical theory for times series and panel data sets. The finite sample properties are demonstrated through Monte Carlo experiment and a real data example of Balassa–Samuelson Model. The possible extensions and limitations of our model have been discussed in details and they will guide our future research projects.

Appendix A: Discussion of assumptions

Assumption 1: Assumptions 1.1 and 1.2 are standard in the time series literature and imply that the non–stationary time series processes \( \{u_{i1}, \ldots, u_{iT}\} \)’s are i.i.d. across \( i \) (c.f. Assumption 1.i of Phillips and Moon (1999), where the coefficients of \( \varepsilon_{ij} \) are treated as i.i.d. random variables.). Notice that the coefficients \( \rho_j \) in Assumption 1.2 can also be written in a matrix form if \( u_{it} \) is chosen as a vector.

Assumption 1.3.a is in the same spirit as Assumption C of Bai (2009) and Assumption A2 and A4
of Chen et al. (2012b). On the cross–section dimension, it is also similar to the set–up on spatial error structure in Pesaran and Tosetti (2011). Therefore, it certainly allows the cross–sectional dependence of the error terms to come in the model. On the time dimension, it entails that only the stationary case is considered. Specifically, the mixing coefficient $\alpha_{ij}(|t − s|)$ is used to measure the relationship between individuals at different time periods, i.e. the relationship between $v_{it}$ and $v_{js}$. Two examples are given below to demonstrate this assumption is reasonable:

- It can easily be seen that Assumption 1.3.a holds if $v_{it}$ is i.i.d. over $i$ and $t$.
- We now use a factor model structure to show that Assumption 1.3.a is verifiable. Suppose that $v_{it} = \gamma_i f_t + \varepsilon_{it}$, where all variables are scalars and $\varepsilon_{it}$ is i.i.d. sequence over $i$ and $t$ with mean zero. Simple algebra shows that the coefficient $\alpha_{ij}(|t − s|)$ reduces to $\alpha_{ij} \cdot b(|t − s|)$, in which $\alpha_{ij} = E[\gamma_i \gamma_j]$ and $b(|t − s|)$ is the $\alpha$–mixing coefficient of the factor time series $\{f_1, \ldots, f_T\}$. If $f_t$ is a strictly stationary $\alpha$–mixing process and $\gamma_i$ is a functional coefficient which converges to 0 at a certain rate as $i$ increases, Assumption 1.3.a can easily be verified. More details and useful empirical examples can be found under Assumption A2 in Chen et al. (2012b).

Assumption 1.3.b is similar to Assumption 1.3.a, but focuses on the cross–sectional dimension of the error term $e_{it}$. It is the same as Assumption A.4 of Chen et al. (2012b) and allows for weak endogeneity between regressors and error terms through $v_{it}$ and $e_{it}$.

The Assumption 1.3.c is a simpler version of (A.18) in Chen et al. (2012a). For the first equation of Assumption 1.3.c, a very detailed proof and relevant discussion can be found on page 17 of Chen et al. (2012a). The second equation is in line with the spirit of Assumption 3.2.ii of Gao and Phillips (2013) and can be easily verified if $e_{it}$ is independent of $v_{js}$.

Within transformation allows us to relax the identification restrictions (1.3) of Chen et al. (2012b) and (1.2) of Chen et al. (2013), i.e. $\sum_{i=1}^{N} \omega_i = 0$ and $\sum_{i=1}^{N} \lambda_i = 0$. Notice that we do not impose any conditions on $\omega_i$ and $\lambda_i$, so they can be correlated with any variables arbitrarily.

Notice that the results of this paper are not achieved in the richer probability space (c.f. Park and Phillips (2000) and Park and Phillips (2001) for the discussion on the richer probability space) due to that we avoid using the local time process in the development of Lemma B.5. In this sense, the results under the panel data setting are stronger than those achieved in the time series setting.

Assumption 2: Assumption 2.1 (c.f. Dong et al. (2014)) ensures that the approximation of the unknown functions $g(w)$ by an orthogonal expansion can have a fast rate. Assumption 2.2 puts restrictions on the truncated parameter $k$, $N$ and $T$, so that they go to infinity at appropriate rates. The requirement of $k = \lfloor aT^\vartheta \rfloor$ for $0 < \vartheta < \frac{1}{4}$ is consistent with the set–up for time series data (c.f. Dong et al. (2014)) and similar to Assumption A3 of Chen et al. (2012a). The requirement of $k/N \rightarrow 0$ is consistent with the case that sieve estimation is used in panel data literature (c.f. Su and Jin (2012)). These two restrictions further imply that $T^\vartheta/N \rightarrow 0$ for the $\vartheta$ given above. The similar conditions and more discussions under panel data settings can be seen in Su and Jin (2012), Chen et al. (2012b) and Chen et al. (2012a).
Appendix B: Proof of the main results

We first give some necessary lemmas for the proofs of the main results before the proofs of the lemmas are given in Appendix C of the supplementary document.

Lemma B.1. Suppose that \( g(w) \) is differentiable on \( \mathbb{R} \) and \( x^{m-j}g^{(j)}(w) \in L^2(\mathbb{R}) \) for \( j = 0,1,\ldots,m \) and \( m \geq 1 \). For the expansion (2.1), the following results hold:

(1) \( \int w^2 \mathcal{H}^2(w) dw = n + 1/2; \) (2) \( \max_w |\gamma_k(w)| = O(1)k^{(-m-1)/2-1/12}; \) (3) \( \int \gamma^2_k(w) dw = O(1)k^{-m}; \)

(4) \( \int \|Z_k(w)\|dw = O(1)k^{11/12}; \) (5) \( \int \|Z_k(w)\|^2 dw = k; \) (6) \( \|Z_k(w)\|^2 = O(1)k \) uniformly on \( \mathbb{R}; \)

(7) \( \int |\gamma_k(w)| dw = O(1)k^{-m/2+11/12}; \) (8) \( \int \mathcal{H}_n(w) dw = O(1)n^{5/12}; \) (9) \( \int |x|^2 \|Z_k(x)\|^2 dx = O(1)k^2. \)

The proof of Lemma B.1 is exactly the same as that in Lemma A.1 of Dong et al. (2014).

Lemma B.2. Under Assumptions 1 and 2, as \( (N,T) \to (\infty,\infty) \) jointly,

(1) \( \left\| \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_{it}) \right\| = O_P(k^{(-m-1)/2}); \) (2) \( \left\| \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) Z_k(u_{it}) \right\| = O_P(1); \)

(3) \( \left\| \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it} Z_k(u_{it}) \right\| = O_P \left( \sqrt{\frac{k}{N}} \right); \) (4) \( \frac{1}{\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it} \phi(u_{it}) = \Sigma_v + O_P \left( \frac{1}{\sqrt{T}} \right); \)

(5) \( \frac{1}{\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) = O_P \left( \frac{1}{\sqrt{T}} \right); \) (6) \( \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_{it}) \epsilon_{it} = O_P \left( \frac{\sqrt{\rho}}{\sqrt{N}\sqrt{T}} \right); \)

(7) \( \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) \epsilon_{it} = O_P \left( \frac{1}{N\sqrt{T}} \right); \) (8) \( \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) \gamma_k(u_{it}) = O_P \left( \frac{1}{\sqrt{NT}} \right); \)

(9) \( \frac{1}{N\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it} \gamma_k(u_{it}) = O_P \left( \frac{k^{-m/2+5/12}}{\sqrt{NT}} \right). \)

The proof of Lemma B.2 is provided later in Appendix C.

Lemma B.3. For two non–singular symmetric matrices \( A,B \) with same dimensions \( k \times k \), where \( k \) tends to \( \infty \). Suppose that their minimum eigenvalues satisfy that \( \lambda_{\min}(A) > 0 \) and \( \lambda_{\min}(B) > 0 \) uniformly in \( k \). Then \( \|A^{-1} - B^{-1}\|^2 \leq \lambda_{\min}^{-2}(A) \cdot \lambda_{\min}^{-2}(B) \|A - B\|^2. \)

The proof of Lemma B.3 is provided later in Appendix C.

Lemma B.4. Let Assumptions 1 and 2 hold. As \( (N,T) \to (\infty,\infty) \) jointly, (1) \( \left\| \frac{1}{N\sqrt{T}} Z\mathcal{E} \right\| = O_P \left( \frac{\sqrt{\rho}}{\sqrt{N}\sqrt{T}} \right); \) (2) \( \left\| \frac{1}{N\sqrt{T}} X'Z \right\| = O_P(1); \) (3) \( \frac{1}{\sqrt{T}} X'\mathcal{E} = O_P \left( \frac{1}{\sqrt{NT}} \right); \) (4) \( \frac{1}{\sqrt{NT}} X'\gamma = O_P \left( \frac{1}{\sqrt{N\sqrt{T}}} \right); \)

(5) \( \left\| \frac{1}{N\sqrt{T}} Z'\gamma \right\| = O_P(k^{(-m-1)/2}); \) (6) \( \frac{1}{\sqrt{NT}} X'X \to \Sigma_v. \)

The proof of Lemma B.4 is provided later in Appendix C.

Lemma B.5. Suppose that Assumptions 1.1, 1.2 and 2.2 hold. As \( (N,T) \) go to \( (\infty,\infty) \) jointly,

(1) \( \left\| \frac{1}{N\sqrt{T}} Z' - a_0 I_k \right\| \to_P 0, \) where \( a_0 = \sqrt{\frac{2}{\pi k^2}}(1 + o(1)). \)

(2) Suppose further that \( \frac{k^2}{N} \to 0. \) Then \( \left\| \frac{1}{N\sqrt{T}} Z' - a_0 I_k \right\| = O_P(k^{-1/2}). \)

In the above lemma, the first result is of general interest and can be used in sieve estimation for panel data models where nonstationary time series are involved, while the second one establishes the convergence rate with a harsher requirement on \( k \) and \( N \), which will be used in the proof of Theorem 3.2. The proof of Lemma B.5 is provided later in Appendix C.
We are now ready to provide the proofs for the main results of this paper.

**Proof of Theorem 3.1:** By Lemma B.5, we have uniformly in $k$

$$
\lambda_{\min} \left( \frac{1}{N\sqrt{T}} Z'Z \right) = \min_{\|\mu\|=1} \left\{ \mu' a_0 I_k \mu + \mu' \left( \frac{1}{N\sqrt{T}} Z'Z - a_0 I_k \right) \mu \right\}
\geq a_0 - \left\| \frac{1}{N\sqrt{T}} Z'Z - a_0 I_k \right\| \geq \frac{1}{2} a_0 (1 + o_P(1)). \tag{B.1}
$$

Therefore, by Lemma B.3

$$\left\| \left( \frac{1}{N\sqrt{T}} Z'Z \right)^{-1} - \frac{1}{a_0} I_k \right\| \leq \frac{2(1 + o_P(1))}{a_0^2} \left\| \frac{1}{N\sqrt{T}} Z'Z - a_0 I_k \right\| = o_P(1). \tag{B.2}
$$

For consistency, we consider (3.2)–(3.4) respectively below. Start from (3.2).

$$\frac{1}{NT} X'MZ = \frac{1}{NT} X'X - \frac{1}{N\sqrt{T}} X'Z a_0^{-1} I_k \frac{1}{NT} Z'X
+ \frac{1}{N\sqrt{T}} X'Z \left[ a_0^{-1} I_k - \left( \frac{1}{N\sqrt{T}} Z'Z \right)^{-1} \right] \frac{1}{NT} Z'X. \tag{B.3}
$$

Notice that

$$\left\| \frac{1}{N\sqrt{T}} X'Z \left[ a_0^{-1} I_k - \left( \frac{1}{N\sqrt{T}} Z'Z \right)^{-1} \right] \frac{1}{NT} Z'X \right\|
\leq \frac{1}{\sqrt{T}} \left\| \frac{1}{N\sqrt{T}} X'Z \right\|^2 \left\| a_0^{-1} I_k - \left( \frac{1}{N\sqrt{T}} Z'Z \right)^{-1} \right\| = o_P \left( \frac{1}{\sqrt{T}} \right),
$$

where the last line follows from (B.2) and (2) of Lemma B.4. Similarly, by (2) of Lemma B.4,

$$\left\| \frac{1}{N\sqrt{T}} X'Z a_0^{-1} I_k \frac{1}{NT} Z'X \right\| \leq o(1) \left\| \frac{1}{N\sqrt{T}} X'Z \right\| \left\| \frac{1}{NT} Z'X \right\| = O_P \left( \frac{1}{\sqrt{T}} \right).
$$

In connection with (6) of Lemma B.4, we can further write

$$\frac{1}{NT} X'MZ = \frac{1}{NT} X'X + O_P \left( \frac{1}{\sqrt{T}} \right) \rightarrow_p \Sigma_v. \tag{B.4}
$$

For (3.3), write

$$\frac{1}{NT} X'MZ = \frac{1}{NT} X'X - \frac{1}{N\sqrt{T}} X'Z a_0^{-1} I_k \frac{1}{NT} Z'X
+ \frac{1}{N\sqrt{T}} X'Z \left[ a_0^{-1} I_k - \left( \frac{1}{N\sqrt{T}} Z'Z \right)^{-1} \right] \frac{1}{NT} Z'X. \tag{B.5}
$$

Notice that

$$\left\| \frac{1}{N\sqrt{T}} X'Z \left[ a_0^{-1} I_k - \left( \frac{1}{N\sqrt{T}} Z'Z \right)^{-1} \right] \frac{1}{NT} Z'X \right\|$$
\[
\left\| \frac{1}{N^{\alpha}} X'Z \right\| a_0^{-1} I_k - \left( \frac{1}{N^{\alpha}} Z'Z \right)^{-1} \left\| \frac{1}{N^{\alpha}} Z'E \right\| = o_p \left( \frac{\sqrt{k}}{N^{\alpha}/T^3} \right),
\]

where the last line follows from (B.2) and (1)–(2) of Lemma B.4. Similarly, by (1)–(2) of Lemma B.4,

\[
\left\| \frac{1}{N^{\alpha}} X'Z a_0^{-1} I_k \frac{1}{N^{\alpha}} Z'E \right\| \leq O(1) \left\| \frac{1}{N^{\alpha}} X'Z \right\| \left\| \frac{1}{N^{\alpha}} Z'E \right\| = o_p \left( \frac{\sqrt{k}}{N^{\alpha}/T^3} \right).
\]

Then we can further write (B.5) as

\[
\frac{1}{N^{\alpha}} X'MZ\gamma = \frac{1}{N^{\alpha}} X'\gamma + O_p \left( \frac{\sqrt{k}}{N^{\alpha}/T^3} \right) = O_p \left( \frac{1}{\sqrt{k^{m-1}T}} \right),
\]

where the second equality follows from (3) of Lemma B.4 and Assumption 2.2.

For (3.4), write

\[
\frac{1}{N^{\alpha}} X'MZ\gamma = \frac{1}{N^{\alpha}} X'\gamma - \frac{1}{N^{\alpha}} X'Z a_0^{-1} I_k \frac{1}{N^{\alpha}} Z'\gamma
+ \frac{1}{N^{\alpha}} X'Z \left[ a_0^{-1} I_k - \left( \frac{1}{N^{\alpha}} Z'Z \right)^{-1} \right] \frac{1}{N^{\alpha}} Z'\gamma.
\]

Notice that

\[
\left\| \frac{1}{N^{\alpha}} X'Z \left[ a_0^{-1} I_k - \left( \frac{1}{N^{\alpha}} Z'Z \right)^{-1} \right] \frac{1}{N^{\alpha}} Z'\gamma \right\|
\leq \left\| \frac{1}{N^{\alpha}} X'Z \right\| \left\| a_0^{-1} I_k - \left( \frac{1}{N^{\alpha}} Z'Z \right)^{-1} \right\| \left\| \frac{1}{N^{\alpha}} Z'\gamma \right\| = o_p \left( \frac{1}{\sqrt{k^{m-1}T}} \right),
\]

where the last line follows from (B.2), and (2) and (5) of Lemma B.4. Similarly, by (2) and (5) of Lemma B.4,

\[
\left\| \frac{1}{N^{\alpha}} X'Z a_0^{-1} I_k \frac{1}{N^{\alpha}} Z'\gamma \right\| \leq O(1) \left\| \frac{1}{N^{\alpha}} X'Z \right\| \left\| \frac{1}{N^{\alpha}} Z'\gamma \right\| = o_p \left( \frac{1}{\sqrt{k^{m-1}T}} \right).
\]

Then we can further write (B.7) as

\[
\frac{1}{N^{\alpha}} X'MZ\gamma = \frac{1}{N^{\alpha}} X'\gamma + O_p \left( \frac{1}{\sqrt{k^{m-1}T}} \right) = O_p \left( \frac{1}{\sqrt{k^{m-1}T}} \right),
\]

where the second equality follows from (4) of Lemma B.4.

The consistency follows from (B.4), (B.6) and (B.8) immediately.

Below, we focus on the normality.

\[
\sqrt{N^{\alpha}} (\beta - \beta_0) = \left( \frac{1}{N^{\alpha}} X'MZX \right)^{-1} \frac{1}{\sqrt{N^{\alpha}}} X'MZ(\gamma + \varepsilon)
\]
By (B.4) and (B.8), it is straightforward to obtain that
\[
\left( \frac{1}{NT} X' M Z \right)^{-1} \frac{1}{\sqrt{NT}} X' M Z \gamma = O_P \left( N^{1/2} k^{-\frac{m-1}{2}} \right) = o_P(1),
\]
where the second equality follows from the assumption $N/k^{m-1} \to 0$.

Therefore, we need only to consider the next term
\[
\sqrt{NT} (\hat{\beta} - \beta) = \left( \frac{1}{NT} X' M Z \right)^{-1} \frac{1}{\sqrt{NT}} X' M Z \gamma + o_P(1).
\]

By (B.4), $\frac{1}{NT} X' M Z X \to_P \Sigma_v$. We then focus on $\frac{1}{\sqrt{NT}} X' M Z E$ below. Further expand (B.6)
\[
\frac{1}{\sqrt{NT}} X' M Z E = \frac{1}{\sqrt{NT}} N \sum_{i=1}^{N} \sum_{t=1}^{T} (\phi(u_{it}) + v_{it}) e_{it} + O_P \left( \frac{\sqrt{k}}{\sqrt{T}} \right).
\]

In the proof for (3) of Lemma B.4, we have shown that $\frac{1}{\sqrt{NT}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \phi(u_{it}) e_{is} = o_P \left( \frac{1}{\sqrt{NT}} \right)$ and $\frac{1}{\sqrt{NT}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} v_{it} e_{is} = o_P \left( \frac{1}{\sqrt{NT}} \right)$. Thus, it is straightforward to obtain that
\[
\frac{\sqrt{NT}}{NT^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\phi(u_{it}) + v_{it}) e_{is} = o_P(1).
\]

Hence, we can further write
\[
\frac{1}{\sqrt{NT}} X' M Z E = \frac{1}{\sqrt{NT}} N \sum_{i=1}^{N} \sum_{t=1}^{T} (\phi(u_{it}) + v_{it}) e_{it} + o_P(1).
\]

By (7) of Lemma B.2, it is easy to know that $\frac{1}{\sqrt{NT}} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) e_{it} = o_P(1)$. Therefore, we can write $\frac{1}{\sqrt{NT}} X' M Z E$ as
\[
\frac{1}{\sqrt{NT}} X' M Z E = \frac{1}{\sqrt{NT}} N \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it} e_{it} + o_P(1).
\]

Chen et al. (2012b) have shown that $\frac{1}{\sqrt{NT}} \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it} e_{it} \to_D N(0, \Sigma_{v,e})$ in their formula (A.44). In connection with $\frac{1}{NT} X' M Z X \to_P \Sigma_v$, the normality follows.

Proof of Lemma 3.1: Note that
\[
\hat{C} - C = \left( \hat{Z}' M_X Z \right)^{-1} \hat{Z}' M_X \gamma + \left( Z' M_X Z \right)^{-1} Z' M_X E,
\]
and we normalize each term as

\[
\frac{1}{N^{1/2}} Z' M_X Z = \frac{1}{N^{1/2}} Z' Z - \frac{1}{N^{1/2}} Z' X \left( \frac{1}{N T} X' X \right)^{-1} \frac{1}{N T} X' Z \quad (B.10)
\]

\[
\frac{1}{N^{1/2}} Z' M_X \gamma = \frac{1}{N^{1/2}} Z' \gamma - \frac{1}{N^{1/2}} Z' X \left( \frac{1}{N T} X' X \right)^{-1} \frac{1}{N T} X' \gamma \quad (B.11)
\]

\[
\frac{1}{N^{1/2}} Z' M_X \epsilon = \frac{1}{N^{1/2}} Z' \epsilon - \frac{1}{N^{1/2}} Z' X \left( \frac{1}{N T} X' X \right)^{-1} \frac{1}{N T} X' \epsilon. \quad (B.12)
\]

We now consider (B.10)–(B.12) respectively. Firstly, notice that

\[
\| \frac{1}{N^{1/2}} Z' M_X Z - a_0 I_k \| \leq \left( \frac{1}{N^{1/2}} Z' - a_0 I_k \right) + \left( \frac{1}{N^{1/2}} Z' X \right) \left( \frac{1}{N T} X' X \right)^{-1} \left( \frac{1}{N T} X' \right) = o_P(1),
\]

where the last line follows from Lemma B.5 and (2) and (6) of Lemma B.4 in this paper. Consequently, we obtain that

\[
\lambda_{min} \left( \frac{1}{N^{1/2}} Z' M_X Z \right) = \min_{\| \mu \|=1} \left\{ \mu' a_0 I_k \mu + \mu' \left( \frac{1}{N^{1/2}} Z' M_X Z - a_0 I_k \right) \mu \right\} \geq a_0 - \| \frac{1}{N^{1/2}} Z' M_X Z - a_0 I_k \| \geq \frac{1}{2} a_0 + o_P(1).
\]

For (B.11),

\[
\| \frac{1}{N^{1/2}} Z' M_X \gamma \| \leq \left( \frac{1}{N^{1/2}} Z' \right) \| \frac{1}{N^{1/2}} Z' X \| \left( \frac{1}{N T} X' X \right)^{-1} \left( \frac{1}{N T} X' \right) = O_P \left( k^{-(m+1)/2} \right),
\]

where the equality follows from (2), (4), (5) and (6) of Lemma B.4. According to the above, it is easy to obtain that

\[
\left\| (Z' M_X Z)^{-1} Z' M_X \gamma \right\|^2 \leq \lambda_{min}^{-2} \left( \frac{1}{N^{1/2}} Z' M_X Z \right) \cdot \left\| \frac{1}{N^{1/2}} Z' M_X \gamma \right\|^2 = O_P(k^{-m+1}). \quad (B.13)
\]

For (B.12),

\[
\| \frac{1}{N^{1/2}} Z' M_X \epsilon \| \leq \left( \frac{1}{N^{1/2}} Z' \right) \| \frac{1}{N^{1/2}} Z' X \| \left( \frac{1}{N T} X' X \right)^{-1} \left( \frac{1}{N T} X' \right) = O_P \left( \frac{\sqrt{k}}{N^{1/2}} \right),
\]

where the equality follows from (1), (2), (3) and (6) of Lemma B.4 in this paper. Similar to (B.13), it is straightforward to obtain that

\[
\left\| (Z' M_X Z)^{-1} Z' M_X \epsilon \right\|^2 \leq \lambda_{min}^{-2} \left( \frac{1}{N^{1/2}} Z' M_X Z \right) \cdot \left\| \frac{1}{N^{1/2}} Z' M_X \epsilon \right\|^2 = O_P \left( \frac{k}{N^{1/2}} \right). \quad (B.14)
\]

Therefore, the result follows from (B.13) and (B.14) immediately. ■
Proof of Theorem 3.2: 1) It follows from the orthogonality of the Hermite sequence that

\[
\int (\hat{g}(w) - g(w))^2 dw = (\hat{C} - C)' \int Z_k(w)Z_k(w)'d\hat{C}(\hat{C}) + \int \gamma_k^2(w) dw
= \|\hat{C} - C\|^2 + \int \gamma_k^2(w) dw = O_P\left(\frac{k}{N\sqrt{T}}\right) + O_P(k^{-m+1}),
\]

where Lemmas 3.1 and B.1 are used.

2) We now focus on the normality. We can write

\[
\sqrt{N\sigma_k^{-1}(w)} \sqrt{T}(\hat{g}(w) - g(w)) = \sqrt{N\sigma_k^{-1}(w)} \sqrt{T}Z_k(w)'(\hat{C} - C) - \sqrt{N\sigma_k^{-1}(w)} \sqrt{T}Z_k(w)'\gamma_k(w)
= \sqrt{N\sigma_k^{-1}(w)} \sqrt{T}Z_k(w)'(Z'M_XZ)^{-1}Z'M_X\Gamma
\]

\[
+ \sqrt{N\sigma_k^{-1}(w)} \sqrt{T}Z_k(w)'(Z'M_XZ)^{-1}Z'M_X\gamma - \sqrt{N\sigma_k^{-1}(w)} \sqrt{T}Z_k(w)'\gamma_k(w)
= \sqrt{N\sigma_k^{-1}(w)} \sqrt{T}Z_k(w)'(Z'M_XZ)^{-1}Z'M_X\Gamma + O_P(N^{\frac{1}{2}}T^{\frac{1}{4}}k^{-\frac{m-1}{2}}) + O_P(N^{\frac{1}{2}}T^{\frac{1}{4}}k^{-\frac{m}{2}} + 1)
= \frac{1}{\sqrt{N\sigma_k(w)a_0^2\sqrt{T}}} Z_k(w)'Z'\Gamma + o_P(1)
= \frac{1}{\sqrt{N\sigma_k(w)a_0^2\sqrt{T}}} \sum_{i=1}^{T} Z_k(w)'Z_k(u_{it})e_{it} + o_P(1),
\]

where the third equality follows from \(Z_k(w) = O(\sqrt{k})\), (2) of Lemma B.1 and (B.13); the fourth equality follows from the assumption in the body of this theorem; the sixth equality follows from (2) of Lemma B.5, (2), (3) and (6) of Lemma B.4 of this paper and Lemma B.3; the last equality follows from the proof for (1) of Lemma B.4.

For notation simplicity, denote \(V_{Nk}(t; w) = \frac{1}{\sqrt{N\|Z_k(w)\|^2}} \sum_{i=1}^{N} Z_k(w)'Z_k(u_{it})e_{it}\) and \(\hat{\sigma} = \sqrt{a_0\sigma_\Gamma^2}\).

We further write

\[
\sqrt{N\sigma_k^{-1}(w)} \sqrt{T}(\hat{g}(w) - g(w)) = \frac{1}{\hat{\sigma}} \sum_{t=1}^{T} \frac{1}{\sqrt{T}} V_{Nk}(t; w) + o_P(1).
\]

Notice that \(V_{Nk}(t; w)\) is a martingale difference array by Assumption 1. We then use the central limit theorem for martingale difference array to show the normality. See Lemma B.1 of Chen et al. (2012b) and Corollary 3.1 of Hall and Heyde (1980, p. 58) for reference. Firstly, we verify the conditional
Lindeberg condition, i.e. as \((N, T) \to (\infty, \infty)\), for \(\forall \epsilon > 0\),

\[
\frac{1}{\sqrt{T}} \sum_{t=1}^{T} E \left[ V_{Nk}^2(t; w) I \left( |V_{Nk}(t; w)| \geq \epsilon \sqrt{T} \right) \right] = o_P(1). \tag{B.17}
\]

To this end, write

\[
\frac{1}{\epsilon^2 T} \sum_{t=1}^{T} E \left[ V_{Nk}^2(t; w) I \left( |V_{Nk}(t; w)| \geq \epsilon \sqrt{T} \right) \right] \leq \frac{1}{\epsilon^2 T} \sum_{t=1}^{T} E \left[ V_{Nk}^2(t; w) \right] E \left[ \frac{1}{N} \sum_{i=1}^{N} \frac{1}{N} \sum_{j=1}^{N} |Z_k(w)' Z_k(u_{it})|^4 \right] E \left[ e_{i1t} e_{i2t} e_{i3t} e_{i4t} \right] F_{Nt-1} \]

\[
\leq \frac{1}{\epsilon^2 T} \sum_{t=1}^{T} E \left[ |Z_k(u_{it})|^4 \right] \cdot \frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} |Z_k(w)' Z_k(u_{it})|^4 \left( \frac{1}{N} \sum_{i=1}^{N} \sum_{j=1}^{N} |Z_k(u_{it})|^4 \right) E \left[ e_{i1t} e_{i2t} e_{i3t} e_{i4t} \right] F_{Nt-1} \]

\[
\leq O_P(1) \frac{1}{\epsilon^2 T} \sum_{t=1}^{T} \frac{1}{d_t} \int \|Z_k(x)\|^4 dx = O_P(1) \frac{k^2}{\epsilon^2 \sqrt{T}} = o_P(1), \tag{B.18}
\]

due to the independence of \(u_{it}\) and \(u_{jt}\) for \(i \neq j\), where the first inequality follows from Hölder inequality; the second inequality follows from Markov inequality; the last line follows from the assumption in the body of this theorem, and \(\|Z_k(\cdot)\|^2 = O(k), \int \|Z_k(x)\|^2 dx = k\) as well as the density \(f_t(x)\) of \(d_t^{-1} u_{it}\) being bounded uniformly (note that \(d_t = |\rho| \sqrt{T} (1 + o(1))\) and see the proof of Lemma B.5 in the supplement of this paper for more details).

Next, we verify the convergence of the conditional variance of \(V_{Nk}(t; w)\). Again, by the independence of \(u_{it}\) and \(u_{jt}\) for \(i \neq j\),

\[
\sum_{t=1}^{T} E \left[ V_{Nk}^2(t; w) \right] = \frac{1}{\sqrt{T}} \sum_{t=1}^{T} E \left[ Z_k(w)' Z_k(u_{it}) Z_k(u_{jt})' Z_k(w) \sigma_e(i, j) \right] \]

\[
= \frac{1}{\sqrt{T}} \sum_{t=1}^{T} E \left[ Z_k(w)' Z_k(u_{it}) Z_k(u_{jt})' Z_k(w) \sigma_e^2 \right] + \frac{1}{\sqrt{T}} \sum_{t=1}^{T} E \left[ Z_k(u_{it}) Z_k(u_{jt})' Z_k(w) \sigma_e(i, j) \right] \]

\[
\equiv A_{NT1} + A_{NT2}.
\]

By (1) of Lemma B.5, we have \(A_{NT1} \to_P a_q \sigma_e^2\), and we may show that \(A_{NT2} = o_P(1)\). In fact,

\[
|A_{NT2}| \leq \frac{1}{N \sqrt{T}} \sum_{i \neq j} \sum_{t=1}^{T} E \left[ \|Z_k(u_{it})\| \right] E \left[ \|Z_k(u_{jt})\| \right] \cdot |\sigma_e(i, j)|
\]

\[
= \frac{1}{N} \sum_{i \neq j} |\sigma_e(i, j)| \cdot \frac{1}{\sqrt{T}} \sum_{t=1}^{T} \left( \int \|Z_k(d_t x)\| f_t(x) dx \right)^2
\]

\[
\leq O(1) \frac{1}{N} \sum_{i \neq j} |\sigma_e(i, j)| \cdot \frac{1}{\sqrt{T}} \sum_{t=1}^{T} \frac{1}{d_t^2} \left( \int \|Z_k(x)\| dx \right)^2.
\]

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Meanwhile, as in Assumption 1. Hence, the distribution of \( u \) follows from the uniformly boundedness of \( f_i(x) \); the last line follows from (4) of Lemma B.1 and Assumption 1.3.b.

Therefore, in connection with (B.16), \( \sqrt{N\sigma_k^{-1}(w)}\sqrt{T}(\hat{g}(w) - g(w)) \to_D N(0, 1) \).

Appendix C below is a supplementary document for the proofs of the lemmas and corollary.

**Appendix C: Proofs of Lemmas and Corollary**

We start from the proof of Lemma B.5, which provides some fundamental results and notations used throughout this document.

**Proof of Lemma B.5**

1) It suffices to show that as \((N, T) \to (\infty, \infty)\) jointly,

\[
\left\| \frac{1}{N \sqrt{T}} Z'Z - \frac{1}{N \sqrt{T}} E[Z'Z] \right\| \to_P 0 \quad \text{and} \quad \frac{1}{N \sqrt{T}} E[Z'Z] = a_0 I_k.
\]

Notice that

\[
\frac{1}{N \sqrt{T}} Z'Z = \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_{it})Z_k(u_{it})' - \frac{\sqrt{T}}{N} \sum_{i=1}^{N} \bar{Z}_{k,i} \bar{Z}_{k,i}'
\]

\[
= \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_{it})Z_k(u_{it})' - \frac{1}{NT^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} Z_k(u_{it})Z_k(u_{is})' \equiv A_{NT} - B_{NT}. \quad (C.1)
\]

**Stage One.** Calculate the expectation. Note that \( \{u_{it}\} \) is i.i.d sequence across \( i \). Therefore, the distribution of \( u_{it} \) does not depend on \( i \). Let \( d_t = (E[u_{it}^2])^{1/2} = |\rho| \sqrt{t(1 + o(1))} \), where \( \rho \neq 0 \) is given in Assumption 1. Hence, \( d_t^{-1} u_{it} \) has a density \( f_i(x) \), which is uniformly bounded over \( x \) and large \( t \). Meanwhile, as \( t \to \infty \), \( \max_x |f_i(x) - \varphi(x)| \leq C d_t^{-1} \) for some \( C > 0 \), where \( \varphi(x) \) is the density of a standard normal variable (see Dong and Gao (2014) for more details on the properties of \( f_i(x) \)). Let \( \nu = \nu(T) \) be a function of \( T \) such that \( \nu \to \infty \) and \( k\nu/\sqrt{T} \to 0 \) as \( T \to \infty \).

\[
E[A_{NT}] = \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} E[Z_k(u_{it})Z_k(u_{it})']
\]

\[
= \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} E[Z_k(u_{it})Z_k(u_{it})'] + \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} E[Z_k(u_{it})Z_k(u_{it})']
\]

\[
= \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} E[Z_k(u_{it})Z_k(u_{it})'] + \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} d_t^{-1} \int Z_k(x)Z_k(x)'f_i(d_t^{-1}x)dx
\]

\[
= \frac{1}{\sqrt{T}} \sum_{t=1}^{T} E[Z_k(u_{1t})Z_k(u_{1t})'] + \frac{1}{\sqrt{T}} \sum_{t=\nu+1}^{T} d_t^{-1} \int Z_k(x)Z_k(x)'f_i(d_t^{-1}x)dx = A_{NT,1} + A_{NT,2}.
\]
By the construction, it is easy to obtain that for $A_{NT,1}$
\[
\frac{1}{\sqrt{T}} \left\| \sum_{t=1}^{T} d_{t}^{-1} \int Z_{k}(x)Z_{k}(x)' f_{t}(d_{t}^{-1} x) dx \right\| \leq \frac{1}{\sqrt{T}} \sum_{t=1}^{T} d_{t}^{-1} \int Z_{k}(x)Z_{k}(x)' (f_{t}(d_{t}^{-1} x) - \varphi(d_{t}^{-1} x)) dx + \frac{1}{\sqrt{T}} \sum_{t=1}^{T} d_{t}^{-1} \int Z_{k}(x)Z_{k}(x)' \varphi'(d_{t}^{-1} x) dx
\]
where the equality follows from (6) of Lemma B.1. We then consider $A_{NT,2}$
\[
A_{NT,2} = \frac{1}{\sqrt{T}} \sum_{t=1}^{T} d_{t}^{-1} \int Z_{k}(x)Z_{k}(x)' f_{t}(d_{t}^{-1} x) dx
\]
By the construction, it is easy to obtain that for $A_{NT,2}$
\[
\frac{1}{\sqrt{T}} \left\| \sum_{t=1}^{T} d_{t}^{-1} \int Z_{k}(x)Z_{k}(x)' (f_{t}(d_{t}^{-1} x) - \varphi(d_{t}^{-1} x)) dx \right\| \leq O(1) \frac{k \ln T}{\sqrt{T}} = o(1).
\]
Notice also that
\[
\frac{1}{\sqrt{T}} \left\| \sum_{t=1}^{T} d_{t}^{-1} \int_{|x| < \varepsilon d_{t}} Z_{k}(x)Z_{k}(x)' (\varphi(d_{t}^{-1} x) - \varphi(0)) dx \right\|
\]
\[
\leq O(1) \frac{k \ln T}{\sqrt{T}} \int_{|x| < \varepsilon d_{t}} Z_{k}(x)Z_{k}(x)' (\varphi(d_{t}^{-1} x) - \varphi(0)) dx
\]
\[
\leq O(1) \frac{k \ln T}{\sqrt{T}} \int_{|x| < \varepsilon d_{t}} Z_{k}(x)Z_{k}(x)' (\varphi(d_{t}^{-1} x) - \varphi(0)) dx
\]
\[
\leq O(1) \frac{k \ln T}{\sqrt{T}} \int_{|x| < \varepsilon d_{t}} Z_{k}(x)Z_{k}(x)' (\varphi(d_{t}^{-1} x) - \varphi(0)) dx
\]
where the last line follows from (5) and (9) of Lemma B.1. Moreover,
\[
\frac{1}{\sqrt{T}} \left\| \sum_{t=1}^{T} d_{t}^{-1} \int_{|x| < \varepsilon d_{t}} Z_{k}(x)Z_{k}(x)' (\varphi(d_{t}^{-1} x) - \varphi(0)) dx \right\|
\]
\[
\leq O(1) \frac{k \ln T}{\sqrt{T}} \int_{|x| < \varepsilon d_{t}} Z_{k}(x)Z_{k}(x)' (\varphi(d_{t}^{-1} x) - \varphi(0)) dx
\]
\[
\leq O(1) \frac{k \ln T}{\sqrt{T}} \int_{|x| < \varepsilon d_{t}} Z_{k}(x)Z_{k}(x)' (\varphi(d_{t}^{-1} x) - \varphi(0)) dx
\]
\[ \leq O(1) \frac{1}{\sqrt{T}} \sum_{t=\nu+1}^{T} d_t^{-1} \int_{|x| \geq \epsilon d_t} \| Z_k(x) Z_k(x)' \| dx \]

\[ \leq O(1) \frac{1}{\sqrt{T}} \sum_{t=\nu+1}^{T} \varepsilon^{-1} d_t^{-2} \int_{|x| \geq \epsilon d_t} \| Z_k(x) Z_k(x)' \| \cdot |x| dx \]

\[ \leq O(1) \varepsilon^{-1} \frac{\ln(T)}{\sqrt{T}} \left( \int |x|^2 \| Z_k(x)\|^2 dx \int \| Z_k(x)\|^2 dx \right)^{1/2} = O(1) \frac{k^{3/2} \ln(T)}{\sqrt{T}}. \quad (C.3) \]

In view of Assumption 2, (C.2) and (C.3), we obtain that \( E[A_{NT}] = 2\varphi(0)/|\rho| \cdot I_k(1 + o(1)) \).

Next, we will show that \( E[B_{NT}] = o(1) \). For \( t > s \) and \( t - s \) is large, note that, without loss of generality letting \( u_{i0} = 0 \) a.s.

\[ u_{it} = \sum_{t=1}^{t} \eta_{it} = \sum_{t=1}^{t} \sum_{j=-\infty}^{t} \rho_{t-j} \epsilon_{ij} = \sum_{j=-\infty}^{t} b_{t,j} \epsilon_{ij} \]

\[ = \sum_{j=s+1}^{t} b_{t,j} \epsilon_{ij} + \sum_{j=-\infty}^{s} b_{t,j} \epsilon_{ij} := u_{i,ts} + u_{i,ts}', \]

where \( b_{t,j} = \sum_{\ell=\max(1,j)}^{t} \rho_{t-j} \).

Similar to the proof of Lemma A.4 of Dong et al. (2014), \( \frac{1}{d_{ts}} u_{i,ts} \) has uniformly bounded densities \( f_{ts}(w) \) over all \( t \) and \( s \), where \( d_{ts} = O(1) \sqrt{t - s} \). Without loss of generality, in what follows we abuse the density by neglecting the argument on \( \nu = \nu(T) \) as we did before. Let \( \mathcal{R}_{is} = \sigma(\ldots, \varepsilon_{i,s-1}, \varepsilon_{is}) \) be the sigma field generated by \( \varepsilon_{ij}, j \leq s \). Then,

\[ E[B_{NT}] = \frac{1}{NT^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ Z_k(u_{it}) Z_k(u_{is})' \right] \]

\[ = \frac{1}{NT^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} E \left[ Z_k(u_{it}) Z_k(u_{it})' \right] + \frac{2}{NT^{3/2}} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{t-1} E \left[ E[Z_k(u_{it}) Z_k(u_{is})' | \mathcal{R}_{is}] \right] \]

\[ = \frac{1}{NT^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} \int Z_k(d_{t}w) Z_k(d_{t}w)' f_{t}(w) dw \]

\[ + \frac{2}{NT^{3/2}} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{t-1} E \int Z_k(d_{ts}w_{1} + u_{i,ts}^{*}) Z_k(u_{is})' f_{ts}(w_{1}) dw_{1} \]

\[ = \frac{1}{T^{3/2}} \sum_{t=1}^{T} \frac{1}{d_{t}} \int Z_k(w) Z_k(w)' f_{t}(w/d_{t}) dw \]

\[ + \frac{2}{T^{3/2}} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{d_{ts}} E \int Z_k(w_{1}) Z_k(u_{is})' f_{ts} \left( \frac{w_{1} - u_{i,ts}^{*}}{d_{ts}} \right) dw_{1}. \]

The first term is confined by

\[ \frac{1}{T^{3/2}} \sum_{t=1}^{T} \frac{1}{d_{t}} \int \| Z_k(w) Z_k(w)' \| f_{t}(w/d_{t}) dw \leq O(1) \frac{1}{T^{3/2}} \sum_{t=1}^{T} \frac{1}{d_{t}} \int \| Z_k(w)\|^2 dw = O(1) \frac{k}{T} \]
while the second term is bounded by
\[
\frac{2}{T^{3/2}} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{d_{ts}} \int \|Z_k(w_1)Z_k(u_{is})\| f_{ts} \left( \frac{w_1 - u_{is}}{d_{ts}} \right) dw_1
\]
\[
\leq O(1) \frac{1}{T^{3/2}} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{d_{ts}} \int \|Z_k(w_1)\| \|Z_k(u_{is})\| \|Z_k(w_1)\| dw_1 \|Z_k(u_{is})\|
\]
\[
\leq O(1) \frac{1}{T^{3/2}} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{d_{ts}} \frac{1}{d_s} \left( \int \|Z_k(w_1)\| dw_1 \right)^2 = O(1) \frac{k^{11/6}}{T^{1/2}} = o(1),
\]
where the last equality follows from (4) of Lemma B.1. The calculation yields $\frac{1}{N^{1/2}} E[Z'|Z] = a_0 J_k(1 + o(1))$.

**Stage Two.** We shall show that as $(N, T) \to (\infty, \infty)$ jointly, $E \left\| \frac{1}{N^{1/2}} Z'|Z - \frac{1}{N^{1/2}} E[Z'|Z] \right\|^2 \to 0$. To do so, $N \to \infty$ and $u_{it}$ being independent with respect to (w.r.t.) $i$ are important. By (C.1) again,

\[
E \left\| \frac{1}{N^{1/2}} Z'|Z - \frac{1}{N^{1/2}} E[Z'|Z] \right\|^2 \geq \frac{2}{N^2 T} E \left\| \sum_{i=1}^{N} \sum_{t=1}^{T} \{ Z_k(u_{it})Z_k(u_{it})' - E[Z_k(u_{it})Z_k(u_{it})'] \} \right\|^2
\]
\[
+ \frac{2}{N^2 T^3} E \left\| \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \{ Z_k(u_{it})Z_k(u_{is})' - E[Z_k(u_{it})Z_k(u_{is})'] \} \right\|^2 \equiv \bar{A}_{NT} + \bar{B}_{NT}.
\]

We now consider $\bar{A}_{NT}$ and $\bar{B}_{NT}$ respectively.

\[
\bar{A}_{NT} = \frac{2}{N^2 T} E \left\| \sum_{i=1}^{N} \sum_{t=1}^{T} \{ Z_k(u_{it})Z_k(u_{it})' - E[Z_k(u_{it})Z_k(u_{it})'] \} \right\|^2
\]
\[
= \frac{2}{N^2 T} \sum_{i=1}^{N} E \left\| \sum_{t=1}^{T} \{ Z_k(u_{it})Z_k(u_{it})' - E[Z_k(u_{it})Z_k(u_{it})'] \} \right\|^2
\]
\[
\leq \frac{2}{N^2 T} \sum_{i=1}^{N} E \left\| \sum_{t=1}^{T} Z_k(u_{it})Z_k(u_{it})' \right\|^2
\]
\[
= \frac{2}{N^2 T} \sum_{n=0}^{k-1} \sum_{m=0}^{k-1} \sum_{i=1}^{N} \sum_{t=1}^{T} E [\mathcal{H}_n(u_{it}), \mathcal{H}_m(u_{it}), \mathcal{H}_n(u_{is}), \mathcal{H}_m(u_{is})]
\]
\[
= \frac{2}{N^2 T} \sum_{n=0}^{k-1} \sum_{m=0}^{k-1} \sum_{i=1}^{N} \sum_{t=1}^{T} E [\mathcal{H}_n^2(u_{it}), \mathcal{H}_m^2(u_{it})]
\]
\[
+ \frac{4}{N^2 T} \sum_{n=0}^{k-1} \sum_{m=0}^{k-1} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} E [\mathcal{H}_n(u_{it}), \mathcal{H}_m(u_{it}), \mathcal{H}_n(u_{is}), \mathcal{H}_m(u_{is})]
\]
\[
= \bar{A}_{NT,1} + \bar{A}_{NT,2}.
\]

For $\bar{A}_{NT,1}$, write

\[
\bar{A}_{NT,1} = \frac{2}{NT} \sum_{n=0}^{k-1} \sum_{m=0}^{k-1} \sum_{t=1}^{T} \mathcal{H}_n^2(d_t w) \mathcal{H}_m^2(d_t w) f_t(w) dw
\]
\[ \leq O(1) \frac{1}{NT} \sum_{n=0}^{k-1} \sum_{m=0}^{k-1} \sum_{t=1}^{T} \frac{1}{d_t} \int \mathcal{H}_n^2(w) f_t(w/d_t) dw \]

\[ \leq O(1) \frac{1}{NT} \sum_{n=0}^{k-1} \sum_{m=0}^{k-1} \sum_{t=1}^{T} \frac{1}{d_t} \int \mathcal{H}_n^2(w) dw = O(1) \frac{k^2}{N \sqrt{T}}. \]

where the first inequality follows from \( \mathcal{H}_n(w) \) being bounded uniformly.

For \( \bar{A}_{NT,2} \), write

\[ \bar{A}_{NT,2} = 4 \frac{1}{N^2T} \sum_{n=0}^{k-1} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{T-1} E \left[ \mathcal{H}_n^2(u_{it}) \mathcal{H}_n^2(u_{is}) \right] \]

\[ + 8 \frac{1}{N^2T} \sum_{n=1}^{k-1} \sum_{m=0}^{N-1} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{T-1} d_t d_s E \left[ \mathcal{H}_n^2(u_{it}) \mathcal{H}_m(u_{it}) \mathcal{H}_n(u_{is}) \mathcal{H}_m(u_{is}) \right] \equiv \bar{A}_{NT,21} + \bar{A}_{NT,22}. \]

For \( \bar{A}_{NT,21} \), using conditional argument again we have

\[ \bar{A}_{NT,21} \leq O(1) \frac{1}{NT} \sum_{n=0}^{k-1} \sum_{t=2}^{T} \sum_{s=1}^{T-1} \frac{1}{d_t} \frac{1}{d_s} \int \mathcal{H}_n^2(w_1) \mathcal{H}_n^2(w_2) dw_1 dw_2 = O(1) \frac{k}{N}. \]

For \( \bar{A}_{NT,22} \), we use the decomposition \( u_{it} = u_{i,ts} + u_{i,ts}^* \) again. Note that for \( 1 \leq i \leq N \) and \( s < t \), \( u_{i,ts} \) includes all the information between time periods \( s + 1 \) and \( t \) and \( u_{i,ts}^* \) includes all the information up to time period \( s \). As Dong and Gao (2014) show, \( \frac{1}{d_t} u_{i,ts} \) has a density \( f_{ts}(w) \), which is uniformly bounded on \( \mathbb{R} \) and satisfies uniform Lipschitz condition on \( \mathbb{R} \), i.e. \( \sup_w |f_{ts}(w + v) - f_{ts}(w)| \leq C|v| \) for some absolutely constant \( C \). Then we can write

\[ \bar{A}_{NT,22} = O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{N-1} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{T-1} d_t d_s E \left[ \mathcal{H}_n^2(u_{it}) \mathcal{H}_m(u_{it}) \mathcal{H}_n(u_{is}) \mathcal{H}_m(u_{is}) \right] \]

\[ = O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{N-1} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{T-1} \frac{1}{d_t} \frac{1}{d_s} \int \mathcal{H}_n^2(w) \mathcal{H}_m(w) f_{ts} \left( \frac{w - u_{is}^*}{d_{ts}} \right) dw \cdot \mathcal{H}_n(u_{is}) \mathcal{H}_m(u_{is}) \]

\[ = O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{N-1} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{T-1} \frac{1}{d_{ts}} \int \mathcal{H}_n^2(w) \mathcal{H}_m(w) \left[ f_{ts} \left( \frac{w - u_{is}^*}{d_{ts}} \right) - f_{ts} \left( \frac{-u_{is}^*}{d_{ts}} \right) \right] dw \cdot \mathcal{H}_n(u_{is}) \mathcal{H}_m(u_{is}) \]

where the last line follows from the truth that \( \int \mathcal{H}_n(w) \mathcal{H}_m(w) dw = 0 \) for \( m \neq n \). By the uniform Lipschitz condition of \( f_{ts} \), we then obtain that

\[ |\bar{A}_{NT,22}| \leq O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{N-1} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{T-1} \frac{1}{d_{ts}} \int |w \mathcal{H}_n(w) \mathcal{H}_m(w)| dw \cdot E \left[ |\mathcal{H}_n(u_{is}) \mathcal{H}_m(u_{is})| \right] \]
\[
O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{n-1} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{dt_s} \int |w \mathcal{H}_n(w) \mathcal{H}_m(w)| dw \cdot \int |\mathcal{H}_n(d_s w) \mathcal{H}_m(d_s w)| f_s(w) dw
\]
\[
\leq O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{n} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{dt_s} \int |w \mathcal{H}_n(w) \mathcal{H}_m(w)| dw \cdot \int |\mathcal{H}_n(w) \mathcal{H}_m(w)| dw
\]
\[
\leq O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{n} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{dt_s} \frac{1}{d_s} \left\{ \int \mathcal{H}_n^2 dw \int w^2 \mathcal{H}_m^2 dw \right\}^{1/2}
\]
\[
\cdot \left\{ \int \mathcal{H}_n^2 dw \int \mathcal{H}_m^2 dw \right\}^{1/2}
\]
\[
\leq O(1) \frac{1}{NT} \sum_{n=1}^{k-1} \sum_{m=0}^{n} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \frac{1}{dt_s} \frac{1}{d_s} \sqrt{m} = O \left( \frac{k^{5/2} \ln T}{N \sqrt{T}} \right) = o(1).
\]

By the calculation of \(A_{NT,1}\) and \(A_{NT,2}\), we have shown that \(A_{NT} = o(1)\).

For \(B_{NT}\), by the independence across \(i\) of \(\{u_{i1}, \ldots, u_{iT}\}\), write

\[
B_{NT} = \frac{2}{N^2 T^3} \sum_{i=1}^{N} E \left[ \left\| \sum_{t=1}^{T} \sum_{s=1}^{T} \{Z_k(u_{it})Z_k(u_{is})\}' - E[Z_k(u_{it})Z_k(u_{is})] \right\| ^2 \right]
\]
\[
\leq O(1) \frac{1}{N^2 T^3} \sum_{i=1}^{N} E \left[ \sum_{t=1}^{T} \sum_{s=1}^{T} Z_k(u_{it})Z_k(u_{is}) \right] ^2 \leq O(1) \frac{1}{N^2 T^3} \sum_{i=1}^{N} E \left[ \sum_{t=1}^{T} \sum_{s=1}^{T} \|Z_k(u_{it})\| \|Z_k(u_{is})\| \right] ^2
\]
\[
= O(1) \frac{1}{N^2 T^3} \sum_{i=1}^{N} E \left[ \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \|Z_k(u_{it_1})\| \|Z_k(u_{it_2})\| \|Z_k(u_{it_3})\| \|Z_k(u_{it_4})\| \right]
\]
\[
+ O(1) \frac{1}{N^2 T^3} \sum_{i=1}^{N} E \left[ \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \|Z_k(u_{it_1})\| \|Z_k(u_{it_2})\| \|Z_k(u_{it_3})\| \|Z_k(u_{it_4})\| \right]
\]
\[
+ O(1) \frac{1}{N^2 T^3} \sum_{i=1}^{N} E \left[ \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \|Z_k(u_{it_1})\| \|Z_k(u_{it_2})\| \|Z_k(u_{it_3})\| \|Z_k(u_{it_4})\| \right]
\]
\[
= B_{NT,1} + B_{NT,2} + B_{NT,3} + B_{NT,4}.
\]

For \(B_{NT,1}\), without losing generality, assume that \(t_1 > t_2 > t_3 > t_4\). Then, by the conditional argument,

\[
B_{NT,1} = O(1) \frac{1}{N^2 T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E \left[ \|Z_k(u_{it_1})\| \|Z_k(u_{it_2})\| \|Z_k(u_{it_3})\| \|Z_k(u_{it_4})\| \right]
\]
\[
\leq O(1) \frac{1}{N^2 T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \frac{1}{d_{t_1} d_{t_2} d_{t_3} d_{t_4}} \int \int \int \int \|Z_k(w_1)\| \|Z_k(w_2)\| \|Z_k(w_3)\| \|Z_k(w_4)\| dw_1 dw_2 dw_3 dw_4
\]

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\[
\frac{O(1)}{NT} \left( \int \|Z_k(w)\|dw \right)^4 = O \left( \frac{k^{11/3}}{NT} \right) = o(1),
\]

where the last line follows from (4) of Lemma B.1 and Assumption 2.2.

For \( \bar{B}_{NT,2} \), without losing generality, assume that \( t_1 = t_2 > t_3 > t_4 \). Then write

\[
\bar{B}_{NT,2} = \frac{O(1)}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} t_1 \sum_{t_2=1}^{t_1} \sum_{t_3=1}^{t_2} \sum_{t_4=1}^{t_3} E[\|Z_k(u_{t_1})\|^2 \|Z_k(u_{t_2})\| \|Z_k(u_{t_3})\|] 
\leq \frac{O(1)}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} t_1 \sum_{t_2=1}^{t_1} \sum_{t_3=1}^{t_2} \sum_{t_4=1}^{t_3} \frac{1}{d_{t_1}d_{t_2}d_{t_3}d_{t_4}} \int \int \int \|Z_k(w_1)\|^2 \|Z_k(w_2)\| \|Z_k(w_3)\| dw_1 dw_2 dw_3 
\leq \frac{O(1)}{NT^{3/2}} \int \|Z_k(w)\|^2 dw \left( \int \|Z_k(w)\|dw \right)^2 = O \left( \frac{k^{17/6}}{NT^{3/2}} \right) = o(1),
\]

where the last line follows from (4)–(5) of Lemma B.1 and Assumption 2.2.

For \( \bar{B}_{NT,3} \), without losing generality, assume that \( t_1 = t_2 = t_3 > t_4 \). Then write

\[
\bar{B}_{NT,3} = \frac{O(1)}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} t_1 \sum_{t_2=1}^{t_1} \sum_{t_3=1}^{t_2} \sum_{t_4=1}^{t_3} E[\|Z_k(u_{t_1})\|^3 \|Z_k(u_{t_2})\|] 
\leq \frac{O(1)}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} t_1 \sum_{t_2=1}^{t_1} \sum_{t_3=1}^{t_2} \sum_{t_4=1}^{t_3} \frac{1}{d_{t_1}d_{t_2}d_{t_3}d_{t_4}} \int \int \int \|Z_k(w_1)\|^3 \|Z_k(w_2)\| dw_1 dw_2 
\leq O \left( \frac{k}{NT^2} \right) \left( \int \|Z_k(w)\|dw \right)^2 = O \left( \frac{k^{17/6}}{NT^2} \right) = o(1),
\]

where the last line follows from (4) and (6) of Lemma B.1 and Assumption 2.2.

For \( \bar{B}_{NT,4} \), write

\[
\bar{B}_{NT,4} = \frac{1}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} \int \|Z_k(w)\|^4 dw = \frac{1}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} \int \|Z_k(d_{t_1}w)\|^4 f_t(w) dw 
\leq O \left( \frac{1}{N^2T^3} \right) \sum_{i=1}^{N} \sum_{t_1=1}^{T} \frac{1}{d_{t_1}} \int \|Z_k(w)\|^4 dw \leq O \left( \frac{k}{NT^{3/2}} \right) \int \|Z_k(w)\|^2 dw = O \left( \frac{k^2}{NT^{5/2}} \right) = o(1).
\]

Combining \( \bar{B}_{NT,1}, \bar{B}_{NT,2}, \bar{B}_{NT,3} \) and \( \bar{B}_{NT,4} \) together, we know that \( \bar{B}_{NT} = o(1) \).

Therefore, we have shown that \( \| \frac{1}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} Z_k(u_{t_1}) \gamma_k(u_{t_1}) \| = O_P(k^{-(m-1)/2}) \).

Lemma B.2. Under Assumptions 1 and 2, as \((N,T) \to (\infty, \infty)\) jointly,

1. \( \| \frac{1}{N^2T^3} \sum_{i=1}^{N} \sum_{t_1=1}^{T} Z_k(u_{t_1}) \gamma_k(u_{t_1}) \| = O_P(k^{-(m-1)/2}) \);
Proof of Lemma B.2:

1) Write

\[ E \left\| \frac{1}{\sqrt{NT}} \sum_{t=1}^{T} \sum_{i=1}^{N} Z_k(u_{it}) \gamma_k(u_{it}) \right\|^2 \]

\[ = \frac{1}{N^2T} E \left[ \sum_{i=1}^{N} \left( \sum_{t=1}^{T} \|Z_k(u_{it})\|^2 \gamma_k^2(u_{it}) + 2 \sum_{t=2}^{T} \sum_{s=1}^{s} Z_k(u_{it})'Z_k(u_{is})\gamma_k(u_{it})\gamma_k(u_{is}) \right) \right] \]

\[ + \frac{2}{N^2T} E \left[ \sum_{i=2}^{N} \sum_{j=1}^{T} Z_k(u_{it})'Z_k(u_{jt})\gamma_k(u_{it})\gamma_k(u_{jt}) \right] \]

\[ + \frac{4}{N^2T} E \left[ \sum_{i=2}^{N} \sum_{j=1}^{T} \sum_{t=2}^{T} \sum_{s=1}^{s} Z_k(u_{it})'Z_k(u_{is})\gamma_k(u_{it})\gamma_k(u_{is}) \right] \equiv A_1 + 2A_2 + 4A_3. \]

Notice that

\[ A_1 = \frac{1}{N^2T} \sum_{i=1}^{N} \sum_{t=1}^{T} E \left[ \|Z_k(u_{it})\|^2 \gamma_k^2(u_{it}) \right] \]

\[ + \frac{2}{N^2T} \sum_{i=2}^{N} \sum_{j=1}^{T} \sum_{t=2}^{T} \sum_{s=1}^{s} E \left[ Z_k(u_{it})'Z_k(u_{is})\gamma_k(u_{it})\gamma_k(u_{is}) \right]. \quad (C.5) \]

The first term on RHS of (C.5) can be written as

\[ \frac{1}{N^2T} \sum_{i=1}^{N} \sum_{t=1}^{T} E[\|Z_k(u_{it})\|^2 \gamma_k^2(u_{it})] \leq O \left( \frac{k^{-m+5/6}}{N^2T} \right) \sum_{i=1}^{N} \sum_{t=1}^{T} \|Z_k(d_t w)\|^2 f_t(w)dw \]

\[ = O \left( \frac{k^{-m+5/6}}{N^2T} \right) \sum_{i=1}^{N} \sum_{t=1}^{T} \int \frac{1}{d_t} \|Z_k(w)\|^2 f_t(w/d_t)dw \]

\[ \leq O \left( \frac{k^{-m+5/6}}{N^2T} \right) \sum_{i=1}^{N} \sum_{t=1}^{T} \frac{1}{d_t} \int \|Z_k(w)\|^2 dw \leq O \left( \frac{k^{-m+11/6}}{N^2T} \right), \]
where the first inequality follows from (2) of Lemma B.1 and the second inequality follows from \( f_t(w) \) being bounded uniformly.

For the second term on RHS of (C.5),

\[
\frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{t-1} E[Z_k(u_{it})' Z_k(u_is) \gamma_k(u_{it}) \gamma_k(u_is)] \\
\leq \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{t-1} E[\|Z_k(u_{it})\| \|Z_k(u_is)\| \|\gamma_k(u_{it})\| \|\gamma_k(u_is)\|] \\
\leq O \left( \frac{1}{N^2 T} \right) \sum_{i=1}^{N} \sum_{t=2}^{T} \sum_{s=1}^{t-1} \int \int \frac{1}{d_{ts} d_s} \|Z_k(w_1)\| \|Z_k(w_2)\| \|\gamma_k(w_1)\| \|\gamma_k(w_2)\| dw_1 dw_2 \\
\leq O \left( \frac{1}{N} \right) \left( \int \|Z_k(w)\| \|\gamma_k(w)\| dw \right)^2 \leq O \left( \frac{1}{N} \right) \int \|Z_k(w)\|^2 dw \int |\gamma_k(w)|^2 dw = O \left( \frac{k^{-m+1}}{N} \right).
\]

Therefore, \( A_1 = O \left( \frac{k^{-m+1}}{N} \right) \).

For \( A_2 \), by virtue of \( Z_k(w) = (\mathcal{H}_0(w), \ldots, \mathcal{H}_{k-1}(w))' \),

\[
|A_2| = \left| \frac{1}{N^2 T} \sum_{i=2}^{N} \sum_{j=1}^{T} \sum_{t=1}^{k-1} E [\mathcal{H}_n(u_{it}) \gamma_k(u_{it})] \cdot E [\mathcal{H}_n(u_{jt}) \gamma_k(u_{jt})] \right| \\
= \left| \frac{1}{N^2 T} \sum_{i=2}^{N} \sum_{j=1}^{T} \sum_{t=1}^{k-1} \int \mathcal{H}_n(d_{iw}) \gamma_k(d_{iw}) f_i(w) dw \int \mathcal{H}_n(d_{iw}) \gamma_k(d_{iw}) f_i(w) dw \right| \\
\leq O \left( \frac{1}{N^2 T} \right) \sum_{i=2}^{N} \sum_{j=1}^{T} \sum_{t=1}^{k-1} \frac{1}{dt} \sum_{s=1}^{k-1} \left( \int |\mathcal{H}_n(w)\| \gamma_k(w)\| dw \right)^2 \\
\leq O \left( \frac{\ln T}{T} \right) \int \|Z_k(w)\|^2 dw \int |\gamma_k(w)|^2 dw = o \left( \frac{k^{-m+1}}{N} \right).
\]

Similar to \( A_2 \), for \( A_3 \) we write

\[
|A_3| = \left| \frac{1}{N^2 T} \sum_{i=2}^{N} \sum_{j=1}^{T} \sum_{t=1}^{k-1} \sum_{s=1}^{k-1} \sum_{n=0}^{k-1} E [\mathcal{H}_n(u_{it}) \gamma_k(u_{it})] \cdot E [\mathcal{H}_n(u_{js}) \gamma_k(u_{js})] \right| \\
\leq O \left( \frac{1}{T} \right) \sum_{t=2}^{T} \sum_{s=1}^{k-1} \frac{1}{dt} d_s \sum_{n=0}^{k-1} \left( \int |\mathcal{H}_n(w)\| \gamma_k(w)\| dw \right)^2 \\
\leq O(1) \int \|Z_k(w)\|^2 dw \int |\gamma_k(w)|^2 dw = O(k^{-m+1}).
\]

Thus, the result follows.

2) Write

\[
E \left\| \frac{1}{\sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) Z_k(u_{it})' \right\|^2 = \frac{1}{N^2 T} \sum_{m=1}^{d} \sum_{n=0}^{k-1} \sum_{t=1}^{T} E[\phi_m(u_{it}) \mathcal{H}_n(u_{it})]
\]

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\[
+ \frac{2}{N^2T} \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \sum_{s=1}^{T} E[\phi_m(u_{it}) \mathcal{H}_n(u_{it}) \phi_m(u_{js}) \mathcal{H}_n(u_{js})]
\]
\[
+ \frac{2}{N^2T} \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \sum_{s=1}^{T} E[\phi_m(u_{it}) \mathcal{H}_n(u_{it})] E[\phi_m(u_{js}) \mathcal{H}_n(u_{js})]
\]
\[
\leq O\left(\frac{1}{N^2T}\right) \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \sum_{s=1}^{T} \frac{1}{dt} \int \mathcal{H}_n^2(w) dw
\]
\[
+ O\left(\frac{2}{N^2T}\right) \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \sum_{s=1}^{T} \frac{1}{dt} \frac{1}{ds} \int \int \phi_m(w_1) \mathcal{H}_n(w_1) \phi_m(w_2) \mathcal{H}_n(w_2) dw_1 dw_2
\]
\[
+ O\left(\frac{2}{N^2T}\right) \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \sum_{s=1}^{T} \frac{1}{dt} \frac{1}{ds} \left(\int \phi_m(w) \mathcal{H}_n(w) dw\right)^2
\]
\[
\leq O\left(\frac{k}{N\sqrt{T}}\right) + \frac{2}{N^2} \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \left(\int \phi_m(w) \mathcal{H}_n(w) dw\right)^2
\]
\[
+ \frac{2}{N^2} \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \left(\int \phi_m(w) \mathcal{H}_n(w) dw\right)^2
\]
\[
= o(1) + \frac{2}{N^2} \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \left(\int \phi_m(w) \mathcal{H}_n(w) dw\right)^2
\]
\[
\leq o(1) + \frac{2}{N^2} \sum_{m=1}^{d} \sum_{k=0}^{N} \sum_{i=1}^{T} \sum_{j=1}^{T} \int \phi_m^2(w) dw = O(1),
\]

where the first equality is due to Assumption 1.4; the first inequality follows from that \(f_t(w)\) being bounded uniformly and \(\phi_m(w)\) being bounded uniformly on \(\mathbb{R}\) for \(m = 1, \ldots, d\); the last inequality follows from that \(\phi_m(w) \in L^2(\mathbb{R})\) (such that \(\phi_m(w) = \sum_{n=0}^{\infty} c_{m,n} \mathcal{H}_n(w)\) for \(m = 1, \ldots, d\), \(c_{m,n} = \int \phi_m(w) \mathcal{H}_n(w) dw\) for \(n = 0, \ldots, \infty\) and \(\sum_{n=0}^{\infty} c_{m,n}^2 = \int \phi_m^2(w) dw\)).

The proof is then complete.

3) Let \(v_{it,n1}\) denote the \(n_{1}^{th}\) element of \(v_{it}\). Write
\[
E \left\| \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it} Z_k(u_{it}) \right\|^2 = \sum_{n_{1}=1}^{d} \sum_{n_{2}=0}^{k-1} E \left[ \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it,n1} \mathcal{H}_n(u_{it}) \right]^2
\]
\[
= \sum_{n_{1}=1}^{d} \sum_{n_{2}=0}^{k-1} \sum_{i=1}^{N} \sum_{t=1}^{T} E[v_{it,n1} v_{js,n1}] E[\mathcal{H}_n(u_{it}) \mathcal{H}_n(u_{js})]
\]
\[
\leq O(k) \sum_{n_{1}=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{s=1}^{T} c_{5}(\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} \left( E[v_{it,n1}]^{2+\delta/2} \right)^{2/(4+\delta)} \left( E[v_{js,n1}]^{2+\delta/2} \right)^{2/(4+\delta)}
\]
\[
\leq O(k) \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{s=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} = O(kNT),
\]

where \(c_{5} = 2^{(4+2\delta)/(4+\delta)} \cdot (4+\delta)/\delta\); the second equality follows from Assumption 1.4; the first inequality follows from Davydov inequality (c.f. pages 19–20 in Bosq (1996) and supplementary of Su and Jin (2012)) and the truth that \(\mathcal{H}_n(w)\) is bounded uniformly (c.f. Nevai (1986)); the second inequality
follows from Assumption 1.3.a. Thus, the result follows.

4) Let \( \Sigma_{v,n_1n_2} \) denote the \((n_1, n_2)\)th element of \( \Sigma_v \). Write

\[
E \left| \sum_{t=1}^{N} \sum_{i=1}^{d} (v_{it} v'_{it} - \Sigma_v) \right|^2 = \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} E \left[ \sum_{t=1}^{N} \sum_{i=1}^{d} (v_{it, n_1} v_{it, n_2} - \Sigma_{v, n_1n_2}) \right]^2 \\
\leq \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} c_\delta (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} \\
\cdot \left( E[v_{it, n_1} v_{it, n_2}]^{2+\delta/2} \right)^{2/(4+\delta)} \left( E[v_{js, n_1} v_{js, n_2}]^{2+\delta/2} \right)^{2/(4+\delta)} \\
\leq \frac{c_\delta}{2} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \sum_{i=1}^{T} \sum_{j=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} \cdot \left( E[v_{it, n_1} v_{it, n_2}]^{2+\delta/2} \right)^{4/(4+\delta)} \\
+ \frac{c_\delta}{2} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \sum_{i=1}^{T} \sum_{j=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} \cdot \left( E[v_{js, n_1} v_{js, n_2}]^{2+\delta/2} \right)^{4/(4+\delta)} \\
\leq O(1) \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} = O(NT),
\]

where \( c_\delta = 2^{(4+2\delta)/(4+\delta)} \cdot (4+\delta)/\delta \); the first inequality follows from Davydov inequality; the third inequality follows from Cauchy–Schwarz inequality; the last line follows from Assumption 1.3.a. Therefore, the result follows.

5) Write

\[
E \left| \sum_{t=1}^{N} \sum_{i=1}^{d} v_{it} \phi(u_{it}) \right|^2 = \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} E \left[ \sum_{t=1}^{N} \sum_{i=1}^{d} v_{it, n_1} \phi_{n_2}(u_{it}) \right]^2 \\
= \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} E[v_{it, n_1} v_{js, n_2}] \cdot E[\phi_{n_2}(u_{it}) \phi_{n_2}(u_{js})] \\
\leq O(1) \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} \left( E[v_{it, n_1}]^{2+\delta/2} \right)^{2/(4+\delta)} \left( E[v_{js, n_2}]^{2+\delta/2} \right)^{2/(4+\delta)} \\
\leq O(1) \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} = O(NT),
\]

where the second equality follows from Assumption 1.4; the first inequality follows from Davydov inequality and the uniform boundedness of \( \phi_n(w) \) on \( \mathbb{R} \) for \( n = 1, \ldots, d \). Therefore, the result follows immediately.

6) By Assumptions 1.1 and 1.4,

\[
E \left| \frac{1}{N \sqrt{T}} \sum_{t=1}^{T} Z_k(u_{it}) e_{it} \right|^2 = \frac{1}{N^{2T}} E \left[ \left( \sum_{t=1}^{T} \sum_{i=1}^{d} Z_k(u_{it}) e_{it} \right)' \left( \sum_{t=1}^{T} \sum_{i=1}^{d} Z_k(u_{it}) e_{it} \right) \right]
\]
\[
\frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{t=1}^{T} E \left[ \|Z_k(u_{it})\|^2 \right] E \left[ e_{it}^2 \right] + \frac{2}{N^2 T} \sum_{i=2}^{N} \sum_{j=1}^{T} \sum_{t=1}^{T} E \left[ Z_k(u_{it}) \right] E \left[ Z_k(u_{jt}) \right] E \left[ e_{it} e_{jt} \right]
\]
\[
= B_1 + 2B_2.
\]

For \( B_1 \), write
\[
B_1 = \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{t=1}^{T} \int \|Z_k(d_t w)\|^2 f_t(w) dw \cdot \sigma_e^2
\]
\[
\leq O \left( \frac{1}{NT} \right) \sum_{t=1}^{T} \frac{1}{dt} \int \|Z_k(w)\|^2 dw = O \left( \frac{k}{N^{1/2}} \right),
\]
where the second line follow from that \( f_t(w) \) being bounded uniformly.

For \( B_2 \),
\[
|B_2| = \left| \frac{1}{N^2 T} \sum_{n=0}^{k-1} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t=1}^{T} \left( \mathcal{H}_n(d_t w) f_t(w) dw \right) \right|
\]
\[
\leq \frac{1}{N^2 T} \sum_{n=0}^{k-1} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t=1}^{T} \left( \mathcal{H}_n^2(d_t w) dw \right) \int f_t^2(w) dw |\sigma_e(i, j)|
\]
\[
\leq O \left( \frac{1}{NT^2} \right) \sum_{n=0}^{k-1} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t=1}^{T} \left| \sigma_e(i, j) \right| \leq O \left( \frac{k}{N^{1/2}} \right),
\]
where the first inequality follows from Cauchy–Schwarz inequality; the second inequality follows from \( f_t(w) \) being bounded uniformly; the third inequality follows from Assumption 1.3.b. In connection with \( B_1 = O \left( \frac{k}{N^{1/2}} \right) \), we obtain that \( \frac{1}{N^{1/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_{it})e_{it} = O P \left( \frac{\sqrt{T}}{N^{1/2}} \right) \).

7) Write
\[
E \left[ \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) e_{it} \right]^2 = \frac{\sigma_e^2}{N^2 T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} E \left[ \phi_n(u_{it}) \phi_n(u_{jt}) \right] E \left[ e_{it} e_{jt} \right]
\]
\[
= \frac{\sigma_e^2}{N^2 T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{t=1}^{T} \int \phi_n^2(d_t w) f_t(w) dw
\]
\[
+ \frac{2}{N^2 T^2} \sum_{n=1}^{d} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t=1}^{T} \int \phi_n(d_t w) f_t(w) dw \int \phi_n(d_t w) f_t(w) dw \cdot \sigma_e(i, j)
\]
\[
\leq O \left( \frac{1}{NT^2} \right) \sum_{n=1}^{d} \sum_{i=1}^{T} \frac{1}{dt} \int \phi_n^2(w) dw
\]
\[
+ O \left( \frac{2}{NT^2} \right) \sum_{n=1}^{d} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t=1}^{T} \int \phi_n^2(d_t w) dw \int f_t^2(w) dw |\sigma_e(i, j)|
\]
\[
\leq O \left( \frac{1}{NT^{3/2}} \right) + O \left( \frac{1}{NT^{3/2}} \right) = O \left( \frac{1}{NT^{3/2}} \right),
\]
where the first equality follows from Assumption 1.4; the first inequality follows from \( f_t(w) \) being bounded uniformly and \( \phi_n(w) \in L^2(\mathbb{R}) \); the second inequality follows from \( \phi_n(w) \) being integrable and Assumption 1.3. Therefore, the result follows.
8) Write

$$E \left\| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it}) \gamma_{k}(u_{it}) \right\|^2 = \frac{1}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ \phi_n(u_{it}) \gamma_k(u_{it}) \phi_n(u_{js}) \gamma_k(u_{js}) \right]$$

$$= \frac{1}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ \phi_n(u_{it}) \gamma_k(u_{it}) \phi_n(u_{is}) \gamma_k(u_{is}) \right]$$

$$+ \frac{2}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ \phi_n(u_{it}) \gamma_k(u_{it}) \right] E \left[ \phi_n(u_{js}) \gamma_k(u_{js}) \right]$$

$$= \frac{1}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ \phi_n^2(u_{it}) \gamma_k^2(u_{it}) \right] + \frac{2}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ \phi_n(u_{it}) \gamma_k(u_{it}) \phi_n(u_{is}) \gamma_k(u_{is}) \right]$$

$$+ \frac{2}{N^2T} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{t=1}^{T} \sum_{s=1}^{T} \frac{1}{\sqrt{T}} \sum_{t=1}^{T} E \left[ \phi_n(u_{it}) \gamma_k(u_{it}) \right] \frac{1}{\sqrt{T}} \sum_{t=1}^{T} E \left[ \phi_n(u_{js}) \gamma_k(u_{js}) \right]$$

$$\equiv C_1 + 2C_2 + 2C_3.$$

By (2) of Lemma B.1,

$$C_1 = O \left( \frac{k^{-m+5/6}}{N^2T^2} \right), \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{t=1}^{T} \int \phi_n^2(d_t w) f_t(w) dw$$

$$\leq O \left( \frac{k^{-m+5/6}}{N^2T^2} \right), \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{t=1}^{T} \int \phi_n^2(w) dw \leq O \left( \frac{k^{-m+5/6}}{NT^{3/2}} \right).$$

For $C_2$,

$$|C_2| = \left| \frac{1}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \int \phi_n(d_{ts} w_1 + d_s w_2) \gamma_k(d_{ts} w_1 + d_s w_2) \phi_n(d_s w_2) \gamma_k(d_s w_2) \right|$$

$$\leq O \left( \frac{1}{N^2T^2} \right), \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \frac{1}{d_t s} \int \phi_n(w_1) \gamma_k(w_1) \phi_n(w_2) \gamma_k(w_2) dw_1 dw_2$$

$$\leq O \left( \frac{1}{NT} \right), \sum_{n=1}^{d} \left( \int \phi_n(w) \gamma_k(w) dw \right)^2 \leq O \left( \frac{1}{NT} \right), \sum_{n=1}^{d} \int \phi_n^2(w) dw \int \gamma_k^2(w) dw = O \left( \frac{k^{-m}}{NT} \right).$$

For $C_3$,

$$\left| \frac{1}{\sqrt{T}} \sum_{i=1}^{T} \int \phi_n(u_{it}) \gamma_k(u_{it}) \right| \leq \frac{1}{\sqrt{T}} \sum_{i=1}^{T} \int \phi_n(d_t w) \gamma_k(d_t w) f_t(w) dw$$

$$\leq O(1), \frac{1}{\sqrt{T}} \sum_{i=1}^{T} \int \phi_n(w) \gamma_k(w) dw \leq O(1), \left\{ \int \phi_n^2(w) dw \int \gamma_k^2(w) dw \right\}^{1/2} = O(k^{-m/2}).$$

Thus, $|C_3| \leq \frac{1}{\sqrt{T}} \sum_{n=1}^{d} \sum_{i=1}^{T} \sum_{s=1}^{T} o(k^{-m}) = O \left( \frac{1}{\sqrt{T}} \right)$, In connection with the analysis for $C_1$ and $C_2$, $\frac{1}{\sqrt{T}} \sum_{i=1}^{T} \phi(u_{it}) \gamma_k(u_{it}) = O \left( \frac{1}{\sqrt{T}} \right)$. Then the proof is complete.
9) Write
\[
E \left\| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} v_{it} \gamma_k(u_i) \right\|^2 = \frac{1}{N^2T^2} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ v_{it} v_{js} \gamma_k(u_i) \gamma_k(u_j) \right]
\]
\[
= \frac{1}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} E \left[ v_{it,n} v_{js,n} \right] E \left[ \gamma_k(u_i) \gamma_k(u_j) \right]
\]
\[
\leq O \left( \frac{k^{-m+5/6}}{N^2T^2} \right) \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} \left( E \left[ |v_{it,n}|^{2+\delta/2} \right] \cdot E \left[ |v_{js,n}|^{2+\delta/2} \right] \right)^{2/(4+\delta)}
\]
\[
\leq O \left( \frac{k^{-m+5/6}}{N^2T^2} \right) \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\alpha_{ij}(|t-s|))^{\delta/(4+\delta)} = O \left( \frac{k^{-m+5/6}}{NT} \right),
\]
where the second equality follows from Assumption 1.4; the first inequality follows from (2) of Lemma B.1 and Davydov inequality; the last line follows from Assumption 1.3.a. Then the result follows.

**Lemma B.3.** For two non-singular symmetric matrices \(A, B\) with same dimensions \(k \times k\), where \(k\) tends to \(\infty\). Suppose that their minimum eigenvalues satisfy that \(\lambda_{\min}(A) > 0\) and \(\lambda_{\min}(B) > 0\) uniformly in \(k\). Then \(\|A^{-1} - B^{-1}\|^2 \leq \lambda_{\min}^2(A) \cdot \lambda_{\min}^2(B) \|A - B\|^2\).

**Proof of Lemma B.3:**

For two non-singular symmetric matrices \(A\) and \(B\) with same dimensions, we observe that
\[
\|A^{-1} - B^{-1}\|^2 = \|B^{-1} (B - A) A^{-1}\|^2 = \|\text{vec} (B^{-1} (B - A) A^{-1})\|^2
\]
\[
= \| (A^{-1} \otimes B^{-1}) \text{vec} (B - A) \|^2 \leq \lambda_{\min}^{-2} (A \otimes B) \|\text{vec} (B - A)\|^2
\]
\[
= \lambda_{\min}^{-2} (A) \cdot \lambda_{\min}^{-2} (B) \|A - B\|^2.
\]
The above calculation is straightforward and all the necessary theorems can be found in Magnus and Neudecker (2007).

**Lemma B.4.** Let Assumptions 1 and 2 hold. As \((N,T) \to (\infty,\infty)\) jointly, (1) \(\frac{1}{NVT} \mathcal{Z} \mathcal{E} = O_P \left( \frac{\sqrt{K}}{\sqrt{NVT}} \right)\); (2) \(\frac{1}{NVT} X' \mathcal{Z} = O_P(1)\); (3) \(\frac{1}{NVT} X' \mathcal{E} = O_P \left( \frac{1}{\sqrt{NVT}} \right)\); (4) \(\frac{1}{NVT} X' \mathcal{E} = O_P \left( \frac{1}{\sqrt{NVT}} \right)\); (5) \(\frac{1}{NVT} \mathcal{Z}' \gamma = O_P(k^{-(m-1)/2})\); (6) \(\frac{1}{NVT} X' X \rightarrow_d \Sigma_v\).

**Proof of Lemma B.4:**

1) \[
\frac{1}{NVT} \mathcal{Z}' \mathcal{E} = \frac{1}{NVT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_i)e_{it} - \frac{1}{NVT^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_i)e_{is} \equiv A_1 - A_2
\]

We have shown that \(A_1 = O_P \left( \frac{\sqrt{K}}{\sqrt{NVT}} \right)\) in (6) of Lemma B.2. We then just focus on \(A_2\). By Assumptions 1.1, 1.3.b and 1.4, write
\[
E\|A_2\|^2 = \frac{1}{N^2 T^2} \sum_{i=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} E[Z_k(u_{it_1})^T Z_k(u_{it_2})] \sum_{s=1}^{T} E[e_{is}^2]
+ \frac{2}{N^2 T^2} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} E[Z_k(u_{it_1})] E[Z_k(u_{jt_2})] \sum_{s=1}^{T} E[e_{is} e_{js}]
= \frac{\sigma_e^2}{N^2 T^2} \sum_{i=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} E[Z_k(u_{it_1})^T Z_k(u_{it_2})]
+ \frac{2}{N^2 T^2} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} E[Z_k(u_{it_1})] E[Z_k(u_{jt_2})] \sigma_e(i, j) \equiv A_{21} + 2A_{22}.
\]

For \(A_{21}\), write
\[
|A_{21}| \leq O\left(\frac{1}{N^2 T^2}\right) \sum_{i=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} E[\|Z_k(u_{it_1})\| \|Z_k(u_{it_2})\|] \leq O\left(\frac{T k^{11}}{N T^2}\right) = o\left(\frac{k}{N \sqrt{T}}\right),
\]
where the second inequality has been provided in the proof of Lemma B.5 in this paper and the last equality follows from Assumption 2.2.

For \(A_{22}\), write
\[
|A_{22}| \leq \frac{1}{N^2 T^2} \sum_{n=0}^{k-1} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \left|\int \mathcal{H}_n(d_{t_1}) w f_{t_1}(w) \right| \left|\int \mathcal{H}_n(d_{t_2}) w f_{t_2}(w) \right| \sigma_e(i, j)
\leq O\left(\frac{1}{N^2 T^2}\right) \sum_{n=0}^{k-1} \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \left|\int \mathcal{H}_n(w) \right| \sigma_e(i, j)
\leq O\left(\frac{k^2}{N T}\right) = o\left(\frac{k}{\sqrt{N T}}\right),
\]
where the last line follows from (8) of Lemma B.1 and Assumption 2.2.

By the analysis for \(A_{21}\) and \(A_{22}\), we obtain that \(A_2 = o_P\left(\frac{\sqrt{T}}{\sqrt{N \sqrt{T}}}\right)\). In connection with that \(A_1 = O_P\left(\frac{\sqrt{T}}{\sqrt{N \sqrt{T}}}\right)\), the result follows.

2)
\[
\frac{1}{N \sqrt{T}} X'Z = \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} (\phi(u_{it}) + v_{it}) Z_k(u_{it})' - \frac{1}{N T^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\phi(u_{is}) + v_{is}) Z_k(u_{is})'
\equiv B_1 - B_2
\]
\[
\|B_1\| = O_P(1) \text{ follows from (2) and (3) of Lemma B.2 of this paper immediately. Then we just need to focus on } B_2 \text{ below.}
\]
\[
B_2 = \frac{1}{N T^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \phi(u_{it}) Z_k(u_{is})' + \frac{1}{N T^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} v_{it} Z_k(u_{is})' \equiv B_{21} + B_{22}
\]

For \(B_{21}\), write
\[
E\|B_{21}\|^2 = \frac{1}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{d-1} \sum_{i=1}^{N} \sum_{j=1}^{j} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E[\phi_{n_1}(u_{it_1}) \mathcal{H}_{n_2}(u_{it_2}) \phi_{n_1}(u_{jt_3}) \mathcal{H}_{n_2}(u_{jt_4})]
\]
\[
= \frac{1}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{d} \sum_{N=1}^{T} \sum_{T=1}^{T} \sum_{T=1}^{T} \sum_{T=1}^{T} \sum_{E}[\phi_n(u_{it_1})_\mathcal{H}_n(u_{it_2})_\phi_n(u_{it_3})_\mathcal{H}_n(u_{it_4})] \\
+ \frac{2}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{d} \sum_{N=1}^{T} \sum_{i=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \sum_{E}[\phi_n(u_{it_1})_\mathcal{H}_n(u_{it_2})E[\phi_n(u_{it_3})_\mathcal{H}_n(u_{it_4})] \\
\equiv B_{211} + 2B_{212}.
\]

For \(B_{211}\), we write
\[
B_{211} = \frac{1}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{d} \sum_{N=1}^{T} \sum_{i=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \sum_{E}[\phi_n(u_{it_1})_\mathcal{H}_n(u_{it_2})_\phi_n(u_{it_3})_\mathcal{H}_n(u_{it_4})] \\
= \frac{1}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{d} \sum_{N=1}^{T} \sum_{i=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \sum_{E}[\phi_n(u_{it_1})_\mathcal{H}_n(u_{it_2})_\phi_n(u_{it_3})_\mathcal{H}_n(u_{it_4})] \\
\]

For \(B_{2111}\), without losing generality, assume that \(t_1 > t_2 > t_3 > t_4\). For other cases, for example \(t_2 > t_3 > t_1 > t_4\), the analysis will be same and the order will remain same. Then
\[
\leq O\left(\frac{1}{N^2 T^3}\right) \sum_{n_1=1}^{d} \sum_{n_2=0}^{d} \sum_{N=1}^{T} \sum_{i=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \frac{1}{d_{i,t_2}} \frac{1}{d_{i,t_3}} \frac{1}{d_{i,t_4}} \\
\cdot \int \int \int \int |\phi_n(w_1)_\mathcal{H}_n(w_2)_\phi_n(w_3)_\mathcal{H}_n(w_4)| dw_1 dw_2 dw_3 dw_4 \\
\leq O\left(\frac{1}{N^2 T^3}\right) \sum_{n_1=1}^{d} \sum_{n_2=0}^{d} \sum_{N=1}^{T} \sum_{i=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \frac{1}{d_{i,t_2}} \frac{1}{d_{i,t_3}} \frac{1}{d_{i,t_4}} \\
\cdot \int |\phi_n(w)|^2 \left(\int |\mathcal{H}_n(w)| dw\right)^2 \\
\leq O\left(\frac{1}{NT}\right) \sum_{n_2=0}^{d} n_2^{5/6} \leq O\left(\frac{k^2}{NT}\right) = o(1),
\]
where the last line follows from (8) of Lemma B.1, \(\phi_n(w)\) being integrable function on \(\mathbb{R}\) for \(n = 1, \ldots, d\) and Assumption 2.2.

For \(B_{2112}\), without losing generality, assume that \(t_1 = t_2 > t_3 > t_4\). For other cases, for example \(t_1 = t_3 > t_2 > t_4\), the analysis will be even simpler and the order will remain same. Then write
and Assumption 2.2.

where the last line follows from (8) of Lemma B.1, \( \phi_n(w) \) being integrable function on \( \mathbb{R} \) for \( n = 1, \ldots, d \) and Assumption 2.2.

For \( B_{2113} \), without losing generality, assume that \( t_1 = t_2 = t_3 > t_4 \). For other cases, for example \( t_1 = t_3 = t_4 > t_2 \), the analysis will be the same and the order will remain same. Then write

\[
\frac{1}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{N} \sum_{T} \sum_{t_1=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \left| E[\phi_{n_1}(u_{it_1}) \mathcal{H}_{n_2}(u_{it_1}) \phi_{n_1}(u_{it_3}) \mathcal{H}_{n_2}(u_{it_4})] \right|
\]

\[
\leq O \left( \frac{1}{N^2 T^3} \right) \sum_{n_1=1}^{d} \sum_{n_2=0}^{N} \sum_{T} \sum_{t_1=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \frac{1}{d_{t_1 t_3} d_{t_3 t_4} d_{t_4}}
\]

\[
\cdot \int \int \int \left| \phi_{n_1}(w_1) \mathcal{H}_{n_2}(w_1) \phi_{n_1}(w_2) \mathcal{H}_{n_2}(w_3) \right| dw_1 dw_2 dw_3
\]

\[
\leq O \left( \frac{1}{N T^{3/2}} \right) \sum_{n_1=1}^{d} \sum_{n_2=0}^{N} \left\{ \int \phi_{n_1}^2(w) dw \int \mathcal{H}_{n_2}(w) dw \right\}^{1/2} \int \phi_{n_1}(w) dw \int \mathcal{H}_{n_2}(w) dw
\]

\[
\leq O \left( \frac{k^2}{N T^{3/2}} \right) = o(1),
\]

where the last line follows from (8) of Lemma B.1 and \( \phi_n(w) \) being bounded uniformly, (8) of Lemma B.1 and Assumption 2.2.

For \( B_{2114} \), write

\[
B_{2114} = \frac{1}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{N} \sum_{T} \sum_{t_1=1}^{T} E[\phi_{n_1}^2(u_{it_1}) \mathcal{H}_{n_2}(u_{it_1})]
\]

\[
= \frac{1}{N^2 T^3} \sum_{n_1=1}^{d} \sum_{n_2=0}^{N} \sum_{T} \sum_{t_1=1}^{T} \int \phi_{n_1}^2(d_t w) \mathcal{H}_{n_2}(d_t w) f_t(w) dw
\]

\[
\leq O \left( \frac{1}{N^2 T^3} \right) \sum_{n_1=1}^{d} \sum_{n_2=0}^{N} \sum_{T} \sum_{t=1}^{T} \frac{1}{d_t} \int \phi_{n_1}^2(w) dw \leq O \left( \frac{k}{N T^{5/2}} \right) = o(1).
\]

Combining \( B_{2111}, B_{2112}, B_{2113} \) and \( B_{2114} \) together, we obtain that \( B_{211} = o(1) \).

For \( B_{212} \), write

\[
\left| E \left[ \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \phi_{n_1}(u_{it_1}) \mathcal{H}_{n_2}(u_{it_1}) \right] \right|
\]

\[
\leq \sum_{t=1}^{T} E[|\phi_{n_1}(u_{it}) \mathcal{H}_{n_2}(u_{it})|] + \sum_{t=2}^{T-1} \sum_{s=1}^{t-1} E[|\phi_{n_1}(u_{it}) \mathcal{H}_{n_2}(u_{is})|] + \sum_{t=2}^{T} \sum_{s=1}^{t-1} E[|\mathcal{H}_{n_2}(u_{it}) \phi_{n_1}(u_{is})|]
\]

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where the last line follows from Davydov inequality, Assumption 1.3 and (8) of Lemma B.1. Therefore,

$$|B_{212}| \leq O\left(\frac{1}{N^2T^3}\right) \sum_{n_1=1}^{N} \sum_{n_2=0}^{N} \sum_{j=1}^{T} \sum_{t_1}^{T} |E[v_{it_1,n_1} H_{n_2}(u_{it_2}) H_{n_2}(u_{jt_4})]|$$

$$= \frac{1}{N^2T^3} \sum_{n_1=1}^{N} \sum_{n_2=0}^{N} \sum_{i=1}^{T} \sum_{t_1}^{T} |E[v_{it_1,n_1} H_{n_2}(u_{it_2}) H_{n_2}(u_{jt_4})]|$$

$$= \frac{1}{N^2T^3} \sum_{n_1=1}^{N} \sum_{n_2=0}^{N} \sum_{i=1}^{T} \sum_{t_1}^{T} |E[v_{it_1,n_1} v_{it_3,n_1} H_{n_2}(u_{it_2}) H_{n_2}(u_{jt_4})]|$$

$$+ O\left(\frac{1}{N^2T^3}\right) \sum_{n_1=1}^{N} \sum_{n_2=0}^{N} \sum_{i=1}^{T} \sum_{t_1}^{T} |E[v_{it_1,n_1} v_{it_3,n_1} H_{n_2}(u_{it_2}) H_{n_2}(u_{jt_4})]|$$

$$\equiv B_{221} + 2B_{222}.$$
\[
\cdot \left( E[|v_{jt_3,n_1}|^{2+\delta/2}] \right)^{2/(4+\delta)} \sum_{t_2=1}^T \frac{1}{d_{t_2}} \int |\mathcal{N}_{t_2}(w)|dw \sum_{t_4=1}^T \frac{1}{d_{t_4}} \int |\mathcal{N}_{t_4}(w)|dw \\
\leq C \left( \frac{1}{N^{2T^2}} \right)^{k-1} \sum_{n_2=0}^{N/6} n_2^5 \sum_{i=2}^{N} \sum_{j=1}^{i-1} \sum_{T} \sum_{T} (\alpha_{ij}(|t_1 - t_2|))^{\delta/(4+\delta)} \leq O \left( \frac{k^2}{NT} \right) = o(1),
\]

where the second inequality follows from Davydov inequality and \( c_\delta = 2^{(4+2\delta)/(4+\delta)} \cdot (4 + \delta)/\delta; \) the third inequality follows from Assumption 1.3 and (8) of Lemma B.1.

Since \(|B_{221}| = o(1)\) and \(|B_{222}| = o(1)\), we know that \( B_{22} = o_P(1)\).

Based on the analysis for \( B_1, B_{21} \) and \( B_{22} \), the result follows.

3)

\[
\frac{1}{NT} X'E = \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \left( \phi(u_{it}) + v_{it} \right) e_{it} - \frac{1}{NT^2} \sum_{i=1}^N \sum_{t=1}^T \sum_{s=1}^T e_{ist} = C_1 - C_2.
\]

Expand \( C_1 \) as

\[
C_1 = \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \phi(u_{it}) e_{it} + \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T v_{it} e_{it} = C_{11} + C_{12}.
\]

We have shown that \( C_{11} = O_P \left( \frac{1}{\sqrt{NT}} \right) \) in (7) of Lemma B.2. Moreover, by Assumption 1.3.b

\[
E[|C_{12}|^2] = \frac{1}{N^{2T^2}} \sum_{n=1}^d \sum_{i=1}^N \sum_{j=1}^N \sum_{T} \sum_{T} E[v_{it,n}v_{jt,n}E[e_{ist}^{ijt} \mathcal{F}_{Nt-1}]] = O \left( \frac{1}{NT^2} \right).
\]

Thus, \( C_{12} = O_P \left( \frac{1}{\sqrt{NT^2}} \right) \). In connection with \( C_{11} = O_P \left( \frac{1}{\sqrt{NT}} \right) \), we obtain \( C_1 = O_P \left( \frac{1}{\sqrt{NT}} \right) \).

Then we focus on \( C_2 \) below and write

\[
C_2 = \frac{1}{NT^2} \sum_{i=1}^N \sum_{t=1}^T \sum_{s=1}^T \phi(u_{it}) e_{is} + \frac{1}{NT^2} \sum_{i=1}^N \sum_{t=1}^T v_{it} e_{is} = C_{21} + C_{22}.
\]

For \( C_{21} \),

\[
E[|C_{21}|^2] = \frac{1}{N^{2T^3}} \sum_{n=1}^d \sum_{i=1}^N \sum_{t=1}^T \sum_{i=1}^T E[\phi_n^2(u_{it})] \sum_{s=1}^T E[e_{is}^2] \\
+ \frac{2}{N^{2T^3}} \sum_{n=1}^d \sum_{i=1}^N \sum_{t=1}^T \sum_{t_2=1}^T E[\phi_n(u_{it_1}) \phi_n(u_{it_2})] \sum_{s=1}^T E[e_{is}^2] \\
+ \frac{2}{N^{2T^3}} \sum_{n=1}^d \sum_{i=1}^N \sum_{t=1}^T \sum_{t_2=1}^T E[\phi_n(u_{it_1}) \phi_n(u_{jt_2})] \sum_{s=1}^T E[e_{is}^2]
\equiv C_{211} + C_{212} + C_{213}.
\]

For \( C_{211} \),

\[
C_{211} = O \left( \frac{1}{N^{2T^3}} \right) \sum_{n=1}^d \sum_{i=1}^N \sum_{t=1}^T \int \phi_n^2(d_{t}w) f_{t}(w) dw \leq O \left( \frac{1}{NT^3} \right) \sum_{n=1}^d \sum_{t=1}^T \frac{1}{dT} \int \phi_n^2(w) dw
\]
where the last inequality follows from $f_{t_1t_2}(w)$ and $f_{t_2}(w)$ being bounded uniformly and $\phi_n(w)$ being integrable for $n = 1, \ldots, d$.

For $C_{211}$, note that

$$|C_{211}| \leq O\left(\frac{1}{NT^2}\right) \sum_{n=1}^{d} \sum_{T_1=1}^{T} \sum_{T_2=1}^{T} \sum_{t_1=2}^{N} \sum_{t_2=1}^{t_1-1} |E[\phi_n(u_{it_1})]E[\phi_n(u_{jt_2})]| \cdot |\sigma_e(i, j)|$$

$$\leq O\left(\frac{1}{NT^2}\right) \sum_{n=1}^{d} \sum_{T_1=1}^{T} \sum_{T_2=1}^{T} \sum_{t_1=2}^{N} \sum_{t_2=1}^{t_1-1} \frac{1}{d_{t_1}d_{t_2}} \int |\phi_n(w)|dw \cdot \frac{1}{d_{t_2}} \int |\phi_n(w)|dw \cdot |\sigma_e(i, j)|$$

$$\leq O\left(\frac{1}{NT^2}\right) \sum_{n=1}^{d} \sum_{T_1=1}^{T} \sum_{t_1=2}^{N} \sum_{t_2=1}^{t_1-1} \sum_{i=2}^{N} \sum_{j=1}^{t_1-1} |\sigma_e(i, j)| = O\left(\frac{1}{NT^2}\right) = o\left(\frac{1}{NT}\right),$$

where the last line follows form $f_{t_1t_2}(w)$ and $f_{t_2}(w)$ being bounded uniformly, $\phi_n(w)$ being integrable for $n = 1, \ldots, d$ and Assumption 1.3.b.

Since $|C_{211}| = o\left(\frac{1}{NT}\right), |C_{212}| = o\left(\frac{1}{NT}\right)$ and $|C_{213}| = o\left(\frac{1}{NT}\right)$, we obtain that $C_{21} = o_P\left(\frac{1}{\sqrt{NT}}\right)$.

By Assumption 1.3.c, it is straightforward to obtain that

$$E\|C_{22}\|^2 = \frac{1}{NT^2} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E[v_{i,t_1}e_{i,t_2}v_{j,t_3}e_{j,t_4}] = O\left(\frac{1}{NT^2}\right).$$

Thus, $C_{22} = o_P\left(\frac{1}{\sqrt{NT}}\right)$. Since $C_{21} = o_P\left(\frac{1}{\sqrt{NT}}\right)$ and $C_{22} = o_P\left(\frac{1}{\sqrt{NT}}\right)$, then we have $C_2 = o_P\left(\frac{1}{\sqrt{NT}}\right)$. In connection with that $C_1 = O_P\left(\frac{1}{\sqrt{NT}}\right)$, the result follows.

4)

$$\frac{1}{NT}X'\gamma = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (\phi(u_{it}) + v_{it})\gamma_k(u_{it}) - \frac{1}{NT^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\phi(u_{it}) + v_{it})\gamma_k(u_{is}) \equiv D_1 - D_2$$

By (8) and (9) of Lemma B.2, $D_1 = O_P\left(\frac{1}{\sqrt{NT}}\right)$ follows immediately. $D_2$ can be expanded as

$$D_2 = \frac{1}{NT^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \phi(u_{it})\gamma_k(u_{is}) + \frac{1}{NT^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} v_{it}\gamma_k(u_{is}) \equiv D_{21} + D_{22}.$$
\[ \|D_{21}\| \leq \frac{1}{NT^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \phi(u_{it}) \gamma_k(u_{is}) \leq O(1) \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} |\gamma_k(u_{it})|, \]

where the second inequality follows from \( \phi_n(w) \) being bounded uniformly for \( n = 1, \ldots, d \). For the summation on RHS above,

\[
E \left| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \gamma_k(u_{it}) \right|^2 = \frac{1}{N^2T^2} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} E[|\gamma_k(u_{it})||\gamma_k(u_{js})|] \\
= \frac{1}{N^2T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} E[\gamma_k(u_{it})]^2 + \frac{2}{N^2T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} E[|\gamma_k(u_{it})||\gamma_k(u_{is})|] \\
+ \frac{2}{N^2T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{j=1}^{T} \sum_{s=1}^{T} E[|\gamma_k(u_{it})||\gamma_k(u_{js})|] \\
\leq O \left( \frac{1}{N^2T^2} \right) \sum_{i=1}^{N} \sum_{t=1}^{T} \frac{1}{dt} \int \gamma_k^2(w) dw \\
+ O \left( \frac{1}{N^2T^2} \right) \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \int \gamma_k(w)^2 dw \left\{ \int f_t^2(w) dw \right\}^{1/2} \left\{ \int f_s^2(w) dw \right\}^{1/2} \\
+ O \left( \frac{1}{N^2T^2} \right) \sum_{t=1}^{N} \sum_{j=1}^{T} \sum_{s=1}^{T} \frac{1}{dt} \int \gamma_k(w)^2 dw \left\{ \int f_t^2(w) dw \right\}^{1/2} \left\{ \int f_s^2(w) dw \right\}^{1/2} \\
\leq O \left( \frac{1}{NT^{3/2}} \right) + O \left( \frac{k^{-m}}{NT} \right) + O \left( \frac{k^{-m}}{T} \right), \tag{C.6} \]

where the first inequality follows from \( f_t(w) \) being bounded uniformly and Cauchy–Schwarz inequality; the second inequality follows from (3) of Lemma B.1 and \( f_t(w) \) and \( f_s(w) \) being bounded uniformly.

Then we have shown that \( D_{21} = O_P \left( \frac{1}{\sqrt{k^{m-1}}} \right) \).

We now focus on \( D_{22} \).

\[
E\|D_{22}\|^2 = \frac{1}{N^2T^4} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E[v_{it_1}v_{jt_3}v_{jt_4}] E[\gamma_k(u_{it_2})\gamma_k(u_{jt_4})] \\
\leq O(1) \frac{1}{N^2T^2} \sum_{n=1}^{d} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_2=1}^{T} \sum_{t_4=1}^{T} |E[\gamma_k(u_{it_2})\gamma_k(u_{jt_4})]| \leq O \left( \frac{k^{-m}}{T} \right),
\]

where the first equality follows from Assumption 1.4; the first inequality follows from Assumption 1.3.a; the second inequality follows from (C.6). Then \( D_{22} = O_P \left( \frac{1}{\sqrt{k^{m-1}}} \right) \).

Based on the above, the result follows. \[ \blacksquare \]

5)

\[
\frac{1}{N \sqrt{T}} Z' \gamma = \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} Z_k(u_{it}) \gamma_k(u_{it}) - \frac{\sqrt{T}}{N} \sum_{i=1}^{N} Z_{k,i} \bar{\gamma}_{k,i} = E_1 - E_2
\]

In (1) of Lemma B.2, we have shown that \( \|E_1\| = O_P(k^{-(m-1)/2}) \). Then we just need to focus on \( E_2 \) below and write
\[ \|E_2\| \leq \frac{1}{N T^{3/2}} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \|Z_k(u_{it}) \gamma_k(u_{is})\| \leq O(k^{1/2}) \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} |\gamma_k(u_{it})|, \]

where the second inequality follows from (6) of Lemma B.1. In (C.6) of this lemma, we have shown that \( \frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} |\gamma_k(u_{it})| = O_P \left( \frac{k^{-m/2}}{\sqrt{T}} \right) \), so we easily obtain \( \frac{1}{N \sqrt{T}} \sum_{i=1}^{N} \sum_{t=1}^{T} |\gamma_k(u_{it})| = O_P \left( k^{-m/2} \right) \). Based on the above, it further implies that \( \|E_2\| = O_P(k^{-(m-1)/2}) \). Then the result follows. \[ \blacksquare \]

6) For the first result, write
\[
\frac{1}{N T} X'X = \frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} (\phi(u_{it}) + v_{it})(\phi(u_{it}) + v_{it})' - \frac{1}{N T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} (\phi(u_{it}) + v_{it})(\phi(u_{is}) + v_{is})' \equiv F_1 - F_2.
\]

By going a procedure similar to (C.6), it is easy to show that
\[
\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} \phi(u_{it})\phi(u_{it})' \to_P 0.
\]

In connection with (4) and (5) of Lemma B.2, we obtain that \( F_1 \to_P \Sigma_u \) immediately.

We just need to focus on \( F_2 \) below.

\[
F_2 = \frac{1}{N T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \phi(u_{it})\phi(u_{is})' + \frac{1}{N T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} \phi(u_{it})v_{is}'
\]
\[
+ \frac{1}{N T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} v_{it}\phi(u_{is})' + \frac{1}{N T^2} \sum_{i=1}^{N} \sum_{t=1}^{T} \sum_{s=1}^{T} v_{it}v_{is}'
\]
\[
\equiv F_{21} + F_{22} + F_{23} + F_{24}.
\]

Notice that \( F_{24} = o_P(1) \) follows from Assumption 1.3.c straightaway. We then focus on \( F_{21} \) below and write
\[
E\|F_{21}\|^2 = \frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{j=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})]
\]
\[
= \frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{j=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})]
\]
\[
+ \frac{2}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=2}^{N} \sum_{j=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})]
\]
\[
= F_{211} + 2F_{212}.
\]

For \( F_{211} \), write
\[
F_{211} = \frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{i=1}^{N} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})]
\]
\[
\begin{align*}
= \frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2,t_3,t_4} \sum_{t_3,t_4 = \text{different}} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})] \\
+ \frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2,t_3,t_4} \sum_{t_2,t_3,t_4 = \text{same}} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})] \\
+ \frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2,t_3,t_4} \sum_{t_2,t_3,t_4 = \text{same}} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})] \\
+ \frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2,t_3,t_4} \sum_{t_2,t_3,t_4 = \text{same}} E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})] \\
= F_{2111} + F_{2112} + F_{2113} + F_{2114}.
\end{align*}
\]

For \(F_{2111}\), without losing generality, assume that \(t_1 > t_2 > t_3 > t_4\). For other cases, for example \(t_2 > t_3 > t_1 > t_4\), the analysis will be same and the order will remain same. Then

\[
\begin{align*}
\frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} |E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})]| \\
\leq O\left(\frac{1}{N^2 T^4}\right) \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \frac{1}{d_{t_1} d_{t_2} d_{t_3} d_{t_4}} \\
\cdot \int \int \int \int |\phi_{n_1}(w_1)\phi_{n_2}(w_2)| \int |\phi_{n_1}(w_3)| \int |\phi_{n_2}(w_4)| d w_1 d w_2 d w_3 d w_4 \\
\leq O\left(\frac{1}{NT^2}\right) \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \left(\int |\phi_{n_1}(w)| d w\right)^2 \left(\int |\phi_{n_2}(w)| d w\right)^2 \leq O\left(\frac{1}{NT^2}\right) = o(1),
\end{align*}
\]

where the last inequality follows from \(\phi_n(w)\) being integrable for \(n = 1, \ldots, d\).

For \(F_{2112}\), without losing generality, assume that \(t_1 = t_2 > t_3 > t_4\). For other cases, for example \(t_1 = t_3 > t_2 > t_4\), the analysis will be even simpler and the order will remain same. Then write

\[
\begin{align*}
\frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2=1}^{T} \sum_{t_3=1}^{t_1-1} \sum_{t_4=1}^{t_1} |E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})]| \\
\leq O\left(\frac{1}{N^2 T^4}\right) \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2=1}^{T} \sum_{t_3=1}^{t_1-1} \sum_{t_4=1}^{t_1} \frac{1}{d_{t_1} d_{t_2} d_{t_3} d_{t_4}} \\
\cdot \int \int \int \int |\phi_{n_1}(w_1)\phi_{n_2}(w_2)| \int |\phi_{n_1}(w_3)| \int |\phi_{n_2}(w_3)| d w_1 d w_2 d w_3 d w_4 \\
\leq O\left(\frac{1}{NT^{5/2}}\right) \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \left\{ \int |\phi_{n_1}^2(w)| d w \int |\phi_{n_2}^2(w)| d w \right\}^{1/2} \int |\phi_{n_1}(w)| d w \int |\phi_{n_2}(w)| d w \\
\leq O\left(\frac{1}{NT^{5/2}}\right),
\end{align*}
\]

where the last line follows from \(\phi_n(w)\) being integrable and \(\phi_n(w) \in L^2(\mathbb{R})\) for \(n = 1, \ldots, d\).

For \(F_{2113}\), without losing generality, assume that \(t_1 = t_2 = t_3 > t_4\). For other cases, for example \(t_1 = t_3 = t_4 > t_2\), the analysis will be same and the order will remain same. Then write

\[
\begin{align*}
\frac{1}{N^2 T^4} \sum_{n_1=1}^{d} \sum_{n_2=1}^{d} \sum_{t_1=1}^{N} \sum_{t_2=1}^{T} \sum_{t_3=1}^{t_1-1} \sum_{t_4=1}^{t_1} |E[\phi_{n_1}(u_{it_1})\phi_{n_2}(u_{it_2})\phi_{n_1}(u_{it_3})\phi_{n_2}(u_{it_4})]| \\
\end{align*}
\]

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\[ \leq O \left( \frac{1}{N^{2}T^{4}} \right) \sum_{n_{1}=1}^{d} \sum_{n_{2}=1}^{d} N \sum_{t_{1}=1}^{T-1} \sum_{t_{4}=1}^{T} \frac{1}{d_{t_{1}t_{4}}} \cdot \int \phi_{n_{1}}(w_{1})\phi_{n_{2}}(w_{1})\phi_{n_{1}}(w_{1})\phi_{n_{2}}(w_{2})dw_{1}dw_{2} \]
\[ \leq O \left( \frac{1}{NT^{3}} \right) \sum_{n_{1}=1}^{d} \sum_{n_{2}=1}^{d} \int \phi_{n_{1}}^{2}(w)dw \int \phi_{n_{2}}(w)dw = O \left( \frac{1}{NT^{3}} \right), \]

where the last line follows from \( \phi_{n}(w) \) being integrable and \( \phi_{n}(w) \in L^{2}(\mathbb{R}) \) for \( n = 1, \ldots, d \).

For \( F_{2114} \), write
\[ F_{2114} = \frac{1}{N^{2}T^{4}} \sum_{n_{1}=1}^{d} \sum_{n_{2}=1}^{d} \sum_{t_{1}=1}^{N} \sum_{t_{4}=1}^{T} \int \phi_{n_{1}}^{2}(d_{t}w)\phi_{n_{2}}^{2}(d_{t}w)f_{t}(w)dw \]
\[ \leq O \left( \frac{1}{N^{2}T^{4}} \right) \sum_{i=1}^{N} \sum_{t=1}^{T} \frac{1}{d_{t}} \leq O \left( \frac{1}{NT^{7/2}} \right), \]

where the first inequality follows from \( \phi_{n}(w) \) being bounded uniformly and \( \phi_{n}(w) \in L^{2}(\mathbb{R}) \) for \( n = 1, \ldots, d \).

Combining \( F_{2111}, F_{2112}, F_{2113} \) and \( F_{2114} \) together, we obtain that \( F_{211} = o(1) \).

We now turn to \( F_{212} \) and write
\[ \left| E \left[ \sum_{t_{1}=1}^{T} \sum_{t_{2}=1}^{T} \phi_{n_{1}}(u_{it_{1}})\phi_{n_{2}}(u_{it_{2}}) \right] \right| \]
\[ \leq \sum_{t_{1}=1}^{T} E[|\phi_{n_{1}}(u_{it})\phi_{n_{2}}(u_{it})|] + \sum_{t_{2}=1}^{T} E[|\phi_{n_{1}}(u_{it})\phi_{n_{2}}(u_{is})|] + \sum_{t_{1}=1}^{T} \sum_{s=1}^{T-1} \frac{1}{d_{is}} \frac{1}{d_{is}} \int |\phi_{n_{1}}(w)|dw \]
\[ \leq O(1) \sum_{t_{1}=1}^{T} \frac{1}{d_{t}} \int |\phi_{n_{1}}(w)|dw + O(1) \sum_{t_{2}=1}^{T} \sum_{s=1}^{T-1} \frac{1}{d_{is}} \frac{1}{d_{is}} \int |\phi_{n_{1}}(w)|dw \]
\[ \leq O(1) \sqrt{T} + O(1)T = O(T), \]

where the last inequality follows from \( \phi_{n}(w) \) being integrable for \( n = 1, \ldots, d \). Therefore,
\[ |F_{212}| \leq O \left( \frac{1}{N^{2}T^{4}} \right) \sum_{n_{1}=1}^{d} \sum_{n_{2}=1}^{d} \sum_{t_{1}=1}^{T-1} T^{2} = o(1). \]

Since \( F_{211} = o(1) \) and \( F_{212} = o(1) \), we have shown that \( \|F_{21}\| = o_P(1) \). Similarly, we can show that \( \|F_{22}\| = o_P(1) \) and \( \|F_{23}\| = o_P(1) \). Therefore, the result follows.

Proof of Corollary 3.1:

We need only to verify the first result of this corollary. The second result then follows immediately.

1) By (6) of Lemma B.4, \( \tilde{\Sigma}_{v} = \frac{1}{NT}X'X \rightarrow_P \Sigma_{v} \). Thus, we just need to focus on \( \hat{\sigma}_{v}^{2} \), where
\[ \hat{\sigma}_{v}^{2} = \frac{1}{N} \sum_{i=1}^{N} \sum_{t=1}^{T} (\tilde{X}_{it}(\beta_{0} - \tilde{\beta}) + \tilde{Z}_{k}(u_{it})' (C - \tilde{C}) + \tilde{\gamma}_{k}(u_{it}) + \tilde{e}_{it})^2. \]
(C.7)
Now denote that $A_1 = \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T (\tilde{X}'_t(\hat{\beta} - \beta))^2$, $A_2 = \frac{1}{N^2} \sum_{i=1}^N \sum_{t=1}^T (\tilde{Z}_k(u_{it})'(C - \hat{C}))^2$, $A_3 = \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \tilde{\gamma}_k^2(u_{it})$ and $A_4 = \frac{1}{N^2} \sum_{i=1}^N \sum_{t=1}^T e_{it}^2$.

For $A_1$, write
$$|A_1| \leq \left\| \hat{\beta} - \beta \right\|^2 \cdot \left\| \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \tilde{X}_i \tilde{X}'_i \right\| = o_P(1),$$
where the last equality follows from Theorem 3.1 and (6) of Lemma B.4.

For $A_2$, write
$$|A_2| \leq \left\| C - \hat{C} \right\|^2 \cdot \frac{1}{\sqrt{T}} \left\| \frac{1}{N\sqrt{T}} \sum_{i=1}^N \sum_{t=1}^T \tilde{Z}_k(u_{it}) \tilde{Z}_k(u_{it})' \right\| = o_P(1),$$
where the last equality follows from Lemma 3.1, Lemma B.5 and Assumption 2.2.

For $A_3$, by (2) of Lemma B.1, $\frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \tilde{\gamma}_k^2(u_{it}) = O(k^{-m+5/6}) = o(1).

For $A_4$, write
$$A_4 = \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T e_{it}^2 - \frac{1}{NT^2} \sum_{i=1}^N \sum_{t=1}^T e_{it} e_{is} = A_{41} - A_{42}.$$

For $A_{41}$, Assumption 1.3.(b),
$$E \left[ A_{41}^2 - \sigma_e^2 \right]^2 = \frac{1}{N^2T^2} \sum_{i=1}^N \sum_{j=1}^N \sum_{t=1}^T \sum_{s=1}^T E((e_{it}^2 - \sigma_e^2)(e_{js}^2 - \sigma_e^2)) = o(1).$$

For $A_{42}$
$$E \left[ A_{42}^2 \right] = \frac{1}{N^2T^4} \sum_{i=1}^N \sum_{j=1}^N \sum_{t_1=1}^T \sum_{t_2=1}^T \sum_{t_3=1}^T \sum_{t_4=1}^T E(e_{it_1} e_{it_2} e_{jt_3} e_{jt_4}) = o(1),$$
where the RHS follows from $e_t$ being martingale difference sequence (c.f. Assumption 1.3.b).

Therefore, we have shown that $A_1 \to_P 0$, $A_2 \to_P 0$, $A_3 \to_P 0$ and $A_4 \to_P \sigma_e^2$. Based on the above, all the interaction terms generated by $\tilde{X}'_t(\beta_0 - \hat{\beta})$, $\tilde{Z}_k(u_{it})'(C - \hat{C})$ and $\tilde{\gamma}_k(u_{it})$ from the expansion of (C.7) can be shown converging to 0 in probability easily. For example,
$$\left\| \frac{2}{NT} \sum_{i=1}^N \sum_{t=1}^T \tilde{X}'_t(\beta_0 - \hat{\beta}) \tilde{Z}_k(u_{it})'(C - \hat{C}) \right\| \leq \frac{2}{NT} \sum_{i=1}^N \sum_{t=1}^T \left| \tilde{X}'_t(\beta_0 - \hat{\beta}) \right| \right\| \leq \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \left| \tilde{X}'_t(\beta_0 - \hat{\beta}) \right|^2 + \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \left| \tilde{Z}_k(u_{it})'(C - \hat{C}) \right|^2 = A_1 + A_2 = o_P(1).$$

We now focus on the interaction terms generated by $\tilde{e}_{it}$.

Firstly,
$$\left\| \frac{2}{NT} \sum_{i=1}^N \sum_{t=1}^T \tilde{X}'_t(\beta_0 - \hat{\beta}) \tilde{e}_{it} \right\| \leq \left\| \beta_0 - \hat{\beta} \right\| \cdot \left\| \frac{2}{NT} \sum_{i=1}^N \sum_{t=1}^T \tilde{X}'_t \tilde{e}_{it} \right\| = o_P(1),$$
where the last equality follows from Theorem 3.1 and (3) of Lemma B.4.
Secondly,

\[ \frac{2}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{Z}_k(u_{it})(C - \hat{C})\tilde{e}_{it} \leq \left\| C - \hat{C} \right\| \cdot \frac{2}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{Z}_k(u_{it})\tilde{e}_{it} = o_p(1), \]

where the last equality follows from Lemma 3.1 and (1) of Lemma B.4.

Thirdly, by similar approach to (9) of Lemma B.2,

\[ \frac{2}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{\gamma}_k(u_{it})\tilde{e}_{it} = o_p(1). \]

Therefore, based on the above, the result follows.

\[ \blacksquare \]

References


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With Cross-Sectional Dependence

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Abstract

In this paper, we consider a semiparametric single index panel data model with cross–sectional dependence, high–dimensionality and stationarity. Meanwhile, we allow fixed effects to be correlated with the regressors to capture unobservable heterogeneity. Under a general spatial error dependence structure, we then establish some consistent closed–form estimates for both the unknown parameters and a link function for the case where both $N$ and $T$ go to $\infty$. Rates of convergence and asymptotic normality consistencies are established for the proposed estimates. Our experience suggests that the proposed estimation method is simple and thus attractive for finite–sample studies and empirical implementations. Moreover, both the finite–sample performance and the empirical applications show that the proposed estimation method works well when the cross-sectional dependence exists in the data set.

Keywords: Asymptotic theory; closed-form estimate; nonlinear panel data model; orthogonal series method.

JEL classification: C13, C14, C23.
1 Introduction

Single-index models have been studied by both econometricians and statisticians in the past twenty years. These models include many classic parametric models (e.g. linear model or logistic model) by using a general function form $g(x'\beta)$ (see, for example, Chapter 2 of Gao (2007)). For nonlinear panel data models, the researcher starts introducing single–index panel data models (cf. Chen et al. (2013a) and Chen et al. (2013b)). For most of the published work on semiparametric single-index models, the estimation is based on a non-parametric kernel method, which may be sensitive to initial values due to the multi–modality or flatness of a curve in practice. Chen et al. (2013b) use this technique to investigate a partially linear panel data model with fixed effects and cross–sectional independence. In their paper, a consistent parameter estimator is achieved with convergence rate $\sqrt{NT}$, but, due to the identification requirements, they have to impose extra restrictions on the fixed effects. Alternatively, one can use sieve estimation techniques to implement a two-step procedure. Meanwhile, Su and Jin (2012) propose using sieve estimation techniques to a nonparametric multi–factor model, which is a nonparametric version of the parametric counterpart proposed in Pesaran (2006).

To the best of our knowledge, consistent closed–form estimates have not been established for this type of semiparametric single–index model in the literature. In this paper, we aim at establishing consistent closed–form estimates for a semiparametric single-index panel data model with both cross-sectional dependence and stationarity for the case where both $N$ and $T$ go to $\infty$. The estimation procedure proposed below allows us to avoid some computational issues and is therefore easy to implement. In this paper, we consider the stationary time series case. Non-stationary situations are much more complex and will be discussed in a companion paper. The estimation techniques proposed in this paper can also be extended to the multi–factor structure model. (Under certain restrictions similar to those of Su and Jin (2012), a semiparametric single–index extension can be achieved.) Furthermore, we add fixed effects to the model and do not impose any particular assumptions on them, so they can be correlated with the regressors to capture unobservable heterogeneity. Compared to Chen et al. (2013b), our set-up is more flexible on the fixed effects. Moreover, we avoid the issue about the curse of dimensionality through using a single–index form for the regressors.

In this paper, we assume that all the regressors and error terms can be cross–sectionally correlated. As covered in Assumption 1 of Section 3 below, we impose a general spatial correlation structure to link the cross-sectional dependence and stationary mixing condition together. As a result, some types of spatial error correlation can easily be covered by the
assumptions given in Section 3 (cf. Chen et al. (2012a) and Chen et al. (2012b)). This setup is more flexible than that considered by Chen et al. (2013b). As Andrews (2005) and Bai (2009) discuss, the common shocks (e.g. global finance crisis) exist in many economic phenomena and cause serious forecasting biases, and an important characteristic is that they induce a correlation among individuals. Thus, it is vital for us to have such models that can capture this type of “global” cross-sectional dependence.

In summary, this paper makes the following contributions:

1. It proposes a semiparametric single-index panel data model to simultaneously accommodate cross-sectional dependence, high-dimensionality, stationarity and unobservable heterogeneity;

2. It establishes simple and consistent closed-form estimates for both unknown parameters and link function, and the closed-form estimates are easy to implement in practice;

3. It establishes both rates of convergence and asymptotic normality results for the estimates under a general spatial error dependence structure; and

4. It evaluates the proposed estimation method and through using both simulated and real data examples.

The structure of this paper is as follows. Section 2 introduces our model and discusses the main idea. Section 3 constructs a closed-form estimate for a vector of unknown parameters of interest and introduces assumptions for the establishment of asymptotic consistency and normality results. In Section 4, we recover the unknown link function and evaluate the rate of convergence. In Section 5, we provide a simple Monte Carlo experiment and two empirical case studies by looking into UK’s climate data and US cigarettes demand. Section 6 concludes this paper with some comments. All the proofs are given in an appendix.

Throughout the paper, we will use the following notation: \( \otimes \) denotes the Kronecker product; \( \text{vec}(A) \) defines the vec operator that transforms a matrix \( A \) into a vector by stacking the columns of the matrix one underneath the other; \( I_k \) denotes an identity matrix with dimensions \( k \times k \); \( i_k \) denotes a \( k \times 1 \) one vector \( (1, \ldots, 1)' \); \( M_p = I_k - P(P'P)^{-1}P' \) denotes the project matrix generated by matrix \( P \) with dimensions \( k \times h \) and \( h \leq k \); \( A^- \) denotes the Moore-Penrose inverse of the matrix \( A \); \( P \stackrel{P}{\rightarrow} \) denotes converging in probability; \( D \rightarrow \) denotes converging in distribution; \( \| \cdot \| \) denotes the Euclidean norm; \( \lfloor a \rfloor \leq a \) means the largest integer part of \( a \).
2 Semiparametric Single-Index Panel Data Models

A semiparametric single–index panel data model is specified as follows:

\[ y_{it} = g(x'_{it}\theta_0) + \gamma_i + e_{it}, \quad i = 1, \ldots, N, \quad t = 1, \ldots, T, \tag{2.1} \]

where \( y_{it} \) is a scalar process, \( x_{it} \) is a \((d \times 1)\) explanatory variable, \( e_{it} \) is an error process and the link function \( g : \mathbb{R} \rightarrow \mathbb{R} \) is unknown. We use \( \gamma_i \)'s to capture fixed effects in this model, which are allowed to be correlated with the regressors. Under the current set-up, our main interests are to consistently estimate the vector of unknown parameters \( \theta_0 = (\theta_{01}, \ldots, \theta_{0d})' \) and link function \( g(\cdot) \) for the case where both \( N \) and \( T \) go to \( \infty \).

To ensure that identification requirements are satisfied (cf. Horowitz (2009) and Ichimura (1993)), we assume that \( \theta_0 \) belongs to a compact set \( \Theta \), \( \|\theta_0\| = 1 \) and \( \theta_{01} > 0 \). For the link function \( g(\cdot) \), we expand it by Hermite polynomials and approximate it by a linear combination of a finite number of basis functions from the expansion. As the number of basis functions increases, the proxy approaches the true function. By doing so, a nonparametric estimation is practically turned to a parametric one, so we need only to estimate \( \theta_0 \) and the coefficients of the basis functions simultaneously.

We now introduce the background of Hermite polynomials briefly and explain how to expand the link function. Hermite polynomial system \( \{H_m(w), \; m = 0, 1, 2, \ldots\} \) is a complete orthogonal system in a Hilbert space \( L^2(\mathbb{R}, \exp(-w^2/2)) \) and each element is denoted as

\[ H_m(w) = (-1)^m \cdot \exp \left( \frac{w^2}{2} \right) \cdot \frac{d^m}{dw^m} \exp \left( -\frac{w^2}{2} \right). \tag{2.2} \]

Since \( \int_{\mathbb{R}} H_m(w)H_n(w)\exp(-w^2/2)\,dw \) equals to \( m!\sqrt{2\pi} \) for \( m = n \) and 0 for \( m \neq n \) respectively, the normalised orthogonal system is denoted as \( \{h_m(w), \; m = 0, 1, 2, \ldots\} \), where \( h_m(w) = \frac{1}{\sqrt{m!\sqrt{2\pi}}} H_m(w) \).

Thus, for \( \forall g \in L^2(\mathbb{R}, \exp(-w^2/2)) \), we can express it in terms of \( h_m(w) \) as follows:

\[ g(w) = \sum_{m=0}^{\infty} c_m h_m(w) \quad \text{and} \quad c_m = \int_{\mathbb{R}} g(w) \cdot h_m(w) \cdot \exp \left( -\frac{w^2}{2} \right) \, dw. \tag{2.3} \]

Furthermore, \( h_m(w) \cdot \exp(-w^2/4) \) is bounded uniformly in \( w \in \mathbb{R} \) and \( m \) (cf. Nevai (1986)).

Based on the above expansion, one is already able to use a profile method or an iterative estimation method to estimate \( \theta_0 \) and the link function. Since neither of these two methods results in a closed form estimation method, numerical estimates are often sensitive to the initial values used in practice due to multi-modality or flatness of a curve. Instead, we
further expand $h(x_t', \theta_0)$ by Lemma 1 of the appendix as follows:

$$g(x_t', \theta_0) = \sum_{m=0}^{k-1} c_m h_m(x_t', \theta_0) + \sum_{m=k}^{\infty} c_m h_m(x_t', \theta_0)$$

$$= \sum_{m=0}^{k-1} \sum_{|p|=m} a_{mp}(\theta_0) \mathcal{H}_p(x_t) + \delta_k(x_t', \theta_0),$$

where

$$\delta_k(x_t', \theta_0) = \sum_{m=k}^{\infty} c_m h_m(x_t', \theta_0), \quad a_{mp} = \binom{m}{p} c_m \theta_0^p, \quad \binom{m}{p} = \frac{m!}{\prod_{j=1}^{d} p_j!},$$

$$\theta_0^p = \prod_{j=1}^{d} \theta_0^{p_j}, \quad \mathcal{H}_p(x_t) = \prod_{j=1}^{d} h_{p_j}(x_{it,j}), \quad x_t = (x_{it,1}, \ldots, x_{it,d})', \quad p = (p_1, \ldots, p_d)',$$

$$|p| = p_1 + \ldots + p_d$$ and $p_j$'s for $j = 1, \ldots, d$ are non-negative integers.

The expansion (2.5) allows us to separate the covariate $x_t$ and the coefficient $\theta_0$, so the closed form estimator can be established from it. The term $\delta_k(x_t', \theta_0)$ can be considered as a truncated error term, which goes to zero as $k$ increases. Since each $h_m(w) \cdot \exp(-w^2/4)$ is bounded uniformly in $w \in \mathbb{R}$ and $m$, $\mathcal{H}_p(x) \cdot \exp(-\|x\|^2/4)$ must be bounded uniformly in $x \in \mathbb{R}^d$ and $p$.

To further investigate the model, we now define an ordering relationship with respect to $p$ in (2.5).

**Definition 1** Let $P_m = \{p : |p| = m\}$, where $m$ is a non-negative integer. Suppose that $\hat{p}, \tilde{p} \in P_m$. We say $\hat{p} = (\hat{p}_1, \ldots, \hat{p}_d) < \tilde{p} = (\tilde{p}_1, \ldots, \tilde{p}_d)$ if $\hat{p}_j = \tilde{p}_j$ for all $j = 1, \ldots, l - 1$ and $\hat{p}_l < \tilde{p}_l$, where $1 < l \leq d$.

Based on Definition 1, we list all the $\mathcal{H}_p(x_t)$’s on the descending order with respect to $|p| = m$ for each $m = 0, 1, \ldots, k - 1$ below.

- As $m = 0$,

$$p = (0, 0, \ldots, 0)', \quad \mathcal{H}_p(x_t) = h_0(x_{it,1}) h_0(x_{it,2}) \cdots h_0(x_{it,d}) = 1, \quad a_{0p}(\theta_0) = c_0.$$


As $m = 1$,

\[
p = (1, 0, \ldots, 0)', \quad \mathcal{H}_p (x_{it}) = h_1 (x_{it,1}) h_0 (x_{it,2}) \cdots h_0 (x_{it,d}) = x_{it,1},
\]
\[
a_{1p} (\theta_0) = c_1 \theta_{01};
\]

\[
p = (0, 1, \ldots, 0)', \quad \mathcal{H}_p (x_{it}) = h_0 (x_{it,1}) h_1 (x_{it,2}) \cdots h_0 (x_{it,d}) = x_{it,2},
\]
\[
a_{1p} (\theta_0) = c_1 \theta_{02};
\]

\[\vdots\]

\[
p = (0, 0, \ldots, 1)', \quad \mathcal{H}_p (x_{it}) = h_0 (x_{it,1}) h_0 (x_{it,2}) \cdots h_1 (x_{it,d}) = x_{it,d},
\]
\[
a_{1p} (\theta_0) = c_1 \theta_{0d}.
\]

As $m = 2, \ldots, k - 1$,

\[
p = (m, 0, \ldots, 0)', \quad \mathcal{H}_p (x_{it}) = h_m (x_{it,1}) h_0 (x_{it,2}) \cdots h_0 (x_{it,d}) = h_m (x_{it,1}),
\]
\[
a_{mp} (\theta_0) = c_m \theta_{01}^m;
\]

\[
p = (m - 1, 1, 0, \ldots, 0)', \quad \mathcal{H}_p (x_{it}) = h_{m-1} (x_{it,1}) h_1 (x_{it,2}) h_0 (x_{it,3}) \cdots h_0 (x_{it,d})
\]
\[= h_{m-1} (x_{it,1}) h_1 (x_{it,2}),
\]
\[
a_{mp} (\theta_0) = m c_m \theta_{01}^{m-1} \theta_{02};
\]

\[\vdots\]

\[
p = (0, 0, \ldots, m)', \quad \mathcal{H}_p (x_{it}) = h_0 (x_{it,1}) h_0 (x_{it,2}) \cdots h_m (x_{it,d}) = h_m (x_{it,d}),
\]
\[
a_{mp} (\theta_0) = c_m \theta_{0d}^m.
\]

Note that, by (2.6), it is easy to know that the first $\mathcal{H}_p(x_{it})$ in (2.5) is constant one and its coefficient is constant $c_0$. The second to the $(d + 1)^{th}$ $\mathcal{H}_p(x_{it})$'s in (2.5) are simply $x_{it}$ with coefficients $c_1 \theta_0$ shown in (2.7) and will be used to recover the interest parameter $\theta_0$ later on.

Accordingly, it allows us to denote the next two vectors to shorten notation:

\[
Z (x_{it}) = (Z_1 (x_{it})', \ldots, Z_{k-1} (x_{it})')' \quad \text{and} \quad \beta = (A_1 (\theta_0)', \ldots, A_{k-1} (\theta_0)')',
\]

where, for $m = 1, \ldots, k - 1$, $Z_m(x_{it})$'s are column vectors consisting of all $\mathcal{H}_p(x_{it})$'s arranged on descent ordering with respect to $|p| = m$ and $A_m(\theta_0)$ are column vectors consisting of all corresponding $a_{mp}(\theta_0)$. Notice that we have suppressed the notation $\theta_0$ in $\beta$ for simplicity. Thus, we can rewrite the model (2.1) as

\[
y_{it} = c_0 + H (x_{it}' \beta) + \delta_k (x_{it}' \theta_0) + \gamma_i + e_{it}
\]
\[= c_0 + Z (x_{it})' \beta + \delta_k (x_{it}' \theta_0) + \gamma_i + e_{it},
\]
where \( c_0 = a_{0p}(\theta_0) \), \( \mathcal{C} = (c_1, c_2, \ldots, c_{k-1})' \) and \( H(w) = (h_1(w), h_2(w), \ldots, h_{k-1}(w))' \) for \( w \in \mathbb{R} \).

Moreover, it is easy to check that the cardinality of \( P_m \) is \( \binom{m+d-1}{d-1} \), so the length of the vector \( Z(x_{it}) \) is

\[
K = \sum_{m=1}^{k-1} \#P_m = \frac{(d + k - 1)!}{d!(k - 1)!} - 1 = O\left(k^d\right).
\] (2.9)

Then, we may write \( Z(x_{it}) \) as

\[
Z(x_{it}) = (Z_1(x_{it})', \ldots, Z_{k-1}(x_{it})')' = (z_1(x_{it}), \ldots, z_K(x_{it}))',
\]

where \( z_u(x_{it})'s \) for \( u = 1, \ldots, K \) are \( \mathcal{H}_p(x_{it})'s \)'s in (2.7) and (2.8) in the exactly same order.

To remove the fixed effects, we introduce the following notation:

\[
\bar{y}_i = \frac{1}{T} \sum_{t=1}^{T} y_{it}, \quad \bar{H}_i(\theta_0) = \frac{1}{T} \sum_{t=1}^{T} H(x'_{it}\theta_0), \quad \bar{Z}_i = \frac{1}{T} \sum_{t=1}^{T} Z(x_{it}),
\]

\[
\delta_{k,i}(\theta_0) = \frac{1}{T} \sum_{t=1}^{T} \delta_k(x'_{it}\theta_0), \quad \bar{e}_i = \frac{1}{T} \sum_{t=1}^{T} e_{it},
\]

\[
\bar{y}_{it} = y_{it} - \bar{y}_i, \quad \bar{H}_{it}(\theta_0) = H(x'_{it}\theta_0) - \bar{H}_i(\theta_0), \quad \bar{Z}_{it} = Z(x_{it}) - \bar{Z}_i,
\]

\[
\bar{\delta}_k(x_{it}\theta_0) = \delta_k(x'_{it}\theta_0) - \bar{\delta}_{k,i}(\theta_0), \quad \bar{e}_{it} = e_{it} - \bar{e}_i,
\]

and then eliminate \( \gamma_i's \) by the within–transformation. The model now becomes

\[
\bar{y}_{it} = \bar{H}_{it}(\theta_0)'\mathcal{C} + \bar{\delta}_k(x'_{it}\theta_0) + \bar{e}_{it}
\]

\[
= \bar{Z}_{it}'\beta + \bar{\delta}_k(x'_{it}\theta_0) + \bar{e}_{it}.
\]

Alternatively, we can express the model in matrix forms as

\[
(I_N \otimes M_{it}) \mathcal{Y} = (I_N \otimes M_{it}) \mathcal{H}(\theta_0) \mathcal{C} + (I_N \otimes M_{it}) \mathcal{D}(\theta_0) + (I_N \otimes M_{it}) \mathcal{E} \quad \text{(2.10)}
\]

\[
= (I_N \otimes M_{it}) \mathcal{Z}\beta + (I_N \otimes M_{it}) \mathcal{D}(\theta_0) + (I_N \otimes M_{it}) \mathcal{E}, \quad \text{(2.11)}
\]

where

\[
\mathcal{Y}_{NT \times 1} = (y_{11}, \ldots, y_{1T}, \ldots, y_{N1}, \ldots, y_{NT})',
\]

\[
\mathcal{H}(\theta)_{NT \times (k-1)} = (H(x'_{11}\theta), \ldots, H(x'_{1T}\theta), \ldots, H(x'_{N1}\theta), \ldots, H(x'_{NT}\theta))' \quad \text{for } \forall \theta \in \Theta,
\]

\[
\mathcal{D}(\theta)_{NT \times 1} = (\delta_k(x'_{11}\theta), \ldots, \delta_k(x'_{1T}\theta), \ldots, \delta_k(x'_{N1}\theta), \ldots, \delta_k(x'_{NT}\theta))' \quad \text{for } \forall \theta \in \Theta,
\]

\[
\mathcal{Z}_{NT \times K} = (Z(x_{11}), \ldots, Z(x_{1T}), \ldots, Z(x_{N1}), \ldots, Z(x_{NT}))',
\]

\[
\mathcal{E}_{NT \times 1} = (e_{11}, \ldots, e_{1T}, \ldots, e_{N1}, \ldots, e_{NT})'.
\]
Notice that $c_0$ is a constant, so it is also removed by the within–transformation. It indicates that one can only identify the unknown function $g(\cdot)$ up to a constant through (2.10)-(2.11). To estimate the location, extra assumptions are needed (e.g. Assumption 1.ix in Su and Jin (2012)). In the next section, we will recover the interest parameter $\theta_0$ by (2.11). After that, we will bring a consistent estimate for $\theta_0$ back to (2.10) and recover the link function in section 4.

3 Estimation of Parameter $\theta_0$

We consider a within–ordinary least squares (OLS) estimator of $\beta$:

$$\hat{\beta} = [Z'(I_N \otimes M_{i_T}) Z]^{-1} Z'(I_N \otimes M_{i_T}) Y.$$  \hspace{1cm} (3.1)

To simplify the notation, for each time series $\{x_{i1}, \ldots, x_{iT}\}$, let $Q_{1,i} = E[Z(x_{it}) Z(x_{it})']$ and $q_i = E[Z(x_{it})]$. Also, denote that $Q_1 = \frac{1}{N} \sum_{i=1}^{N} Q_{1,i}$, $\bar{q} = \frac{1}{N} \sum_{i=1}^{N} q_i$ and $Q_2 = \frac{1}{N} \sum_{i=1}^{N} q_i q_i'$. Moreover, for $t = 1, \ldots, T$, let $x_t = (x_{1t}, \ldots, x_{Nt})'$ and $e_t = (e_{1t}, \ldots, e_{Nt})'$.

We now are ready to introduce the following assumptions. Specifically, we do not impose any assumption on the fixed effects in this paper, so they can be correlated with the regressors to capture unobservable heterogeneity.

**Assumption 1 (Covariates and errors):**

i. Let $E[e_{it}] = 0$ for all $i \geq 1$ and $t \geq 1$. Suppose that $\{x_t, e_t : t \geq 1\}$ is strictly stationary and $\alpha$-mixing. Let $\alpha_{ij}(|t - s|)$ represent the $\alpha$-mixing coefficient between $\{x_{it}, e_{it}\}$ and $\{x_{js}, e_{js}\}$. Let the $\alpha$-mixing coefficients satisfy

$$\sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{\infty} (\alpha_{ij}(t))^{\eta/(4+\eta)} = O(N) \quad \text{and} \quad \sum_{i=1}^{N} \sum_{j=1}^{N} (\alpha_{ij}(0))^{\eta/(4+\eta)} = O(N),$$

where $\eta > 0$ is chosen such that $E[|e_{it}|^{4+\eta}] < \infty$ and $E[||x_{it}||^{4+\eta}] < \infty$.

ii. Suppose that $x_{it}$ is independent of $e_{js}$ for all $i, j \geq 1$ and $t, s \geq 1$.

Assumption 1.i entails that only the stationary cases are considered in this paper. The nonstationary cases are more complex and will be discussed in a companion paper. We use the $\alpha$-mixing coefficient to measure the relationship between $\{x_{it}, e_{it}\}$ and $\{x_{js}, e_{js}\}$. This set-up is in spirit the same as Assumption A2 of Chen et al. (2012a) and Assumption C of Bai (2009). Since the mixing properties are hereditary, it allows us to avoid imposing restrictions on the functions by doing so. Thus, all the cross-sectional dependences and time
series properties are captured by the mixing coefficients. Particularly, \( \alpha_{ij}(0) \) only measures the cross-sectional dependence between \( \{x_{it}, e_{it}\} \) and \( \{x_{jt}, e_{jt}\} \).

We now use the factor model structure as an example to show that Assumption 1.i is verifiable. Suppose that \( e_{it} = \gamma_i f_t + \varepsilon_{it} \), where all variables are scalars and \( \varepsilon_{it} \) is independent and identically distributed (i.i.d.) across \( i \) and \( t \) with mean zero. Simple algebra shows that the coefficient \( \alpha_{ij}(|t-s|) \) reduces to \( \alpha_{ij} \cdot b(|t-s|) \), in which \( \alpha_{ij} = E[\gamma_i \gamma_j] \) and \( b(|t-s|) \) is the \( \alpha \)-mixing coefficient of the factor time series \( \{f_1, \ldots, f_T\} \). If \( f_t \) is strictly stationary \( \alpha \)-mixing process and \( \gamma_i \) is i.i.d. or a m-dependent sequence (cf. Appendix A of Gao (2007) Definition 9.1 and Theorem 9.1 in DasGupta (2008)), Assumption 1.i can easily be verified. More details and useful empirical examples can be found under Assumption A2 in Chen et al. (2012a).

**Assumption 2 (Identifications):**

i. Let \( \Theta \) be a compact subset of \( \mathbb{R}^d \) and \( \theta_0 \in \Theta \) be in the interior of \( \Theta \). Moreover, \( \|\theta_0\| = 1 \) and \( \theta_{01} > 0 \).

ii. \( E[\varphi'(x_{it}^\prime \theta_0)] = 0 \) for all \( i \geq 1 \) and \( t \geq 1 \). Moreover, for the same \( \eta \) in Assumption 1, let \( E[\|\varphi'(x_{it}^\prime \theta_0)\|^{2+\eta/2}] < \infty \).

Assumption 2.i is a standard identification requirement. Instead one can follow Ichimura (1993) to assume \( \theta_{01} = 1 \). However, by doing so, it seems to be hard to decide which variable should be considered as constant one in practice. Assumption 2.ii is not really necessary when the main interests are only estimating the parameter \( \theta_0 \) and measuring the changes in output \( y \). Assumption 2.ii kicks in only if the location of a curve needs to be estimated. In practice, the true expectation of \( E[\varphi'(x_{it}^\prime \theta_0)] \) may not be zero, so Assumption 2.ii essentially means that one is estimating \( \varphi'(x_{it}^\prime \theta_0) - E[\varphi'(x_{it}^\prime \theta_0)] \) rather than the true \( \varphi'(x_{it}^\prime \theta_0) \) (cf. Su and Jin (2012)). An example is given in a Monte Carlo study for illustration.

**Assumption 3 (Boundaries):**

i. Let the smallest eigenvalue of the \( K \times K \) matrix \( (Q_1 - Q_2) \) be uniformly bounded away from zero, such that \( \lambda_{\min}(Q_1 - Q_2) > 0 \) uniformly.

ii. (1) There exists \( r > 0 \) such that \( \sup_{0 \leq \varepsilon \leq 1} \sup_{\|\theta - \theta_0\| \leq \varepsilon} \max_{i \geq 1} E[\delta_k^2(x_{it}^\prime \theta)] = o(k^{-r}) \).

(2) \( \max_{i \geq 1} E[|H_k(x_{it}^\prime)|^{4+\eta}] = O(|p|^d) \) as \( |p| \to \infty \), where \( |p| \) is given under (2.5).

iii. \( \frac{k^d}{NT} \to 0 \) and \( \frac{k^{d/2}}{T} \to 0 \) as \( N, T, k \to \infty \) jointly.
Assumption 3.i can be verified by carrying on a similar procedure to Lemma A.2 in Gao et al. (2002) and it is also similar to Assumption 2 in Newey (1997) and Assumption 3.iv in Su and Jin (2012).

Assumption 3.ii is similar to Assumptions 2.ii and 3 in Newey (1997) and the second condition of this assumption is more general than Assumption 3.iv in Su and Jin (2012). By the argument under Assumption 2 in Newey (1997), it is not possible to assume $H_p(x_{i1})$ is bounded uniformly. Therefore, we put restrictions on the moments of the basis functions. Compared to putting the bounds on the basis power series directly of Newey (1997), we believe our current assumption is more realistic. Also, the second condition in our Assumption 3.ii clearly allows $x_{it}$ to follow the standard multivariate normal distribution, which is ruled out by Assumption 3.iv in Su and Jin (2012) for the cases where the basis functions are the Hermite polynomials. More relevant discussions will be given under Theorem 1.

We now illustrate that it is verifiable by the following example:

Suppose that we consider the second condition in Assumption 3.ii and \{x_{i1}, \ldots, x_{iT}\} has the standard multivariate normal density for $i \geq 1$. Let $\eta$ be large enough (say $\eta = 1$ without losing generality) and $x = (x_1, \ldots, x_d)$. Then

$$E \left[ |H_p(x_{i1})|^5 \right] = \int_{\mathbb{R}^d} |H_p(x)|^5 \cdot \exp(-\|x\|^2/2) dx.$$ 

Note $|H_p(x)|^5 = |h_{p_1}(x_1) \cdots h_{p_d}(x_d)|^5$, so expand it as $|H_p(x)|^5 = \left| \prod_{j=1}^d \sum_{s_j=0}^{5p_j} b_{sj} h_{sj}(x_j) \right|$, which gives that

$$\int_{\mathbb{R}^d} |H_p(x)|^5 \cdot \exp(-\|x\|^2/2) dx \leq \prod_{j=1}^d \sum_{s_j=0}^{5p_j} |b_{sj}| \int_{\mathbb{R}} |h_{sj}(x_j)| \exp \left( -x_j^2/4 \right) \cdot \exp \left( -x_j^2/4 \right) dx$$

$$\leq \prod_{j=1}^d C_1 \sum_{s_j=0}^{5p_j} |b_{sj}| \int_{\mathbb{R}} \exp \left( -x_j^2/4 \right) dx$$

$$\leq \prod_{j=1}^d C_2 \sum_{s_j=0}^{5p_j} |b_{sj}| \leq C_3 \prod_{j=1}^d 5p_j \leq C_4 |p|^d,$$

where we have used that $h_{sj}(x_j) \exp \left( -x_j^2/4 \right)$ is bounded uniformly in $s_j$ and $x_j$, and $|b_{sj}|$ is bounded over $s_j$. Then, by moments monotonicity, the second condition in Assumption 3.ii has been verified. Analogously, we can show that the condition 1 in Assumption 3.ii is verifiable.

Assumption 3.iii implies that the rate of $k \to \infty$ needs to be slower than that of $\min \{(NT)^{1/3}, T^{1/3} \}$. In practice, the lengths of the cross-sectional dimension and time series can be relatively large, so Assumption 3.iii is easy to achieve. Moreover, the researcher
normally assumes that $N/T \rightarrow c \in (0, \infty]$ as $N, T \rightarrow \infty$ in the conventional panel data case, which is also covered by Assumption 3.iii.

We are ready to establish the main results and their proofs are given in the appendix.

**Theorem 1** Let Assumptions 1, 2.i and 3 hold. Then, we have

$$
\left\| \hat{\beta} - \beta \right\|^2 = O_p \left( \frac{k^{3d/2}}{NT} \right) + o_p \left( k^{-r} \right).
$$

The first term of the convergence rate is not the optimal rate $O_p \left( \frac{k^d}{NT} \right)$, which is due to the fact that we can not bound the hermite polynomials uniformly. However, the optimality is achievable when the fourth order moment is bounded uniformly. This may be done in the same way as in Su and Jin (2012). By doing so, we will rule out the standard multivariate normal density for $x_{it}$ at least. The same arguments also apply to the other convergency rates given below.

Notice that the first $d$ elements of $\beta$ only involve $\theta_0$ and constant $c_1$ by (2.7). Moreover, $$
\left\| \hat{\beta}^d - \beta^d \right\|^2 \leq \left\| \hat{\beta} - \beta \right\|^2,$$
where $\hat{\beta}^d$ and $\beta^d$ denote the first $d$ elements of $\hat{\beta}$ and $\beta$, respectively. In connection with the identification restriction, it is easy to obtain that $\sqrt{\sum_{i=1}^d \hat{\beta}^2_i}$ converges to $|c_1|$. Then, intuitively, the estimator of $\theta_0$ is as follows.

$$
\hat{\theta} = \frac{sgn(\hat{\beta}_1)}{\sqrt{\sum_{i=1}^d \hat{\beta}^2_i}} \cdot Q_3 \cdot \hat{\beta}, \quad Q_3 = \left( I_d \begin{array}{c} 0 \\ 0 \end{array} \right)_{d \times (K-d)} \text{ and } I_d \text{ is a } d \times d \text{ identity matrix.}
$$

By Theorem 1, the following corollary follows immediately.

**Corollary 1** Under the conditions of Theorem 1, $\hat{\theta}$ is consistent.

Furthermore, we establish the following normality.

**Theorem 2** Let Assumptions 1, 2.i and 3 hold. If, in addition, $\frac{NT}{k^r} \rightarrow \sigma$ for $0 \leq \sigma < \infty$, $\frac{k^{3d}}{NT} \rightarrow 0$ and $E \left[ \left\| \frac{1}{\sqrt{N}} \sum_{i=1}^N (Q_1 - Q_2)^{-1} (Z(x_{i1}) - q_i) e_{i1} \right\|^4 \right] = O(1)$, as $(N, T) \rightarrow (\infty, \infty)$ jointly, then

$$
\sqrt{NT} \left( \hat{\theta} - \theta_0 \right) \overset{D}{\rightarrow} N \left( 0, c_1^{-2} \cdot \Xi_0 \right),
$$
where
\[
\Xi_0 = \lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^{N} Q_3 (Q_1 - Q_2)^{- \frac{1}{2}} \left\{ E \left[ e_{ii}^2 (Z (x_{ii}) - q_i) (Z (x_{ii}) - q_i)' \right] + \sum_{t=2}^{\infty} E \left[ e_{i1} e_{it} (Z (x_{it}) - q_i) (Z (x_{ii}) - q_i)' \right] \right\} (Q_1' - Q_2')^{- \frac{1}{2}} Q_3',
\]
and \( c_1 \) is denoted in (2.3).

The extra conditions required in the body of this theorem imply that achieving the asymptotic normality comes with a price such that \( r > 4.5d \), which is caused by the second decomposition on \( g(x'_i \theta_0) \) (see (2.5) for details) and can be considered as a trade-off in order to achieve the closed form estimator.

The restriction \( E \left[ \left\| \frac{1}{\sqrt{N}} \sum_{i=1}^{N} Q_3 (Q_1 - Q_2)^{-1} (Z (x_{ii}) - q_i) e_{ii} \right\|^4 \right] = O(1) \) is in spirit the same as Assumption ii of Lemma A.1 in Chen et al. (2012b) and can be easily verified for the i.i.d cases.

Based on Theorems 1 and 2, it is easy to realise that
\[
\hat{\Xi}_0 = Q_3 \hat{Q}_{12}^{-1} \left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{Z}_{it} \tilde{Z}_{it}' \left( \hat{y}_{it} - \hat{Z}_{it}' \hat{\beta} \right)^2 \right) \hat{Q}_{12}^{-1} Q_3' \xrightarrow{P} \Xi_0,
\]
where \( \hat{Q}_{12} = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{Z}_{it} \tilde{Z}_{it}' \). Therefore, the traditional hypothesis tests on \( \theta_0 \) can be established by
\[
\left( \sum_{i=1}^{d} \tilde{\beta}_i^2 \right)^{1/2} \frac{\hat{\xi}_0^{-1/2} \cdot \sqrt{NT} \left( \hat{\theta} - \theta_0 \right)}{D} \xrightarrow{N (0, I_d)}.
\]

So far we have fully recovered the interest parameter \( \theta_0 \). We will focus on the link function in the following section.

4 Estimation of The Link Function

We now can only estimate \( g(x'_i \theta_0) \) up to a constant by using \( \hat{\beta} \), because \( c_0 \) gets cancelled out by the within–transformation. Therefore, we need to take into account the location of the link function by Assumption 2.ii and recover \( c_0 \) by the next theorem. The proofs of the following results are given in the appendix.
Theorem 3  Under Assumptions 1–3, we have

\[(\hat{c}_0 - c_0)^2 = O_p \left( \frac{k^{3d/2}}{NT} \right) + o_p \left( k^{-r} \right),\]

where

\[\hat{c}_0 = -\frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z(x_{it})' \hat{\beta}.\]

In connection with (2.5) and Theorem 1, intuitively, we provide the next estimator for \(g(x' \theta_0)\).

\[\hat{g}(x' \hat{\theta}) = Z(x)' \hat{\beta} + \hat{c}_0\]  (4.1)

Based on the proof of Theorem 2, achieving the next result is straightforward.

Theorem 4  Let Assumptions 1, 2 and 3 hold. If, in addition, \(\frac{NT}{k^r} \rightarrow \sigma\) for \(r > 4.5d\) and \(0 \leq \sigma < \infty\), \(\frac{k^{4.5d}}{NT} \rightarrow 0\) and \(E \left[ \frac{1}{\sqrt{NK^3/2}} \sum_{i=1}^{N} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-1} (Z(x_{i1}) - q_i) e_{i1} \right] \right)^4 = O(1)\), as \((N,T) \rightarrow (\infty,\infty)\) jointly, then

\[\sqrt{\frac{NT}{K^{3/2}}} \left( \hat{g}(x' \hat{\theta}) - g(x' \theta_0) \right) \overset{D}{\rightarrow} N(0, \Xi_1),\]

where

\[\Xi_1 = \lim_{N,k \rightarrow \infty} \frac{1}{N} \sum_{i=1}^{N} \frac{1}{K^{3/2}} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-1} \left\{ E \left[ e_{i1}^2 (Z(x_{i1}) - q_i) (Z(x_{i1}) - q_i)' \right] 
+ \sum_{t=2}^{\infty} E \left[ e_{it} e_{it}' (Z(x_{i1}) - q_i) (Z(x_{i1}) - q_i)' \right] 
+ \sum_{t=2}^{\infty} E \left[ e_{it} e_{it}' (Z(x_{i1}) - q_i) (Z(x_{i1}) - q_i)' \right] \right\} (Q_1' - Q_2')^{-1} (Z(x) - \bar{q}),\]

and \(K\) is chosen by (2.9).

Again, it is pointed out that while the rate of convergence may not be optimal, the optimality is achievable when the fourth order moment is bounded uniformly. This may be done in the same way as in Su and Jin (2012). However, the optimality comes with a price. For example, \(x_{it}\) cannot even follow the standard multivariate normal distribution.

Similar to Theorem 2, it is easy to establish a standardised version of the form:

\[\sqrt{\frac{NT}{K^{3/2}} \cdot \Xi_1^{-1/2}} \cdot \left( \hat{g}(x' \hat{\theta}) - g(x' \theta_0) \right) \overset{D}{\rightarrow} N(0, 1),\]
where
\[
\hat{\zeta}_1 = (Z(x) - \hat{q})' \hat{\Omega}_{12}^{-1} \left( \frac{1}{NTK} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{Z}_{it} \tilde{Z}_{it}' \left( \tilde{y}_{it} - \tilde{\tilde{Z}}_{it}' \hat{\beta} \right) \right) \hat{\Omega}_{12}^{-1} (Z(x) - \hat{q}),
\]
\[
\hat{\Omega}_{12} = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{Z}_{it} \tilde{Z}_{it}' \quad \text{and} \quad \hat{q} = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z(x_{it}).
\]

In practice, the above results are useful to calculate the confidence interval for a point prediction of \(g(x' \theta_0)\).

Notice that the above two theorems just recover \(g(x' \theta_0)\) rather than \(g(w)\) itself. To estimate the link function \(g(w)\) regardless of \(\theta_0\), we now bring \(\hat{\theta}\) in (2.10) and then provide our estimator on \(\mathcal{C}\) below.

\[
\hat{\mathcal{C}} = \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{1T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{1T}) \mathcal{Y} \tag{4.2}
\]

We will proceed as in the previous section to investigate (4.2). To simplify the notation, for each time series \(\{x_{i1}, \ldots, x_{iT}\}\), let \(R_{1,i}(\theta) = E \left[ H(x_{i1}' \theta) H(x_{i1}' \theta)' \right]\) and \(r_i(\theta) = E \left[ H(x_{i1}' \theta) \right]\). Also, denote that \(R_1(\theta) = \frac{1}{N} \sum_{i=1}^{N} R_{1,i}(\theta), \quad \bar{r}(\theta) = \frac{1}{N} \sum_{i=1}^{N} r_i(\theta)\) and \(R_2(\theta) = \frac{1}{N} \sum_{i=1}^{N} r_i(\theta) r_i(\theta)'\). Moreover, the next assumption is necessary for achieving the consistency.

**Assumption 4:**

i. Let the smallest eigenvalue of the \((k - 1) \times (k - 1)\) matrix \((R_1(\theta) - R_2(\theta))\) be bounded away from zero uniformly on a neighbourhood of \(\theta_0\).

ii. \(\sup_{0 \leq \varepsilon \leq 1} \sup_{\|\theta - \theta_0\| \leq \varepsilon} \max_{i \geq 1} E \left[ |h_m(x_{i1}' \theta)|^{4 + \eta} \right] = O(m)\) as \(m \to \infty\), where \(\eta\) is given in Assumption 1.

iii. Suppose that \(x_{it}\) has a support \(\mathcal{X} \subset \mathbb{R}^d\). For \(\forall x \in \mathcal{X}\), \(g(x' \theta)\) satisfies a Lipschitz condition on a neighbourhood of \(\theta_0, U_{\theta_0}\), such that

\[
|g(x' \theta_1) - g(x' \theta_0)| \leq M(x) \|\theta_1 - \theta_0\|,
\]

where \(\theta_1 \in U_{\theta_0}\). Moreover, \(\frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (M(x_{it}))^2 = O_p(1)\).

Assumption 4.i-ii are in spirit the same as Assumption 3.i-ii. Similar to the arguments for Assumption 3.iii, we can show that Assumption 4.ii is verifiable. For example, if \(x_{it}' \theta\) follows a normal distribution, then we can show that Assumption 4.ii is verifiable by going through the similar procedure of the example given for Assumption 3.ii. Assumption 4.iii is
similar to Assumptions 5.3.1 and 5.5 in Ichimura (1993) and Assumption 3 in Newey and Powell (2003). We put Lipschitz condition on a neighbour of $\theta_0$ rather than assume $\mathbb{X}$ is compact. In this sense, this assumption is more general compared to Ichimura (1993). The last equation in Assumption 4.iii can be easily verified under certain restriction by following the similar procedure to the second result of Lemma 2 in the appendix.

Under the extra conditions, we establish the following theorem.

**Theorem 5** *Under the conditions of Theorem 2 and Assumption 4, as $(N,T) \to (\infty, \infty)$ jointly, then*

$$\left\| \hat{C} - C \right\|^2 = O_p \left( \frac{k^{3/2}}{NT} \right) + o_p \left( k^{-r} \right).$$

Similar to the discussion under Theorem 1, if we use a stronger assumption to bound the moments of $h_m(x\prime_it\theta)$ uniformly, the first term in the convergency rate above will become the optimal rate $O_p \left( \frac{k}{NT} \right)$.

Notice that the second decomposition (2.5) raises the curse of dimensionality issue when we estimate $\beta$ (cf. see the convergence rate in Theorem 1), but this issue does not exist in the convergency rate given by Theorem 5.

Intuitively, we denote an estimator of $g(w)$ similar to (4.1) as

$$\hat{g}_1(w) = H(w)\prime \hat{C} + \tilde{c}_0,$$  \hspace{1cm} (4.3)

where $\tilde{c}_0 = -\frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} H \left( x\prime_{it}\theta \right) \prime \hat{C}.$

The integrated mean squared error of the nonparametric estimate is summarised below.

**Corollary 2** *Under the conditions of Theorem 5, if in additional Assumption 2.ii holds, as $(N,T) \to (\infty, \infty)$ jointly, then*

$$\int_{\mathbb{R}} \left( \hat{g}_1(w) - g(w) \right)^2 \cdot \exp \left( -w^2/2 \right) dw = O_p \left( \frac{k^{3/2}}{NT} \right) + o_p \left( k^{-r} \right).$$

The proofs of Theorem 5 and Corollary 2 are given in the appendix. We will evaluate the proposed model and the estimation method using both simulated and real data examples in Section 5 below.
5 Numerical Study

In this section, we provide a Monte Carlo simulation and two empirical studies. In the simulation, we consider an exponential functional form, \( g(w) = \exp(w) \). The expectation \( E[\exp(x'\theta_0)] \) is certainly not zero, but it will not affect us to obtain a consistent estimation on \( \theta_0 \). It further backs up our argument for Assumption 2.ii. Similar discussion can be found in the Monte Carlo study section of Su and Jin (2012). In empirical studies, we investigate UK’s climate data and US cigarettes demand. It clearly shows that our method outperforms some existing methods in practice.

5.1 Monte Carlo Study

The data generating process (DGP) is as follows.

\[
y_{it} = \exp(x_{1,it}\theta_{01} + x_{2,it}\theta_{02}) + \gamma_i + e_{it} \tag{5.1}
\]

and for \( j = 1, 2 \)

\[
x_{j,it} = \rho_j x_{j,i,t-1} + \text{i.i.d. } N(0, 1) \text{ for } t = -99, \ldots, 0, \ldots, T,
\]

\[
\rho_x_1 = 0.7, \quad \rho_x_2 = 0.3, \quad x_{j,i,-100} = 0.
\]

To introduce the cross-sectional dependence to the model, we follow the DGP in Chen et al. (2012a) and let \( e_t = (e_{1t}, \ldots, e_{Nt})', e_{-100} = 0_{N \times 1} \) and \( \rho_e = 0.2 \) for \( 1 \leq t \leq T \). Then the error term \( e_t \) is generated as

\[
e_t = \rho_e e_{t-1} + \text{i.i.d. } N(0_{N \times 1}, \Sigma_e) \text{ for } t = -99, \ldots, 0, \ldots, T,
\]

where \( \Sigma_e = (\sigma_{ij})_{N \times N} = 0.5^{|i-j|} \text{ for } 1 \leq i, j \leq N. \) The fixed effects, \( \gamma_i \)'s, follow from \text{i.i.d. } U(0, 1).

The values of \( \theta_{01} \) and \( \theta_{02} \) are set to 0.8 and -0.6, and they are estimated by \( \hat{\theta}_1 \) and \( \hat{\theta}_2 \), respectively. In this Monte Carlo study, we choose \( N, T = 20, 50, 100, 200 \) and \( k \) as \([1.36 \cdot \sqrt{50}] = 5\), \([1.36 \cdot \sqrt{100}] = 6\) and \([1.36 \cdot \sqrt{200}] = 7\) respectively. We repeat the estimation procedure 10000 times.

As Tables 1-3 shows, all the results are very accurate. The biases and the root mean squared errors (RMSE) of \( \hat{\theta}_1 \) and \( \hat{\theta}_2 \) decrease as both \( N \) and \( T \) increase. Notice that the biases for this simulation are quite small, which is due to the next reasons. In (A.11), it is easy to be seen that the first term on the right hand side (RHS) is unbiased and has expectation zero. The second term on RHS of (A.11) is biased and its convergence rate is
\( o_p(k^{-r}) \), where \( r \) is directly related to the smoothness of the link function \( g(x) \). We know that the \( n^{th} \) derivative of the exponential function exists for all positive integers \( n = 1, 2, \ldots \), so it is reasonable to expect this term will generate very small bias. Similarly, we do not expect the second term on RHS of (A.11) contributes too much to RMSE.

\[
\begin{array}{cccccccc}
\hat{\theta}_1 & & & & \hat{\theta}_2 & & & \\
\hline
k = 5 & N \setminus T & 20 & 50 & 100 & 200 & 20 & 50 & 100 & 200 \\
\hline
\text{Bias} & 20 & -0.0012 & 0.0005 & 0.0006 & 0.0005 & 0.0000 & 0.0012 & 0.0011 & 0.0009 \\
& 50 & -0.0004 & 0.0005 & 0.0005 & 0.0003 & 0.0001 & 0.0009 & 0.0008 & 0.0005 \\
& 100 & -0.0005 & 0.0002 & 0.0004 & 0.0004 & -0.0002 & 0.0005 & 0.0006 & 0.0004 \\
& 200 & -0.0004 & 0.0002 & 0.0002 & 0.0001 & -0.0003 & 0.0004 & 0.0003 & 0.0002 \\
\hline
\text{RMSE} & 20 & 0.0264 & 0.0152 & 0.0109 & 0.0083 & 0.0352 & 0.0204 & 0.0146 & 0.0111 \\
& 50 & 0.0171 & 0.0106 & 0.0078 & 0.0062 & 0.0228 & 0.0162 & 0.0104 & 0.0082 \\
& 100 & 0.0131 & 0.0081 & 0.0061 & 0.0047 & 0.0174 & 0.0108 & 0.0081 & 0.0063 \\
& 200 & 0.0099 & 0.0063 & 0.0048 & 0.0037 & 0.0132 & 0.0084 & 0.0064 & 0.0049 \\
\end{array}
\]

Table 1: Bias and RMSE for \( k = 5 \)

\[
\begin{array}{cccccccc}
\hat{\theta}_1 & & & & \hat{\theta}_2 & & & \\
\hline
k = 6 & N \setminus T & 20 & 50 & 100 & 200 & 20 & 50 & 100 & 200 \\
\hline
\text{Bias} & 20 & -0.0015 & -0.0002 & -0.0001 & -0.0002 & -0.0003 & 0.0002 & 0.0001 & -0.0001 \\
& 50 & -0.0009 & -0.0002 & -0.0001 & -0.0002 & -0.0007 & -0.0001 & 0.0000 & -0.0002 \\
& 100 & -0.0009 & -0.0002 & -0.0001 & -0.0001 & -0.0010 & -0.0002 & -0.0001 & -0.0002 \\
& 200 & -0.0009 & -0.0002 & -0.0001 & -0.0001 & -0.0010 & -0.0002 & -0.0002 & -0.0001 \\
\hline
\text{RMSE} & 20 & 0.0027 & 0.0138 & 0.0093 & 0.0064 & 0.0374 & 0.0185 & 0.0123 & 0.0086 \\
& 50 & 0.0157 & 0.0087 & 0.0060 & 0.0042 & 0.0209 & 0.0116 & 0.0079 & 0.0055 \\
& 100 & 0.0109 & 0.0061 & 0.0042 & 0.0031 & 0.0145 & 0.0082 & 0.0056 & 0.0041 \\
& 200 & 0.0078 & 0.0045 & 0.0031 & 0.0023 & 0.0103 & 0.0060 & 0.0042 & 0.0031 \\
\end{array}
\]

Table 2: Bias and RMSE for \( k = 6 \)
Table 3: Bias and RMSE for $k = 7$

<table>
<thead>
<tr>
<th>$k = 7$</th>
<th>$N \backslash T$</th>
<th>20</th>
<th>50</th>
<th>100</th>
<th>200</th>
<th>20</th>
<th>50</th>
<th>100</th>
<th>200</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bias</td>
<td>20</td>
<td>-0.0014</td>
<td>-0.0001</td>
<td>-0.0001</td>
<td>-0.0001</td>
<td>0.0008</td>
<td>0.0003</td>
<td>0.0001</td>
<td>-0.0001</td>
</tr>
<tr>
<td></td>
<td>50</td>
<td>-0.0009</td>
<td>-0.0002</td>
<td>-0.0001</td>
<td>-0.0001</td>
<td>-0.0006</td>
<td>-0.0001</td>
<td>0.0000</td>
<td>-0.0002</td>
</tr>
<tr>
<td></td>
<td>100</td>
<td>-0.0009</td>
<td>-0.0002</td>
<td>-0.0001</td>
<td>-0.0001</td>
<td>-0.0010</td>
<td>-0.0002</td>
<td>-0.0001</td>
<td>-0.0002</td>
</tr>
<tr>
<td></td>
<td>200</td>
<td>-0.0009</td>
<td>-0.0002</td>
<td>-0.0001</td>
<td>-0.0001</td>
<td>-0.0010</td>
<td>-0.0002</td>
<td>-0.0002</td>
<td>-0.0001</td>
</tr>
<tr>
<td>RMSE</td>
<td>20</td>
<td>0.0333</td>
<td>0.0142</td>
<td>0.0092</td>
<td>0.0063</td>
<td>0.0458</td>
<td>0.0190</td>
<td>0.0123</td>
<td>0.0084</td>
</tr>
<tr>
<td></td>
<td>50</td>
<td>0.0161</td>
<td>0.0086</td>
<td>0.0058</td>
<td>0.0040</td>
<td>0.0214</td>
<td>0.0115</td>
<td>0.0077</td>
<td>0.0053</td>
</tr>
<tr>
<td></td>
<td>100</td>
<td>0.0109</td>
<td>0.0060</td>
<td>0.0040</td>
<td>0.0028</td>
<td>0.0145</td>
<td>0.0079</td>
<td>0.0054</td>
<td>0.0038</td>
</tr>
<tr>
<td></td>
<td>200</td>
<td>0.0076</td>
<td>0.0042</td>
<td>0.0029</td>
<td>0.0020</td>
<td>0.0101</td>
<td>0.0056</td>
<td>0.0039</td>
<td>0.0027</td>
</tr>
</tbody>
</table>

5.2 Empirical Studies

In this section, we provide two empirical studies to demonstrate how our method performs in practice. As a comparison, we also run OLS regression on the following linear model after within transformation for the next two data sets.

$$y_{it} = x_{it}'\theta_0 + \gamma_i + e_{it}. \tag{5.2}$$

According to the results on convergence rates in previous sections, it is impossible to tell what the optimal $k$ should be. To choose the truncation parameter $k$, we use the extended version of the generalized cross-validation (GCV) criterion proposed in Gao et al. (2002) at first. Then select a $k$ according to the other measurements (e.g. $R^2$) in a small range of the $\hat{k}$ suggested by GCV. As they mention in the paper, how to select an optimum truncation parameter has not been completely solved yet.

Below SIM and LIM denote the semiparametric single-index model (2.1) and the linear model (5.2), respectively. The corresponding standard deviations are reported in the brackets.

5.2.1 UK’s Climate Data

Firstly, we use the exactly same UK’s climate data as Chen et al. (2013a), which is available from http://www.metoffice.gov.uk/climate/uk/stationdata/. We investigate how the average maximum temperature (TMAX) is affected by the number of millimeters of rainfall
(RAIN) and the number of hours of sunshine (SUN). The data were collected over the decade of January 1999 to December 2008 from 16 stations across UK, so $N = 16$ and $T = 120$.

The results are reported in Table 4 and Figures 1 and 2.

<table>
<thead>
<tr>
<th></th>
<th>SIM</th>
<th>LIM</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\hat{\theta}_1$</td>
<td>0.313</td>
<td>0.019</td>
</tr>
<tr>
<td>$\hat{\theta}_2$</td>
<td>0.950</td>
<td>0.070</td>
</tr>
<tr>
<td>$R^2$</td>
<td>0.685</td>
<td>0.655</td>
</tr>
<tr>
<td>$(0.702)$</td>
<td>$(0.953)$</td>
<td>$(0.003)$</td>
</tr>
<tr>
<td>$(0.004)$</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 4: Estimated coefficients for UK’s climate data

The $R^2$’s indicate that the semiparametric estimator proposed in this paper generates more accurate results. Compared to the $R^2 = 0.6199$ in Chen et al. (2013a), our method performs better. For our model, the number of Hermite Polynomial function is chosen as 6 (such that $h_0, h_1, \ldots, h_5$ are chosen and $K = 20$ by (2.9)). Due to the similarity, we only report the temperature plots for one station in Figure 1 and omit the others. The dash-dot line is the observed TMAX data; the solid line is the estimated temperature by our approach; and the two dash lines are 95% confidence interval obtained by using Theorem 4. Figure 1 shows that our estimates clearly capture the movement of average maximum temperature. In Figure 2, the estimated curve is plotted according to (4.3). As one can see, the linear model tells an unconvincing story. According to Figure 2 and the results from OLS, one would have concluded that as the amount of rain fall goes up, the average maximum temperature will increase. However, this seems to be very misleading. On the other hand, the single-index model tells us that the maximum temperature will decrease as the amount of rain fall increases, which is more meaningful to us.

5.2.2 US Cigarettes Demand

The data set of the second case study is from Baltagi et al. (2000) for analysing the demand for cigarettes in the U.S., who use the next linear model of the form

$$\ln C_{it} = \beta_0 + \beta_1 \ln C_{i,t-1} + \beta_2 \ln DI_{it} + \beta_3 \ln P_{it} + \beta_4 \ln PN_{it} + u_{it},$$

(5.3)

where $i = 1, \ldots, 46$ and $t = 1, \ldots, 30$ represent the states and the years (1963-1992) respectively, $C_{it}$ is the real per capita sales of cigarettes (measured in packs), $DI_{it}$ is the real per capita disposable income, $P_{it}$ is the average retail price of a pack of cigarettes measured in
real terms, $PN_{it}$ is the minimum real price of cigarettes in any neighbouring state and $u_{it}$ is the disturbance term.

We consider fitting the data by a semiparametric single–index model of the form

$$\ln C_{it} = g(x_{it}' \theta) + \gamma_i + e_{it}, \quad (5.4)$$

where $x_{it} = (\ln C_{i,t-1}, \ln D_{i,t}, \ln P_{it}, \ln PN_{it})'$. Due to the lagged dependent value included in $x_{it}$, the length of time series used in the regression is 29 (such that $t = 2, \ldots, 30$). $\gamma_i$’s capture all the state-specific effects. All the errors’ cross-sectional dependences and year-specific effects are absorbed in $e_{it}$. Similar to the previous section, we report the estimates below. The results of several other attempts can be found in Baltagi et al. (2000), Mammen et al. (2009) and Chen et al. (2013b).

Compared to the $R^2 = 0.9698$ in Chen et al. (2013b), our method provides slightly better results. For our model, the number of Hermite Polynomial function is chosen as 2 (such that
Table 5: Estimated coefficients for US cigarette demand

|h_0 and h_1 are chosen) so that the link function g is a linear function (with a different slope compared to the identity function). Due to the similarity, we only report the plots for one state in Figure 3 and omit the others. The dash-dot line is the real per capita sales of cigarettes; the solid line is the estimated per capita sales of cigarettes by our approach; the two dash lines are 95% confidence interval obtained by using Theorem 4. In Figure 4, the estimated curve is plotted.

Figure 3: Estimated log real per capita sales of cigarettes

6 Conclusion

In this paper, we have proposed a semiparametric single-index panel data model associated with cross-sectional dependence, high-dimensionality, stationarity and unobservable heterogeneity. Some closed-form estimates have been proposed and the closed-form estimates have been used to recover the estimates of the parameters of interest and the link function respectively. The resulting asymptotic theory has been established and illustrated using both simulated and empirical examples. As both the theory and Monte Carlo study have suggested, our model and estimation method perform well when cross-sectional dependence
exists in the system. Moreover, since we have not imposed any specific assumption on the fixed effects, they can be correlated with the regressors to capture unobservable heterogeneity. Two empirical examples have shown that the proposed model and estimation method outperform some natural competitors.

Appendix

We now provide some useful lemmas before we prove the main results of this paper. Lemma 1 is in the same spirit as Lemma 12.4.2 of Blower (2009).

Lemma 1 Suppose that \( u = (u_1, \ldots, u_d), v = (v_1, \ldots, v_d) \in \mathbb{R}^d \) and \( \|v\| = 1 \). Then

\[
H_m(u'v) = \sum_{|p| = m} \left( \prod_{j=1}^{d} H_p(u_j) \prod_{j=1}^{d} v_p^j \right),
\]

where \( p = (p_1, \ldots, p_d), p_j \) for \( j = 1, \ldots, d \) are all nonnegative integers, \( |p| = p_1 + \cdots + p_d \) and \( \binom{m}{p} = \frac{m!}{p_1! \cdots p_d!} \).

Proof of Lemma 1: It is known that Hermite polynomial system has the following generating function

\[
\exp(\lambda x - \lambda^2/2) = \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} H_n(x). \tag{A.1}
\]

For each \( j = 1, \ldots, d \), by (A.1) we have

\[
\exp(v_j u_j - v_j^2/2) = \sum_{p_j=0}^{\infty} \frac{v_j^{p_j}}{p_j!} H_{p_j}(u_j).
\]
Hence, we can take product of $j$ to obtain that
\[
\exp\left( u'v - \|v\|^2/2 \right) = \prod_{j=1}^d \sum_{p_j=0}^\infty \frac{v_j^{p_j}}{p_j!} H_{p_j}(u_j)
\]
\[
= \sum_{m=0}^\infty \sum_{|p|=m} \frac{1}{\prod_{j=1}^d p_j} \prod_{j=1}^d H_{p_j}(u_j) \prod_{j=1}^d v_j^{p_j}.
\]
Notice that $\|v\| = 1$ and once again the generating function indicates that the term of degree $m$ on left hand side (LHS) is $\frac{1}{m!} H_m(u'v)$, which, after matching with the term of degree $m$ on right hand side (RHS), gives the result.

**Lemma 2** Let Assumptions 1, 2 and 3 hold. Then, we have

1. $E \left\| \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T Z(x_{it}) Z(x_{it})' - Q_1 \right\|^2 = O\left( \sum_{i=1}^K \sum_{v=1}^K E \left[ \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T z_u(x_{it}) z_v(x_{it}) - \frac{1}{N} \sum_{i=1}^N Q_{1,iuv} \right]^2 \right)$;

2. $E \left[ \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T g(x_{it}^\theta) \right]^2 = O\left( \frac{1}{NT} \right)$;

3. $E \left\| \frac{1}{T} \sum_{t=1}^T Z(x_{it}) - q_i \right\|^2 = O\left( \frac{k^3}{T} \right)$;

4. $E \left\| \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T Z(x_{it}) e_{it} \right\|^2 = O\left( \frac{k^3/2}{NT} \right)$;

5. $\lambda_{min} \left( \frac{1}{NT} Z' (I_N \otimes M_{il}) Z \right) \geq \lambda_{min} (Q_1 - Q_2)/2 > 0$.

**Proof of Lemma 2:** 1). Write

\[
E \left\| \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T Z(x_{it}) Z(x_{it})' - Q_1 \right\|^2 = \sum_{u=1}^K \sum_{v=1}^K E \left[ \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T z_u(x_{it}) z_v(x_{it}) - \frac{1}{N} \sum_{i=1}^N Q_{1,iuv} \right]^2,
\]

where $z_u(\cdot)$ and $z_v(\cdot)$ are the $u^{th}$ and $v^{th}$ elements of $Z(\cdot)$, respectively, and $Q_{1,iuv}$ is the $(u,v)^{th}$ element of $Q_{1,i}$. 

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Observe that

\[
E \left[ \frac{1}{N^2} \sum_{i=1}^{N} \sum_{t=1}^{T} z_u(x_{it}) z_v(x_{it}) - \frac{1}{N} \sum_{i=1}^{N} Q_{1,1uv} \right]^2
\]

\[
= \frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} E \left[ \frac{1}{T^2} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \left( z_u(x_{it_1}) z_v(x_{it_1}) - Q_{1,1uv} \right) \left( z_u(x_{jt_2}) z_v(x_{jt_2}) - Q_{1,1uv} \right) \right]
\]

\[
= \frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} \text{Cov} \left( z_u(x_{i1}) z_v(x_{i1}), z_u(x_{j1}) z_v(x_{j1}) \right)
\]

\[
+ \frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} \left( 1 - \frac{t}{T} \right) \text{Cov} \left( z_u(x_{i1}) z_v(x_{i1}), z_u(x_{j1+t}) z_v(x_{j,1+t}) \right)
\]

\[
+ \frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} \left( 1 - \frac{t}{T} \right) \text{Cov} \left( z_u(x_{j1}) z_v(x_{j1}), z_u(x_{i,1+t}) z_v(x_{i,1+t}) \right)
\]

\[
= \frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} \left( \Phi_{ijuv,1} + \Phi_{ijuv,2} + \Phi_{ijuv,3} \right). \tag{A.3}
\]

We then consider each term on right hand side (RHS) of (A.3) respectively. Due to the Davydov inequality (cf. pages 19-20 in Bosq (1996) and supplementary of Su and Jin (2012))

\[
\left| \Phi_{ijuv,2} \right| = \sum_{t=1}^{T-1} \left( 1 - \frac{t}{T} \right) \text{Cov} \left( z_u(x_{i1}) z_v(x_{i1}), z_u(x_{j,1+t}) z_v(x_{j,1+t}) \right)
\]

\[
\leq c_\eta \sum_{t=1}^{T-1} \left| 1 - \frac{t}{T} \right| \cdot (\alpha_{ij}(t))^{\eta/(4+\eta)} \cdot \left( E \left[ |z_u(x_{i1}) z_v(x_{i1})|^{2+\eta/2} \right] \right)^{2/(4+\eta)}
\]

\[
\cdot \left( E \left[ |z_u(x_{j1}) z_v(x_{j1})|^{2+\eta/2} \right] \right)^{2/(4+\eta)}
\]

\[
\leq \frac{c_\eta}{2} \sum_{t=1}^{T-1} \left| 1 - \frac{t}{T} \right| \cdot (\alpha_{ij}(t))^{\eta/(4+\eta)} \cdot \left( E \left[ |z_u(x_{i1}) z_v(x_{i1})|^{2+\eta/2} \right] \right)^{4/(4+\eta)}
\]

\[
+ \frac{c_\eta}{2} \sum_{t=1}^{T-1} \left| 1 - \frac{t}{T} \right| \cdot (\alpha_{ij}(t))^{\eta/(4+\eta)} \cdot \left( E \left[ |z_u(x_{j1}) z_v(x_{j1})|^{2+\eta/2} \right] \right)^{4/(4+\eta)}
\]

\[
\leq \frac{c_\eta}{2} \sum_{t=1}^{T-1} (\alpha_{ij}(t))^{\eta/(4+\eta)} \cdot \left( E \left[ |z_u(x_{i1})|^{4+\eta} \right] E \left[ |z_v(x_{i1})|^{4+\eta} \right] \right)^{2/(4+\eta)}
\]

\[
+ \frac{c_\eta}{2} \sum_{t=1}^{T-1} (\alpha_{ij}(t))^{\eta/(4+\eta)} \cdot \left( E \left[ |z_u(x_{j1})|^{4+\eta} \right] E \left[ |z_v(x_{j1})|^{4+\eta} \right] \right)^{2/(4+\eta)} \tag{A.4}
\]

where \( c_\eta = 2^{(4+2\eta)/(4+\eta)} \cdot (4 + \eta)/\eta. \)
In connection with Assumption 3.ii,
\[
\frac{1}{N^2T} \sum_{u=1}^{K} \sum_{v=1}^{K} \sum_{i=1}^{N} \sum_{j=1}^{N} |\Phi_{jv,u,2}|
\leq \frac{C}{N^2T} \sum_{u=1}^{K} \sum_{v=1}^{K} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} (\alpha_{ij}(t))^{\eta/(4+\eta)} : \left( O\left(|p_u|^d\right) \cdot O\left(|p_v|^d\right) \right)^{2/(4+\eta)}
\leq \frac{C}{N^2T} \sum_{u=1}^{K} \sum_{v=1}^{K} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} (\alpha_{ij}(t))^{\eta/(4+\eta)} : \left( O\left(|p_u|^d\right) \cdot |p_v|^d \right)^{1/2} = O\left(\frac{k^{3d}}{NT}\right),
\]
where the last line is true due to the fact that \( \max_{1 \leq u \leq K} |p_u| = k - 1 \) and \( K = O\left(k^d\right) \).

Similarly,
\[
\frac{1}{N^2T} \sum_{u=1}^{K} \sum_{v=1}^{K} \sum_{i=1}^{N} \sum_{j=1}^{N} |\Phi_{jv,u,1}| = O\left(\frac{k^{3d}}{NT}\right) \quad \text{and} \quad \frac{1}{N^2T} \sum_{u=1}^{K} \sum_{v=1}^{K} \sum_{i=1}^{N} \sum_{j=1}^{N} |\Phi_{jv,u,3}| = O\left(\frac{k^{3d}}{NT}\right).
\]
Thus, the result follows. ■

2). Write
\[
E\left[ \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} g(x'_{it} \theta_0) \right]^2 \leq \frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} E\left[ \frac{1}{T^2} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} g(x'_{it_1} \theta_0) g(x'_{jt_2} \theta_0) \right]. \quad (A.5)
\]
Expanding the RHS of the above equation by the same procedure as (A.3) and (A.4), the result follows from Assumptions 1.i and 2.ii. ■

3). By following the same procedure as the first result of this lemma, the result follows. ■

4). Write
\[
E\left[ \left| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z(x'_{it}) e_{it} \right|^2 \right] = \frac{K}{NT} \sum_{u=1}^{K} \left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} z_{iu}(x_{it}) e_{it} \right)^2
\]
\[
= \frac{K}{N^2} \sum_{u=1}^{K} \sum_{i=1}^{N} \sum_{j=1}^{N} E\left[ \frac{1}{T^2} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} z_{iu}(x_{it_1}) e_{it_1} z_{iu}(x_{jt_2}) e_{jt_2} \right]. \quad (A.6)
\]
Following the same procedure as the first result of this lemma, the result follows. ■

5) Write
\[
\lambda_{\min} \left( \frac{1}{NT} \mathbf{Z}' (I_N \otimes M_{tr}) \mathbf{Z} \right) = \lambda_{\min} \left( \frac{1}{NT} \sum_{i=1}^{T} \sum_{t=1}^{N} \tilde{Z}_{it} \tilde{Z}_{it}' \right)
\]
\[
= \min_{\|\mathbf{x}\|=1} \left\{ \chi'(Q_1 - Q_2) \chi + \chi' \left( \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \tilde{Z}_{it} \tilde{Z}_{it}' - (Q_1 - Q_2) \right) \chi \right\}
\]
\[
\geq \lambda_{\min} (Q_1 - Q_2) - \left\| \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \tilde{Z}_{it} \tilde{Z}_{it}' - (Q_1 - Q_2) \right\|. \quad (A.7)
\]
We now consider \( \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \tilde{Z}_{it} \tilde{Z}_{it}' - (Q_1 - Q_2) \).

\[
\frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \tilde{Z}_{it} \tilde{Z}_{it}' - (Q_1 - Q_2) = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (Z (x_{it}) Z (x_{it})' - Q_{1,i}) - \frac{1}{N} \sum_{i=1}^{N} (\tilde{Z}_{i} \tilde{Z}_{i}' - q_i q_i')
\]

Similar to the first result of this lemma

\[
\left\| \frac{1}{N} \sum_{i=1}^{N} (\tilde{Z}_{i} \tilde{Z}_{i}' - q_i q_i') \right\| \leq \left\| \frac{1}{N} \sum_{i=1}^{N} (\tilde{Z}_{i} - q_i) (\tilde{Z}_{i} - q_i)' \right\| + \left\| \frac{1}{N} \sum_{i=1}^{N} (\tilde{Z}_{i} - q_i) q_i' \right\| + \left\| \frac{1}{N} \sum_{i=1}^{N} q_i (\tilde{Z}_{i} - q_i)' \right\| = o_p(1).
\]

In connection with the first result of this lemma, we obtain

\[
\left\| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{Z}_{it} \tilde{Z}_{it}' - (Q_1 - Q_2) \right\| \leq \left\| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (Z (x_{it}) Z (x_{it})' - Q_{1,i}) \right\| + \left\| \frac{1}{N} \sum_{i=1}^{N} (\tilde{Z}_{i} \tilde{Z}_{i}' - q_i q_i') \right\| = o_p(1).
\]

Thus, the result follows.

\[\square\]

**Lemma 3** Let Assumptions 1–4 hold. Then the following results hold uniformly in a small neighbour of \( \theta_0 \):

1. \( E \left\| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} H (x'_{it} \theta) H (x'_{it} \theta)' - R_1 (\theta) \right\|^2 = O \left( \frac{k^3}{NT} \right) \);

2. \( E \left\| \frac{1}{T} \sum_{t=1}^{T} (x'_{it} \theta - r_i (\theta)) \right\|^2 = O \left( \frac{k^{3/2}}{T} \right) \);

3. \( E \left\| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} H (x'_{it} \theta) e_{it} \right\|^2 = O \left( \frac{k^{3/2}}{NT} \right) \);

4. \( \lambda_{\min} \left( \frac{1}{NT} H (\theta)' (I_N \otimes M_{it}) H (\theta) \right) \geq \lambda_{\min} (R_1 (\theta) - R_2 (\theta)) / 2 > 0 \).

**Proof of Lemma 3:** 1). Write

\[
E \left\| \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} H (x'_{it} \theta) H (x'_{it} \theta)' - R_1 (\theta) \right\|^2 = \sum_{u=1}^{k-1} \sum_{v=1}^{k-1} E \left[ \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} h_u (x'_{it} \theta) h_v (x'_{it} \theta) - \frac{1}{N} \sum_{i=1}^{N} R_{1, iuv} (\theta) \right]^2 ,
\]

where \( h_u (\cdot) \) and \( h_v (\cdot) \) are the \( u^{th} \) and \( v^{th} \) elements of \( H (\cdot) \), respectively, and \( R_{1, iuv} \) is the \( (u, v)^{th} \) element of \( R_{1,i}(\theta) \).
Observe that
\[
E \left[ \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{t=1}^{T} h_u(x'_i \theta) h_v(x'_i \theta) - \frac{1}{N} \sum_{i=1}^{N} R_{1,uvw}(\theta) \right]^2 = \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{j=1}^{N} \text{Cov} \left( h_u(x'_i \theta) h_v(x'_i \theta), h_u(x'_j \theta) h_v(x'_j \theta) \right)
\]
\[+ \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} \left( 1 - \frac{t}{T} \right) \text{Cov} \left( h_u(x'_i \theta) h_v(x'_i \theta), h_u(x'_{j,t} \theta) h_v(x'_{j,t} \theta) \right)
\]
\[+ \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} \left( 1 - \frac{t}{T} \right) \text{Cov} \left( h_u(x'_j \theta) h_v(x'_j \theta), h_u(x'_{i,t} \theta) h_v(x'_{i,t} \theta) \right)
\]
\[= \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{j=1}^{N} \left( \Psi_{ijuv,1}(\theta) + \Psi_{ijuv,2}(\theta) + \Psi_{ijuv,3}(\theta) \right).
\]
\[\text{(A.9)}\]

By the similar procedure of (A.4)
\[
|\Psi_{ijuv,2}(\theta)| = \left| \sum_{t=1}^{T-1} \left( 1 - \frac{t}{T} \right) \text{Cov} \left( h_u(x'_i \theta) h_v(x'_i \theta), h_u(x'_{j,t} \theta) h_v(x'_{j,t} \theta) \right) \right|
\]
\[\leq C \sum_{t=1}^{T} (\alpha_{ij} (t))^{(4+\eta)} \cdot \left( E \left[ |h_u(x'_i \theta)|^{4+\eta} \right] E \left[ |h_v(x'_i \theta)|^{4+\eta} \right] \right)^{2/(4+\eta)}
\]
\[+ C \sum_{t=1}^{T} (\alpha_{ij} (t))^{(4+\eta)} \cdot \left( E \left[ |h_u(x'_{j,t} \theta)|^{4+\eta} \right] E \left[ |h_v(x'_{j,t} \theta)|^{4+\eta} \right] \right)^{2/(4+\eta)},
\]
where \(C = 2^{(4+2\eta)/(4+\eta)} \cdot (4 + \eta)/\eta.

In connection with Assumption 4.ii,
\[
\frac{1}{N^2 T} \sum_{u=1}^{k-1} \sum_{v=1}^{k-1} \sum_{i=1}^{N} \sum_{j=1}^{N} |\Psi_{ijuv,2}| \leq C \sum_{u=1}^{k-1} \sum_{v=1}^{k-1} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} (\alpha_{ij} (t))^{(4+\eta)} \cdot (O(u) \cdot O(v))^{2/(4+\eta)}
\]
\[\leq C \sum_{u=1}^{k-1} \sum_{v=1}^{k-1} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T-1} (\alpha_{ij} (t))^{(4+\eta)} \cdot (O(u \cdot v))^{1/2} = O \left( \frac{k^3}{NT} \right).
\]

Similarly,
\[
\frac{1}{N^2 T} \sum_{u=1}^{k-1} \sum_{v=1}^{k-1} \sum_{i=1}^{N} \sum_{j=1}^{N} |\Psi_{ijuv,1}| = O \left( \frac{k^3}{NT} \right) \quad \text{and} \quad \frac{1}{N^2 T} \sum_{u=1}^{k-1} \sum_{v=1}^{k-1} \sum_{i=1}^{N} \sum_{j=1}^{N} |\Psi_{ijuv,3}| = O \left( \frac{k^3}{NT} \right).
\]

Thus, the result follows.

2). Using the similar procedure to the first result of this lemma, the result follows.

3). Write
\[
E \left[ \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} H(x'_i \theta) e_{it} \right]^2 = \sum_{u=1}^{k-1} E \left[ \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} h_u(x'_i \theta) e_{it} \right]^2
\]
\[= \sum_{u=1}^{k-1} \frac{1}{N^2 T} \sum_{i=1}^{N} \sum_{j=1}^{N} E \left[ \sum_{t=1}^{T} \sum_{t_1=1}^{T} h_u(x'_{i,t_1} \theta) h_u(x'_{j,t_2} \theta) e_{i,t_1} e_{j,t_2} \right].
\]
\[\text{(A.10)}\]
Similar to the procedure used in proving the first result of this lemma, the result follows.

4) Similar to (A.7), write

\[ \lambda_{\min}\left(\frac{1}{NT}H'(I_N \otimes M_{iy})H\right) \]

\[ \geq \lambda_{\min}(R_1(\theta) - R_2(\theta)) - \left\| \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \bar{H}(x_{it}'\theta) \bar{H}(x_{it}'\theta)' - (R_1(\theta) - R_2(\theta)) \right\|, \]

where \( \bar{H}(x_{it}'\theta) = H(x_{it}'\theta) - \bar{H}_i(\theta) \) and \( \bar{H}_i(\theta) = \frac{1}{T} \sum_{t=1}^{T} H(x_{it}'\theta) \).

We now consider

\[ \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \bar{H}(x_{it}'\theta) \bar{H}(x_{it}'\theta)' - (R_1(\theta) - R_2(\theta)) \]

\[ = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \left( H(x_{it}'\theta) H(x_{it}'\theta)' - R_{1,i}(\theta) \right) - \frac{1}{N} \sum_{i=1}^{N} \left( \bar{H}_i(\theta) \bar{H}_i(\theta)' - r_i(\theta) r_i(\theta)' \right). \]

In a similar fashion to the proof of the first result of this lemma, we have

\[ \left\| \frac{1}{N} \sum_{i=1}^{N} \left( \bar{H}_i(\theta) \bar{H}_i(\theta)' - r_i(\theta) r_i(\theta)' \right) \right\| \]

\[ \leq \left\| \frac{1}{N} \sum_{i=1}^{N} \left( \bar{H}_i(\theta) - r_i(\theta) \right) \left( \bar{H}_i(\theta) - r_i(\theta) \right)' \right\| + \left\| \frac{1}{N} \sum_{i=1}^{N} \left( \bar{H}_i(\theta) - r_i(\theta) \right) r_i(\theta)' \right\| \]

\[ + \left\| \frac{1}{N} \sum_{i=1}^{N} r_i(\theta) \left( \bar{H}_i(\theta) - r_i(\theta) \right)' \right\| = o_p(1). \]

In connection with the first result of this lemma, we obtain

\[ \left\| \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \bar{H}(x_{it}'\theta) \bar{H}(x_{it}'\theta)' - (R_1(\theta) - R_2(\theta)) \right\| \]

\[ \leq \left\| \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} H(x_{it}'\theta) H(x_{it}'\theta)' - R_1(\theta) \right\| + \left\| \frac{1}{N} \sum_{i=1}^{N} \left( \bar{H}_i(\theta) \bar{H}_i(\theta)' - r_i(\theta) r_i(\theta)' \right) \right\| = o_p(1). \]

Thus, the result follows.

**Proof of Theorem 1:** We now start the proof of the consistency. By the uniqueness of the Moore-Penrose inverse and the fifth result of Lemma 2 of this appendix, the \( K \times K \) dimensions matrix \( Z'(I_N \otimes M_{iy}) Z \) is the inverse of \( Z'(I_N \otimes M_{iy}) \) \( Z \) for each \( K \). Therefore,

\[ \hat{\beta} - \beta = \left[ Z'(I_N \otimes M_{iy}) Z \right]^{-1} Z'(I_N \otimes M_{iy}) \mathcal{E} \]

\[ + \left[ Z'(I_N \otimes M_{iy}) Z \right]^{-1} Z'(I_N \otimes M_{iy}) \mathcal{D}(\theta_0). \quad (A.11) \]
Focusing on $\frac{1}{NT} Z'(I_N \otimes M_{I_T}) \mathcal{E}$ firstly, we have

$$E \left\| \frac{1}{NT} Z'(I_N \otimes M_{I_T}) \mathcal{E} \right\|^2 = E \left\| \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T Z(x_{it}) e_{it} - \frac{1}{N} \sum_{i=1}^N \bar{Z}_i \bar{e}_i \right\|^2$$

$$\leq 2E \left\| \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T Z(x_{it}) e_{it} \right\|^2 + 2E \left\| \frac{1}{N} \sum_{i=1}^N \bar{Z}_i \bar{e}_i \right\|^2.$$  \hspace{1cm} (A.12)

By the fourth result of Lemma 2, we have $E \left\| \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T Z(x_{it}) e_{it} \right\|^2 = O\left(\frac{k^{3d/2}}{NT}\right)$. For the second term on RHS of (A.12), write

$$E \left\| \frac{1}{N} \sum_{i=1}^N \bar{Z}_i \bar{e}_i \right\|^2 = \sum_{u=1}^K E \left[ \frac{1}{NT^2} \sum_{i=1}^N \sum_{t_1=1}^T \sum_{t_2=1}^T z_u(x_{it_1}) e_{it_2} \right]^2$$

$$= \sum_{u=1}^K \frac{1}{N^2} \sum_{i=1}^N \sum_{j=1}^N E \left[ \frac{1}{T^2} \sum_{t_1=1}^T \sum_{t_3=1}^T \sum_{t_4=1}^T z_u(x_{it_1}) e_{it_2} z_u(x_{jt_3}) e_{jt_4} \right]\cdot \sum_{u=1}^K \frac{1}{T^2} \sum_{t_1=1}^T \sum_{t_3=1}^T z_u(x_{it_1}) z_u(x_{jt_3})$$

where the last line follows Assumption 1.ii.

By Cauchy-Schwarz inequality, moment monotonicity and Assumption 3.ii respectively,

$$\left\| \sum_{u=1}^K \frac{1}{T} \sum_{t_1=1}^T \sum_{t_3=1}^T z_u(x_{it_1}) z_u(x_{jt_3}) \right\|$$

$$\leq \sum_{u=1}^K \frac{1}{T^2} \sum_{t_1=1}^T \sum_{t_3=1}^T (E \left[ z_u^2(x_{it_1}) \right] E \left[ z_u^2(x_{jt_3}) \right])^{1/2}$$

$$\leq \sum_{u=1}^K \frac{1}{T^2} \sum_{t_1=1}^T \sum_{t_3=1}^T (E \left[ z_u^{4+\eta}(x_{it_1}) \right] E \left[ z_u^{4+\eta}(x_{jt_3}) \right])^{1/(4+\eta)}$$

$$\leq \sum_{u=1}^K \frac{1}{T^2} \sum_{t_1=1}^T \sum_{t_3=1}^T (E \left[ z_u^{4+\eta}(x_{it_1}) \right] E \left[ z_u^{4+\eta}(x_{jt_3}) \right])^{1/4} = O(k^{3d/2}).$$

Similar to the proof of the first result of Lemma 2, $\frac{1}{NT} \sum_{i=1}^N \sum_{j=1}^N E \left[ \frac{1}{T^2} \sum_{t_2=1}^T \sum_{t_4=1}^T \sigma_{it_2} \sigma_{jt_4} \right] = O\left(\frac{1}{NT}\right)$. Thus, $E \left\| \frac{1}{N} \sum_{i=1}^N \bar{Z}_i \bar{e}_i \right\|^2 = O\left(\frac{k^{3d/2}}{NT}\right)$. Based on the above, we have

$$\left\| \frac{1}{NT} Z'(I_N \otimes M_{I_T}) \mathcal{E} \right\|^2 = O_p\left(\frac{k^{3d/2}}{NT}\right).$$  \hspace{1cm} (A.13)

According to the fifth result of Lemma 2 and (A.13), we obtain

$$\left\| [Z'(I_N \otimes M_{I_T}) - Z'(I_N \otimes M_{I_T}) \mathcal{E}]^2 \right\|$$

$$= \mathcal{E}'(I_N \otimes M_{I_T}) [Z'(I_N \otimes M_{I_T}) - Z'(I_N \otimes M_{I_T}) \mathcal{E}] - \mathcal{E}'(I_N \otimes M_{I_T}) \mathcal{E}$$

$$\leq \lambda_{\text{min}} \left( \frac{1}{NT} Z'(I_N \otimes M_{I_T}) \mathcal{E} \right)^{-1} \cdot \left\| \frac{1}{NT} Z'(I_N \otimes M_{I_T}) \mathcal{E} \right\|^2 = O_p\left(\frac{k^{3d/2}}{NT}\right).$$  \hspace{1cm} (A.14)

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We now consider \( [Z' (I_N \otimes M_{ir}) Z]^{-1} Z' (I_N \otimes M_{ir}) D(\theta_0) \) and write
\[
\left\| (Z' (I_N \otimes M_{ir}) Z)^{-1} Z' (I_N \otimes M_{ir}) D(\theta_0) \right\|^2
= D(\theta_0)' (I_N \otimes M_{ir}) Z (Z' (I_N \otimes M_{ir}) Z/(NT))^{-1}
\cdot (Z' (I_N \otimes M_{ir}) Z)^{-1} Z' (I_N \otimes M_{ir}) D(\theta_0)/(NT)
\leq \left[ \lambda_{\min} (Z' (I_N \otimes M_{ir}) Z/(NT)) \right]^{-1}
\cdot D(\theta_0)' (I_N \otimes M_{ir}) Z (Z' (I_N \otimes M_{ir}) Z)^{-1} Z' (I_N \otimes M_{ir}) D(\theta_0)/(NT)
\leq \left[ \lambda_{\min} (Z' (I_N \otimes M_{ir}) Z/(NT)) \right]^{-1} \cdot \lambda_{\max}(W) \cdot \left( \|D(\theta_0)\|^2/(NT) \right).
\text{(A.15)}
\]

Note that \( W = (I_N \otimes M_{ir}) Z (Z' (I_N \otimes M_{ir}) Z)^{-1} Z' (I_N \otimes M_{ir}) \) is symmetric and idempotent, so \( \lambda_{\max}(W) = 1 \). According to Assumption 3.ii and the Weak Law of Large Numbers (WLLN), it is easy to know that \( \|D(\theta_0)\|^2/(NT) = o_p(k^{-r}) \). In connection with the fifth result of Lemma 2 of this appendix, we obtain that
\[
\left\| [Z' (I_N \otimes M_{ir}) Z]^{-1} Z' (I_N \otimes M_{ir}) D(\theta_0) \right\|^2 = o_p(k^{-r}).
\text{(A.16)}
\]

Therefore, the theorem follows form (A.14) and (A.16).

**Proof of Theorem 2:** It is easy to know that \( sgn(\hat{\beta}_1) \cdot \left( \sum_{i=1}^{d} \hat{\beta}^2_i \right)^{-1/2} \) converges to \(|c_1|^{-1}\) by (2.7) and Theorem 1, so we only need to consider \( \sqrt{NT} \cdot Q_3 \left( \hat{\beta} - \beta \right) \) and write
\[
\sqrt{NT} \cdot Q_3 \left( \hat{\beta} - \beta \right) = \sqrt{NT} \cdot Q_3 \left[ Z' (I_N \otimes M_{ir}) Z \right]^{-1} Z' (I_N \otimes M_{ir}) D(\theta_0)
+ \sqrt{NT} \cdot Q_3 \left[ Z' (I_N \otimes M_{ir}) Z \right]^{-1} Z' (I_N \otimes M_{ir}) E.
\text{(A.17)}
\]

Notice that \( K = O(k^d) \) and \( Q_3 = O(1) \). In connection with (A.16) and the assumption in the body of this theorem, it is straightforward to obtain
\[
\left\| \sqrt{NT} \cdot Q_3 \left[ Z' (I_N \otimes M_{ir}) Z \right]^{-1} Z' (I_N \otimes M_{ir}) D(\theta_0) \right\|
\leq \sqrt{NT} \cdot O(1) \cdot o_p \left( k^{-r/2} \right) = o_p(1).
\text{(A.18)}
\]

Then, to achieve the normality, we need only to consider the second term on RHS of (A.17).
\[
\sqrt{NT} \cdot Q_3 \left[ Z' (I_N \otimes M_{ir}) Z \right]^{-1} Z' (I_N \otimes M_{ir}) E
= \sqrt{NT} \cdot Q_3 \left( \frac{1}{NT} Z' (I_N \otimes M_{ir}) Z \right)^{-1} \left( \frac{1}{NT} Z' (I_N \otimes M_{ir}) E \right)
+ \sqrt{NT} \cdot Q_3 \left( Q_1 - Q_2 \right)^{-1} \left( \frac{1}{NT} Z' (I_N \otimes M_{ir}) E \right)
\text{(A.19)}
\]

For two non-singular symmetric matrices \( A, B \) with same dimensions, we observe that by Theorem 2 on page 35 of Magnus (2007)
\[
\|A^{-1} - B^{-1}\|^2 = \|B^{-1} (B - A) A^{-1}\|^2 = \|vec \left( B^{-1} (B - A) A^{-1} \right)\|^2
= \| (A^{-1} \otimes B^{-1}) vec (B - A) \|^2 \leq \lambda_{\min}^{-2} (A \otimes B) \|vec (B - A)\|^2 = \lambda_{\min}^{-2} (A \otimes B) \|B - A\|^2,
\]

where \( \lambda_{\min} (A \otimes B) = \lambda_{\min} (A) \cdot \lambda_{\min} (B) \) by Theorem 1 on page 28 of Magnus (2007). Therefore, in connection with the proof of the fifth result of Lemma 2 in this appendix,

\[
\left\| \left( \frac{1}{NT} Z' (I_N \otimes M_{tr}) Z \right)^{-} - (Q_1 - Q_2)^{-} \right\| = O_p \left( \sqrt{\frac{k^{3d}}{NT}} \right).
\]

Moreover, by (A.13), we can obtain that

\[
\sqrt{NT} \cdot Q_3 \left( \left( \frac{1}{NT} Z' (I_N \otimes M_{tr}) Z \right)^{-} - (Q_1 - Q_2)^{-} \right) \left( \frac{1}{NT} Z' (I_N \otimes M_{tr}) E \right)
\]

\[
\leq \sqrt{NT} \cdot O_p \left( \sqrt{\frac{k^{3d}}{NT}} \right) \cdot O_p \left( \sqrt{\frac{k^{4d/2}}{NT}} \right) = O_p \left( \sqrt{\frac{k^{4d}}{NT^2}} \right) = o_p (1).
\]

The second term on RHS of (A.19) can be written as follows.

\[
\sqrt{NT} \cdot Q_3 (Q_1 - Q_2)^{-} \left( \frac{1}{NT} Z' (I_N \otimes M_{tr}) E \right)
\]

\[
= \sqrt{NT} \cdot Q_3 (Q_1 - Q_2)^{-} \frac{1}{N} \sum_{i=1}^{N} (q_i - \bar{Z}_i) \bar{e}_i.
\]

\[
+ \sqrt{NT} \cdot Q_3 (Q_1 - Q_2)^{-} \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (Z (x_{it}) - q_i) e_{it}
\]

\[(A.20)\]

For the first term on RHS of (A.20), we have \( E \left\| \frac{1}{N} \sum_{i=1}^{N} (q_i - \bar{Z}_i) \bar{e}_i \right\|^2 = O \left( \frac{k^{3d/2}}{NT^2} \right) \). Similar to (A.14), \( \left\| (Q_1 - Q_2)^{-} \frac{1}{N} \sum_{i=1}^{N} (q_i - \bar{Z}_i) \bar{e}_i \right\| = O_p \left( \sqrt{\frac{k^{3d}}{NT^2}} \right) \).

Therefore,

\[
\left\| \sqrt{NT} \cdot Q_3 (Q_1 - Q_2)^{-} \frac{1}{N} \sum_{i=1}^{N} (q_i - \bar{Z}_i) \bar{e}_i \right\| \leq \sqrt{NT} \cdot O (1) \cdot O_p \left( \sqrt{\frac{k^{3d}}{NT^2}} \right) = o_p (1).
\]

Since \( x_{it} \) and \( e_{it} \) are assumed to be stationary and \( \alpha \)-mixing, we now use the large-block and small-block technique (e.g. Theorem 2.21 in Fan and Yao (2003); Lemma A.1 in Gao (2007); Lemma A.1 in Chen et al. (2012b)) to prove the normality for the second term on RHS of (A.20). Write

\[
\sqrt{NT} \cdot Q_3 (Q_1 - Q_2)^{-} \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (Z (x_{it}) - q_i) e_{it} = \sum_{t=1}^{T} V_{NT} (t),
\]

where \( V_{NT} (t) = \frac{1}{\sqrt{NT}} \sum_{i=1}^{N} Q_3 (Q_1 - Q_2)^{-} (Z (x_{it}) - q_i) e_{it}. \)

Notice that \( Q_3 \) is just a selection matrix that selects the first \( d \) elements of \( \hat{\beta} \), so \( V_{NT} \) is a summation of random vectors with finite dimensions \( d \times 1 \). Then, the conventional Central Limit Theory (CLT) applies.

Partition the set \( \{1, \ldots, T\} \) into \( 2\kappa_T + 1 \) subsets with large block with size \( l_T \), small block with size \( s_T \) and the remaining set with size \( T - \kappa_T (l_T + s_T) \), where

\[
l_T = \lfloor T^{(\lambda-1)/\lambda} \rfloor, \quad s_T = \lfloor T^{1/\lambda} \rfloor, \quad \kappa_T = \lfloor T / (l_T + s_T) \rfloor \quad \text{for any } \lambda > 2.
\]

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For \( \rho = 1, \ldots, \kappa_T \), let \( \hat{V} = \sum_{t=\kappa_T(t_T+s_T)+1}^{T} V_{NT}(t) \).

\[
\hat{V}_\rho = \sum_{t=\rho T + \rho(t-1)s_T}^{\rho(t+s_T)} V_{NT}(t) \quad \text{and} \quad \tilde{V}_\rho = \sum_{t=\rho T + (\rho-1)s_T+1}^{\rho(t+s_T)} V_{NT}(t).
\]

For the small blocks, it can be seen

\[
E \left\| \sum_{\rho=1}^{\kappa_T} \hat{V}_\rho \right\|^2 = \frac{1}{d} \sum_{u=1}^{d} \left\{ \sum_{\rho=1}^{\kappa_T} E \left[ \tilde{v}_{\rho,u}^2 \right] + 2 \sum_{\rho=2}^{\kappa_T} (\kappa_T - \rho + 1) E \left[ \tilde{v}_{1,u} \tilde{v}_{\rho,u} \right] \right\},
\]

where \( \hat{V}_\rho = \sum_{t=\rho T + (\rho-1)s_T+1}^{\rho(t+s_T)} V_{NT}(t) = (\tilde{v}_{\rho,1}, \ldots, \tilde{v}_{\rho,d})' \).

By the properties of \( \alpha \)-mixing time series and a procedure similar to (A.6) in Chen et al. (2012b), we obtain

\[
E \left\| \hat{V} \right\|^2 = O \left( \frac{T^{\kappa_T} s_T}{T} \right) = O(1).
\]

Analogously, we have

\[
E \left\| \tilde{V} \right\|^2 = O \left( \frac{T - \kappa_T l_T}{T} \right) = o(1).
\]

Therefore, in order to establish the CLT, we need only to consider \( \sum_{\rho=1}^{\kappa_T} \tilde{V}_\rho \). In connection with Proposition 2.6 in Fan and Yao (2003) and the condition on the \( \alpha \)-mixing coefficient, we have

\[
E \left[ \exp \left( \sum_{\rho=1}^{\kappa_T} \left\| \tilde{V}_\rho \right\| \right) \right] - \prod_{\rho=1}^{\kappa_T} E \left[ \left\| \tilde{V}_\rho \right\| \right] \leq C (\kappa_T - 1) \alpha(s_T) \rightarrow 0
\]

for some \( 0 < C < \infty \), which implies that \( \tilde{V}_\rho \) for \( \rho = 1, \ldots, \kappa_T \) are asymptotically independent. Furthermore, as in the proof of Theorem 2.21.(ii) in Fan and Yao (2003), we have

\[
\text{Cov} \left[ \tilde{V}_1 \right] = \frac{l_T}{T} \Xi_0 (I + o(1)),
\]

where

\[
\Xi_0 = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^{N} Q_3 \left( Q_1 - Q_2^* \right) \left\{ E \left[ e_{i1}^2 \left( Z(x_{i1}) - q_i \right) \left( Z(x_{i1}) - q_i \right) \right] \right.
\]

\[+ \sum_{t=2}^{\infty} E \left[ e_{i1} e_{it} \left( Z(x_{i1}) - q_i \right) \left( Z(x_{it}) - q_i \right) \right] \]

\[+ \sum_{t=2}^{\infty} E \left[ e_{i1} e_{it} \left( Z(x_{it}) - q_i \right) \left( Z(x_{i1}) - q_i \right) \right] \left( Q_1' - Q_2' \right) Q_3'.
\]

It further implies that

\[
\sum_{\rho=1}^{\kappa_T} \text{Cov} \left[ \tilde{V}_\rho \right] = \kappa_T \cdot \text{Cov} \left[ \tilde{V}_1 \right] = \frac{\kappa_T l_T}{T} \Xi_0 (I + o(1)) \rightarrow \Xi_0.
\]
Thus, the Feller condition is satisfied.

Moreover, by Cauchy-Schwarz inequality, we have
\[ E \left[ \left\| \tilde{V}_p \right\| \cdot I \{ \left\| V_p \right\| \geq \varepsilon \} \right] \leq C \left\{ E \left[ \left\| \tilde{V}_p \right\|^2 \right] \right\}^{2/3} \cdot \left\{ E \left[ \left\| V_p \right\|^2 \right] \right\}^{1/3} \]

and by Lemma B.2 in Chen et al. (2012b),
\[ E \left[ \left\| V_p \right\|^3 \right] \leq \left( \frac{l_T}{T} \right)^{3/2} \left\{ E \left[ \left\| \frac{1}{\sqrt{NT}} \sum_{i=1}^{N} Q_3 (Q_1 - Q_2)^{-1} (Z(x_{i1}) - q_i) e_{i1} \right\|^4 \right] \right\}^{3/4} . \]

By the assumption in the body of the theorem
\[ E \left[ \left\| \tilde{V}_p \right\|^3 \right] \leq O \left( \left( \frac{l_T}{T} \right)^{3/2} \right) , \]
which implies that
\[ E \left[ \left\| \tilde{V}_p \right\|^2 \cdot I \{ \left\| V_p \right\| \geq \varepsilon \} \right] \leq O \left( \left( \frac{l_T}{T} \right)^{4/3} \right) = o \left( \frac{l_T}{T} \right) . \]

Consequently,
\[ \sum_{\rho=1}^{\kappa T} E \left[ \left\| \tilde{V}_p \right\|^2 \cdot I \{ \left\| V_p \right\| \geq \varepsilon \} \right] = o \left( \frac{\kappa T l_T}{T} \right) = o (1) . \]

Therefore, the Lindeberg condition is satisfied. Therefore, the proof is completed. ■

**Proof of Theorem 3:** By (2.5), we have the following decomposition:
\[ \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} g (x'_{it} \theta_0) = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z (x_{it})' \beta + c_0 + \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \delta_k (x'_{it} \theta_0) . \]

Moreover, \( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} g (x'_{it} \theta_0) = O_p \left( \frac{1}{\sqrt{NT}} \right) \) by the second result of Lemma 2. Plus \( \hat{c}_0 \) from both sides and organize the equation, so we obtain that
\[ \hat{c}_0 - c_0 = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z (x_{it})' (\beta - \hat{\beta}) + \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \delta_k (x'_{it} \theta_0) + O_p \left( \frac{1}{\sqrt{NT}} \right) . \quad (A.22) \]

In view of the fact that \( \left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z (x_{it}) \right) \left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z (x_{it})' \right) \) has rank one and using the similar procedure of (A.14), it may be shown
\[ \left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z (x_{it})' (\beta - \hat{\beta}) \right)^2 \]
\[ = (\beta - \hat{\beta})' \left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z (x_{it}) \right) \left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z (x_{it})' \right) (\beta - \hat{\beta}) \]
\[ \leq C \cdot \left\| \beta - \hat{\beta} \right\|^2 = O_p \left( \frac{k^{3d/2}}{NT} \right) + o_p (k^{-r}) . \]

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By using Cauchy-Schwarz inequality twice
\[
\left( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} \delta_k(x'_{it} \theta_0) \right)^2 \leq \left[ \sum_{i=1}^{N} \left( \frac{1}{\sqrt{NT}} \sum_{t=1}^{T} \delta_k(x'_{it} \theta_0) \right)^2 \right] \cdot \left[ \sum_{i=1}^{N} \left( \frac{1}{\sqrt{N}} \right)^2 \right]
\]
\[
= \frac{1}{N} \sum_{i=1}^{N} \left( \frac{1}{T} \sum_{t=1}^{T} \delta_k(x'_{it} \theta_0) \right)^2 \leq \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (\delta_k(x'_{it} \theta_0))^2.
\]

Moreover, we have shown that \( \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (\delta_k(x'_{it} \theta_0))^2 = o_p(k^{-r}) \) in the proof of Theorem 1.

Based on the above, the result has been proved.

**Proof of Theorem 4:** By (A.22) and the assumptions in the body of this theorem, it is easy to obtain the next equation after some algebra.

\[
\sqrt{\frac{NT}{K^{3/2}}} \left( \hat{g} \left( x' \hat{\theta} \right) - g(x' \theta_0) \right)
\]
\[
= \sqrt{\frac{NT}{K^{3/2}}} Z_{NT} (x)' \left[ Z' (I_N \otimes M_T) Z \right]^{-1} Z' (I_N \otimes M_T) \mathcal{D}(\theta_0)
\]
\[
+ \sqrt{\frac{NT}{K^{3/2}}} Z_{NT} (x)' \left[ Z' (I_N \otimes M_T) Z \right]^{-1} Z' (I_N \otimes M_T) \mathcal{E} + o_p(1), \tag{A.23}
\]

where \( Z_{NT} (x) = \left( Z(x) - \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} Z(x'_{it}) \right) \).

In connection with (A.16), it is straightforward to obtain that

\[
\left\| \sqrt{\frac{NT}{K^{3/2}}} Z_{NT} (x)' \left[ Z' (I_N \otimes M_T) Z \right]^{-1} Z' (I_N \otimes M_T) \mathcal{D}(\theta_0) \right\|
\]
\[
\leq \sqrt{\frac{NT}{K^{3/2}}} \cdot O_p\left( \sqrt{k^{3d/2}} \right) \cdot O_p\left( k^{-r/2} \right) = O_p\left( \sqrt{\frac{NT}{k^r}} \right) = o_p(1). \tag{A.24}
\]

Thus, to prove the normality, we need only to consider the second term on RHS of (A.23):

\[
\sqrt{\frac{NT}{K^{3/2}}} Z_{NT} (x)' \left( \frac{1}{NT} Z' (I_N \otimes M_T) Z \right)^{-1} (Q_1 - Q_2)^{-1} \left( \frac{1}{NT} Z' (I_N \otimes M_T) \mathcal{E} \right)
\]
\[
+ \sqrt{\frac{NT}{K^{3/2}}} Z_{NT} (x)' (Q_1 - Q_2)^{-1} \left( \frac{1}{NT} Z' (I_N \otimes M_T) \mathcal{E} \right). \tag{A.25}
\]

Similar to the proof procedure of Theorem 2, write

\[
\left\| \sqrt{\frac{NT}{K^{3/2}}} Z_{NT} (x)' \left( \frac{1}{NT} Z' (I_N \otimes M_T) Z \right)^{-1} (Q_1 - Q_2)^{-1} \left( \frac{1}{NT} Z' (I_N \otimes M_T) \mathcal{E} \right) \right\|
\]
\[
\leq \sqrt{\frac{NT}{K^{3/2}}} \cdot O_p\left( \sqrt{k^{3d/2}} \right) \cdot O_p\left( \sqrt{\frac{k^{3d/2}}{NT}} \right) \cdot O_p\left( \sqrt{\frac{k^{4.5d}}{NT}} \right) = O_p\left( \sqrt{\frac{k^{4.5d}}{NT}} \right).
\]
Similarly, we can show
\[
\sqrt{\frac{NT}{K^{3/2}}} Z_{NT} (x)' (Q_1 - Q_2)^{-} \left( \frac{1}{NT} Z' (I_N \otimes M_{1T}) \mathcal{E} \right) \\
= \sqrt{\frac{NT}{K^{3/2}}} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} \left( \frac{1}{NT} Z' (I_N \otimes M_{1T}) \mathcal{E} \right) + O_p \left( \sqrt{\frac{k^{3d/2}}{T}} \right). 
\]

Thus, we just need to focus on the next term:
\[
\sqrt{\frac{NT}{K^{3/2}}} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} \left( \frac{1}{NT} Z' (I_N \otimes M_{1T}) \mathcal{E} \right) \\
= \sqrt{\frac{NT}{K^{3/2}}} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} \frac{1}{N} \sum_{i=1}^{N} (q_i - \bar{Z}_i) \bar{e}_i. \\
+ \sqrt{\frac{NT}{K^{3/2}}} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (Z(x_{it}) - q_i) e_{it}. \tag{A.26}
\]

In Theorem 2, we have shown that
\[
\left\| (Q_1 - Q_2)^{-} \frac{1}{N} \sum_{i=1}^{N} (q_i - \bar{Z}_i) \bar{e}_i \right\| = O \left( \sqrt{\frac{k^{3d/2}}{NT}} \right).
\]

Hence, we obtain
\[
\left\| \sqrt{\frac{NT}{K^{3/2}}} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} \frac{1}{N} \sum_{i=1}^{N} (q_i - \bar{Z}_i) \bar{e}_i \right\| \\
\leq \sqrt{\frac{NT}{K^{3/2}}} \cdot O \left( \sqrt{k^{3d/2}} \right) \cdot O_p \left( \sqrt{\frac{k^{3d/2}}{NT^2}} \right) = o_p(1). 
\]

We still use the large-block and small-block technique to prove the normality for the second term on RHS of (A.26). Write
\[
\sqrt{\frac{NT}{K^{3/2}}} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (Z(x_{it}) - q_i) e_{it} = \sum_{t=1}^{T} \mathcal{V}_{NTK} (t), \tag{A.27}
\]
where
\[
\mathcal{V}_{NTK} (t) = \frac{1}{\sqrt{NTK^{3/2}}} \sum_{i=1}^{N} (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} (Z(x_{it}) - q_i) e_{it}.
\]

Notice that
\[
\left\| (Z(x) - \bar{q})' (Q_1 - Q_2)^{-} (Z(x_{it}) - q_i) e_{it} \right\|^2 \\
\leq \lambda_{\max} \left( (Z(x) - \bar{q})(Z(x) - \bar{q})' \right) \cdot \left\| (Q_1 - Q_2)^{-} (Z(x_{it}) - q_i) e_{it} \right\|^2 \\
= O_p(k^{3d/2}),
\]
so that \( \mathcal{V}_{NTK} \) is a summation of random scalar and its absolute value is bounded uniformly in \( K \) with probability one. Then the conventional CLT is applicable. The rest of the proof will be
4.iii, we write

\[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \]

is the inverse of \( \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \) for each \( k \). Therefore,

\[
\hat{C} - C = \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) Y' \\
- \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) C \\
+ \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \left( \mathcal{G}(\theta_0) - \mathcal{G}(\hat{\theta}) \right) \\
+ \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) E,
\]

(A.28)

where \( \mathcal{G}(\theta)_{NT \times 1} = (g(x_{11}'), \ldots, g(x_{1T}'), \ldots, g(x_{N1}'), \ldots, g(x_{NT}'))' \) for \( \forall \theta \in \Theta \).

Similar to (A.16), we have

\[
\left\| \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) D(\hat{\theta}) \right\|^2 = o_p \left( k^{-r} \right).
\]

By the third and fourth results of Lemma 3 and the similar procedure of (A.14), we obtain

\[
\left\| \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) E \right\|^2 = O_p \left( \frac{k^{3/2}}{NT} \right).
\]

Then, we need only to consider the next term. By the same proof as (A.15) and Assumption 4.iii, we write

\[
\left\| \left[ \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right]^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \left( \mathcal{G}(\theta_0) - \mathcal{G}(\hat{\theta}) \right) \right\|^2 \\
\leq \left( \lambda_{\min} \left( \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta})/(NT) \right) \right)^{-1} \cdot \lambda_{\max}(\hat{W}) \cdot \left( \left\| \mathcal{G}(\theta_0) - \mathcal{G}(\hat{\theta}) \right\|^2/(NT) \right) \\
\leq \left( \lambda_{\min} \left( \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta})/(NT) \right) \right)^{-1} \cdot \lambda_{\max}(\hat{W}) \cdot \left( \left\| \mathcal{X} \right\|^2 \cdot \left\| \theta_0 - \hat{\theta} \right\|^2/(NT) \right),
\]

where \( \mathcal{X}_{NT \times 1} = (M(x_{11}), \ldots, M(x_{1T}), \ldots, M(x_{N1}), \ldots, M(x_{NT}))' \) and

\[
\hat{W} = (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \left( \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}) \mathcal{H}(\hat{\theta}) \right)^{-1} \mathcal{H}(\hat{\theta})' (I_N \otimes M_{i_T}).
\]

Since \( \hat{W} \) is symmetric and idempotent, \( \lambda_{\max}(\hat{W}) = 1 \).

By Assumption 4.iii and Theorem 2, we know that

\[
\frac{1}{NT} \left\| \mathcal{X} \right\|^2 \cdot \left\| \theta_0 - \hat{\theta} \right\|^2 = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (M(x_{it}))^2 \cdot \left\| \theta_0 - \hat{\theta} \right\|^2 = O_p \left( \frac{1}{NT} \right).
\]

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Hence, similar with (A.16), we obtain that

$$\left\| H(\hat{\theta})' (I_N \otimes M_{iT}) H(\hat{\theta}) \right\|^2 = O_p \left( \frac{1}{NT} \right).$$

Based on the above, the result has been proved. ■

**Proof of Corollary 2:** Write

$$\int (\hat{g}_1(w) - g(w))^2 \cdot \exp \left( -w^2/2 \right) dw$$

$$= \int \left( H(w)\hat{C} + \tilde{c}_0 - c_0 - H(w)C - \delta_k (w) \right)^2 \cdot \exp \left( -w^2/2 \right) dw$$

$$\leq 4 \int \left( \hat{C} - C \right)' H(w)H(w)' \left( \hat{C} - C \right) \cdot \exp \left( -w^2/2 \right) dw$$

$$+ 4 \left\| \tilde{c}_0 - c_0 \right\|^2 + 2 \int \delta_k (w)^2 \cdot \exp \left( -w^2/2 \right) dw$$

$$= 4 \left\| \hat{C} - C \right\|^2 + 4 \left\| \tilde{c}_0 - c_0 \right\|^2 + 2 \int \delta_k (w)^2 \cdot \exp \left( -w^2/2 \right) dw.$$


